## Deep Learning on OpenPower using PowerAl

# Workshop at NCSA, UIUC February 28<sup>th</sup> 2018

Chekuri S. Choudary (<u>chekuri.choudary@ibm.com</u>)

Rodrigo Ceron (Rodrigo.ceron@ibm.com)

#### Agenda – AM Session (Machine Learning)

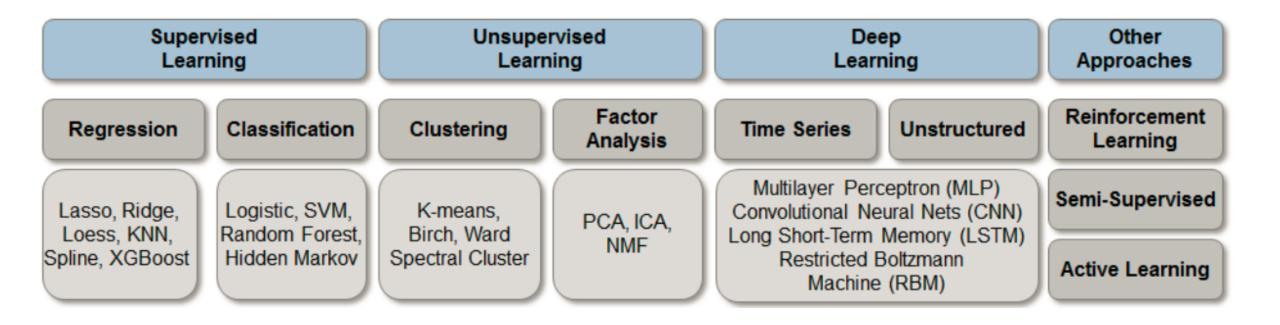
- 8.00 AM 8.30 AM (slides 4-8)
  - Welcome
  - Overview of Machine Learning algorithms
  - Review of IBM Minsky, IBM PowerAI, and Nimbix
  - Workshop Objectives
- 8.30 AM 9.30 AM (slides 9-12)
  - Introduction to Linear Regression
  - Introduction to the Structure of a Tensorflow Program
  - Hands-on Exercise on Linear Regression
    - Change Learning Rate, Number of Epochs, and Learning Algorithm
- 9.30 AM 10.30 AM (slides 13-15)
  - Logistic Regression, Multinomial Logistic Regression/Softmax Regression
  - Lab Multinomial Logistic Regression Using Tensorflow and MNIST
- 10.30 AM 11.00 AM
  - Break
- 11.00 AM 12.00 AM (slides 16-21)
  - Introduction to Fully Connected Neural Network
  - Lab Fully Connected Neural Net Using Tensorflow

#### Agenda – PM Session (Deep Learning)

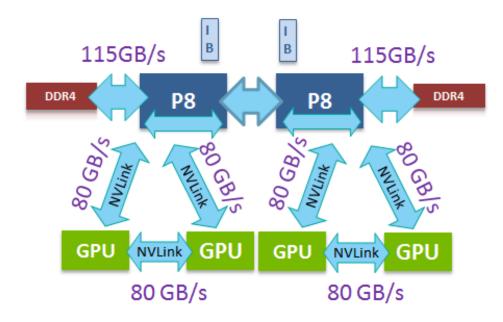
- 12.00 PM 1.00 PM
  - Lunch
- 1.00 PM 2.00 PM (slides 22-31)
  - Introduction to Deep Learning
  - Introduction to Convolutional Neural Networks
  - Lab ImageNet Exercise Using Caffe
  - Lab Transfer Learning Exercise Using Caffe
- 2.00 PM 2.30 PM
  - Break
- 2.30 PM 3.00 PM (slides 32 36)
  - Introduction to Recurrent Neural Networks
  - Lab NLP Exercise Using Tensorflow
- 3.30 PM 4.00 PM
  - NCSA Review of NCSA Deep Learning Environment, How to Access etc.

#### Classification of Machine Learning Techniques

Machine Learning / Artificial Intelligence



#### POWER, NVLink and P100 Advantage



In [7]: # CPU mode net.forward() # call once for allocation %timeit net.forward()

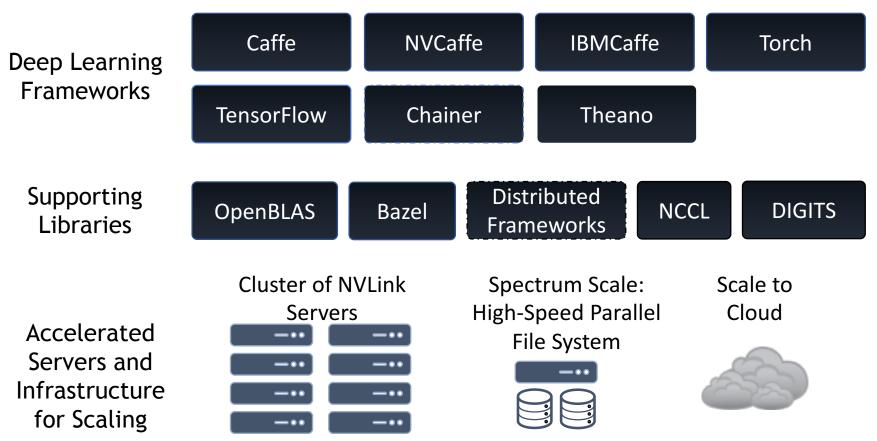
1 loop, best of 3: 7.22 s per loop

That's a while, even for a batch size of 50 images. Let's switch to GPU mode.

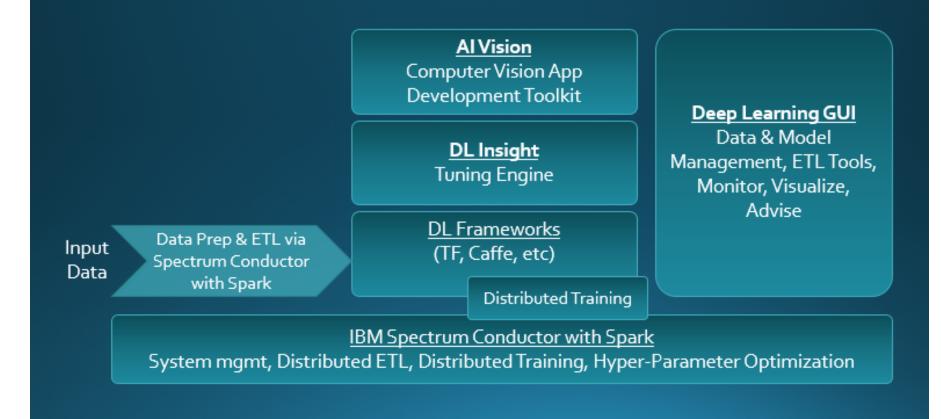
In [8]: # GPU mode caffe.set\_device(0) caffe.set\_mode\_gpu() net.forward() # call once for allocation %timeit net.forward() 10 loops, best of 3: 56.4 ms per loop

- Shorter training times
- Facilitates distributed deep learning and large model support in IBM PowerAl

## PowerAl Platform



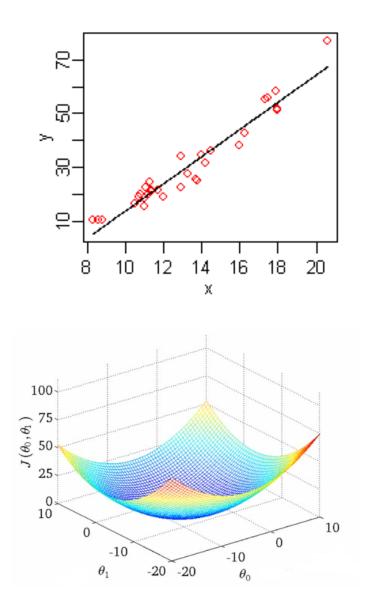
#### PowerAl Deep Learning Software Stack



#### Objectives

- Introduce the foundations of deep learning
- Give an overview of state-of-the-art deep learning technologies
- Demonstrate the benefits of leveraging IBM deep learning technology offerings (Minsky and PowerAI) for research, teaching, and course projects
- Targeted audience include software developers, faculty, research scientists, postdocs, graduate/undergraduate students across various scientific disciplines

#### Linear Regression

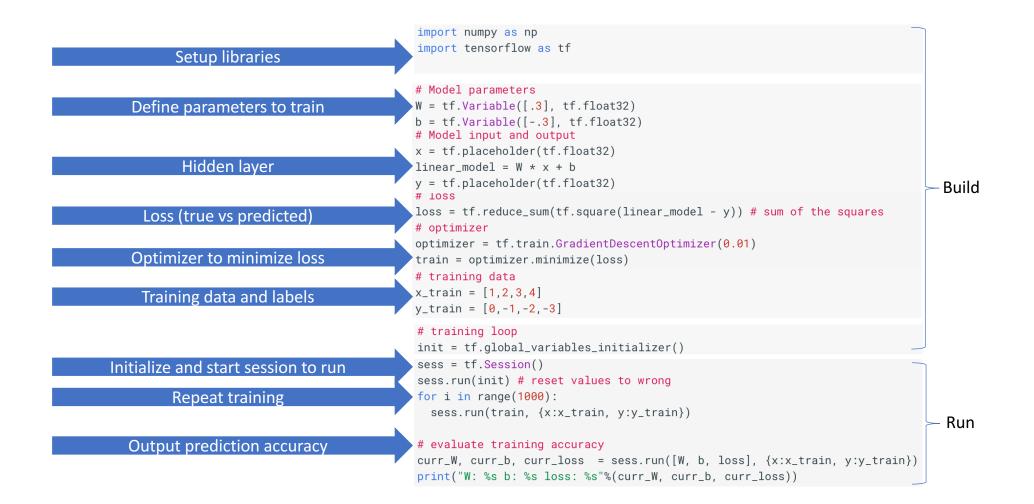


 $h_{\theta}(x) = \theta_0 + \theta_1 x$ Hypothesis: Parameters:  $\theta_0, \theta_1$ Cost Function:  $J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$  $\underset{\theta_0,\theta_1}{\text{minimize }} J(\theta_0,\theta_1)$ Goal: Gradient descent algorithm  $\frac{2}{200}$  J(0,0)repeat until convergence {  $\theta_{0} := \theta_{0} - \alpha \frac{1}{m} \sum_{i=1}^{m} \left( h_{\theta}(x^{(i)}) - y^{(i)} \right)$  $\theta_{1} := \theta_{1} - \alpha \frac{1}{m} \sum_{i=1}^{m} \left( h_{\theta}(x^{(i)}) - y^{(i)} \right) \cdot x^{(i)}$ update  $heta_0$  and  $heta_1$ simultaneously

 $\frac{\partial O}{\partial O}$  ](0,0)

 $= \Theta_0 + \Theta_1 \times$ 

#### Structure of a Tensorflow Program



#### Jupyter Notebooks

💭 jupyter	linear_regression (autosaved)	e
File Edit	View Insert Cell Kernel Help	Python 2 O
₽ + %	Image:	
In [1]:	# A linear regression learning algorithm example using TensorFlow library.	
	# Author: Aymeric Damien	
	<pre># Project: https://github.com/aymericdamien/TensorFlow-Examples/</pre>	
In [6]:	import tensorflow as tf	
	<pre>import numpy import matplotlib.pyplot as plt</pre>	
	rng = numpy.random	
In [17]:	# Parameters learning rate = 0.01	
	training_epochs = 1000	
	<pre>display_step = 50 print "learning rate set to: ", learning_rate</pre>	
	<pre>print "# of epochs set to: ", training_epochs print "display sampling set to: ", display_step</pre>	
	learning rate set to: 0.01	
	# of epochs set to: 1000 display sampling set to: 50	
In [8]:	<pre># Training Data train X = numpy.asarray([3.3,4.4,5.5,6.71,6.93,4.168,9.779,6.182,7.59,2.167,</pre>	
	7.042,10.791,5.313,7.997,5.654,9.27,3.1]) train_Y = numpy.asarray([1.7,2.76,2.09,3.19,1.694,1.573,3.366,2.596,2.53,1.221,	
	2.827, 3.465, 1.65, 2.904, 2.42, 2.94, 1.3])	
	<pre>n_samples = train_X.shape[0]</pre>	
In [9]:	<pre># tf Graph Input X = tf.placeholder("float")</pre>	
	Y = tf.placeholder("float")	
	# Set model weights	
	<pre>W = tf.Variable(rng.randn(), name="weight") b = tf.Variable(rng.randn(), name="bias")</pre>	
Tp [11]	: # Construct a linear model	

pred = tf.add(tf.multiply(X, W), b)

## Linear Regression Exercise using Tensorflow

- <u>https://github.com/aymericdamien/TensorFlow-</u>
   <u>Examples/blob/master/notebooks/2\_BasicModels/linear\_regression.ipynb</u>
- Follow-up

Loss

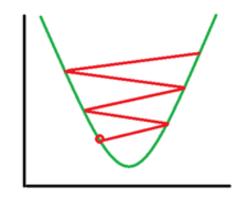
- Change learning rate with [0.001 0.003 0.01 0.03 0.1 0.3 1]
- Change # of epochs with [500 1000 1500 2000 2500 3000]
- Change learning algorithm with

[GradientDescentOptimizer

MomentumOptimizer

RMSPropOptimizer

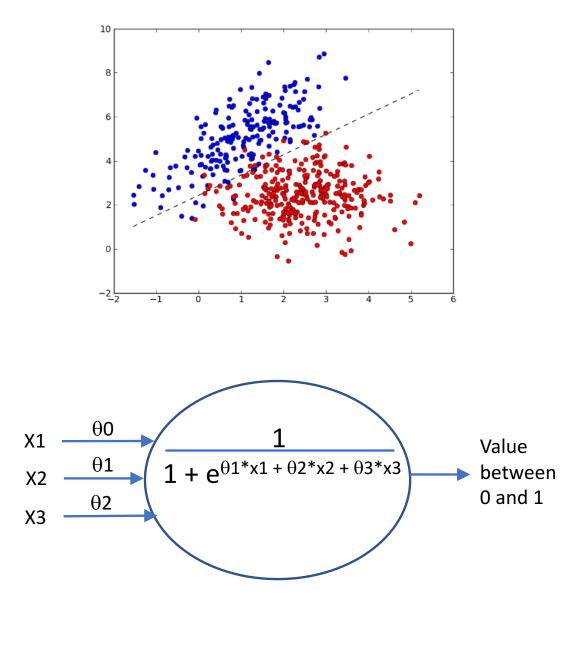
AdamOptimizer]



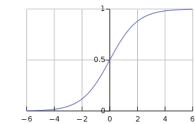
Consequence of a high learning rate where the jumps are too large and we are not able to minimize the loss.

Weights

## Classification (Logistic Regression)



Hypothesis:  $\frac{1}{1 + e^{-(\theta_0 + \theta_1 * x_1 + \theta_2 * x_2)}}$ 



Cost function:

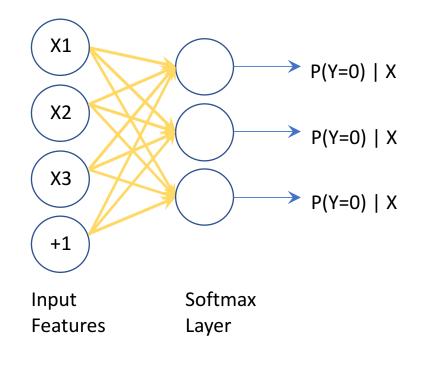
$$J(\theta) = -\frac{1}{m} \sum_{i=1}^{m} \left[ y^{(i)} \log(h_{\theta}(x^{(i)})) + (1 - y^{(i)}) \log(1 - h_{\theta}(x^{(i)})) \right]$$

Gradient Descent Algorithm:

Repeat {

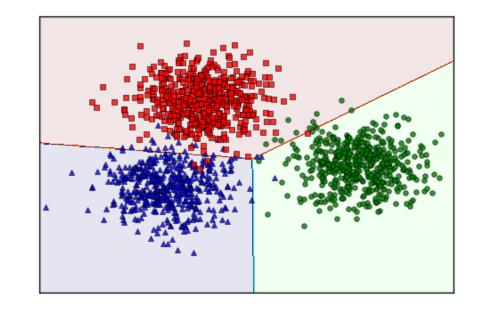
$$\theta_j := \theta_j - \frac{\alpha}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

## Softmax Regression (Multinomial Logistic Regression)



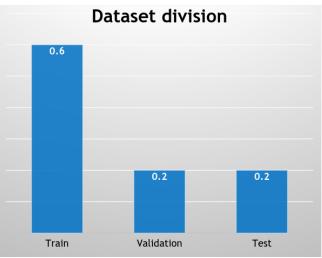
$$P(Y = i | x, W, b) = softmax_i(Wx + b)$$
$$= \frac{e^{W_i x + b_i}}{\sum_j e^{W_j x + b_j}}$$

$$J(\theta) = -\sum_{i} y_{i} ln(\hat{y}_{i})$$
  
Ex: Computed ( $\hat{y}$ ) Targets (y)  
[0.3, 0.3, 0.4] [0, 0, 1]  
$$J(\theta) = -\sum_{i}^{n} [0 * ln(0.3) + 0 * ln(0.3) + 1 * ln(0.4)] = -ln(0.4)$$



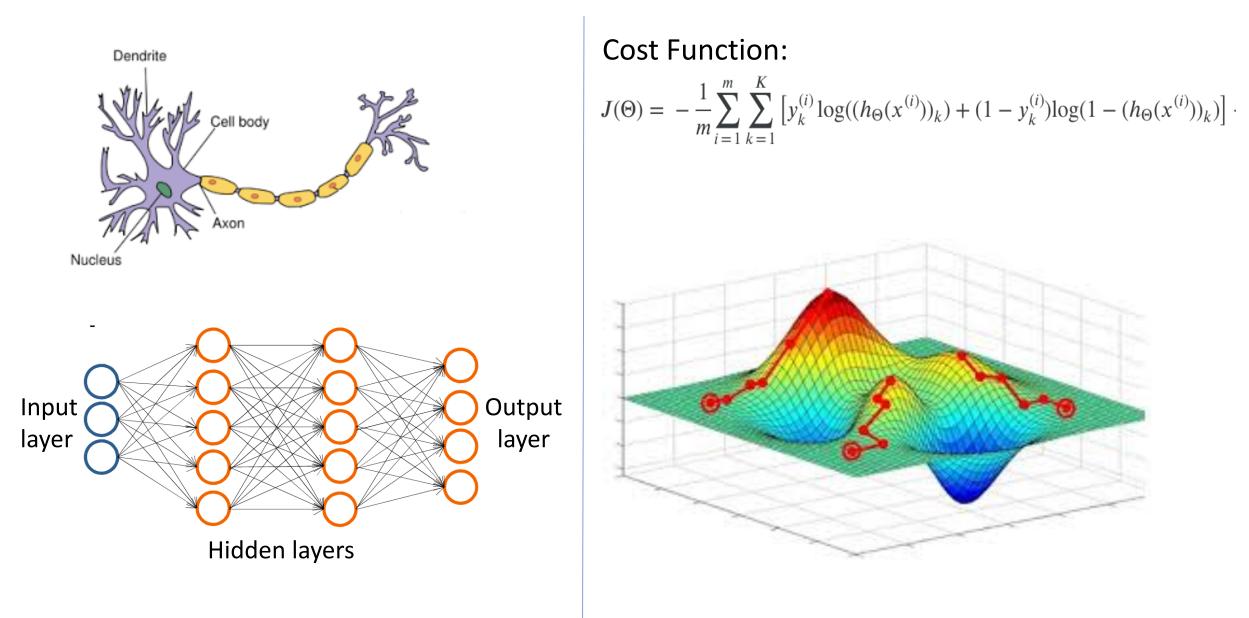
#### Multinomial Logistic Regression using Tensorflow

- <u>https://github.com/aymericdamien/TensorFlow-</u>
   <u>Examples/blob/master/notebooks/2\_BasicModels/logistic\_regression.ipynb</u>
- Stochastic Gradient Descent used in previous exercise for epoch in 1 : num\_epochs: for sample in 1:num\_samples #Run the optimizer for sample
  Mini Batch Gradient Descent used in current exercise Initialize batch\_size num\_batches = num\_samples/batch\_size for epoch in 1: num\_epochs: for batch in 1:num\_batches #Run the optimizer for batch
- Follow-up
- Change batch size in [25 50 100 200 400 800]
- Try with batch size 55000, i.e, batch gradient descent
- Try with batch size = 1, i.e, stochastic gradient descent
- Change number of epochs

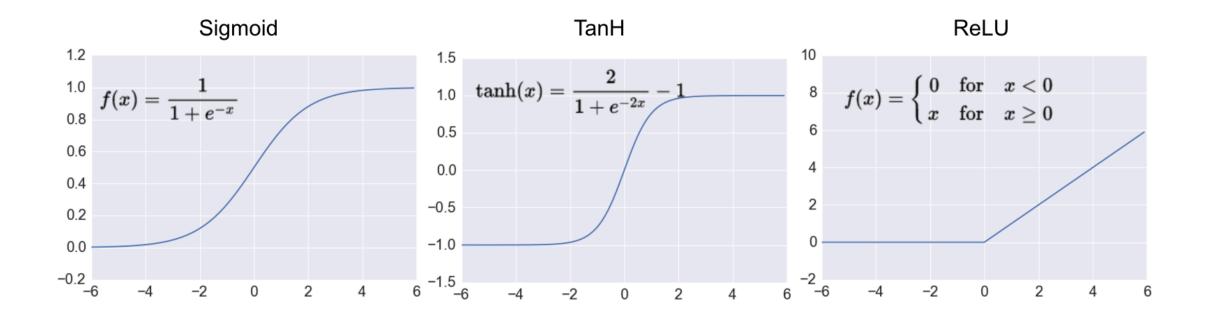


- Training set:
  - bang on this data all you want
- Test set:
  - rarely (weekly), evaluate progress
- Validation set:
  - periodically during training, check

## Artificial Neural Networks



#### **Activation Functions**



#### Forward Propagation and Back Propagation

Gradient Descent Iteration:

- 1. Forward Propagation (Calculate the cost using cost function)
- 2. Backward Propagation (Calculate partial derivatives of cost function w.r.t each parameter)

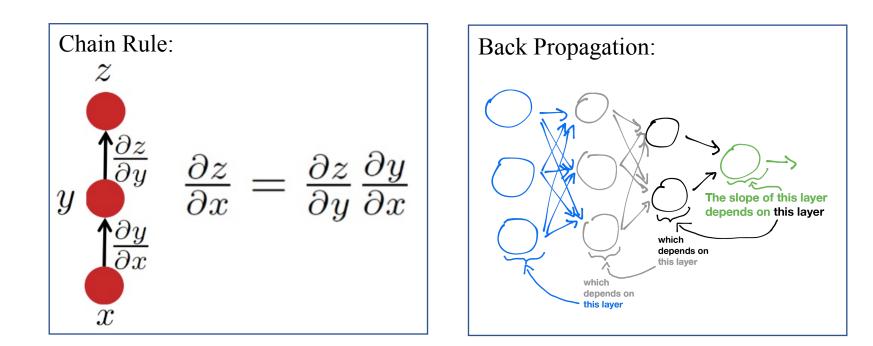
Option 1: Numerical Derivatives

Change the weight a little, calculate the change in cost function

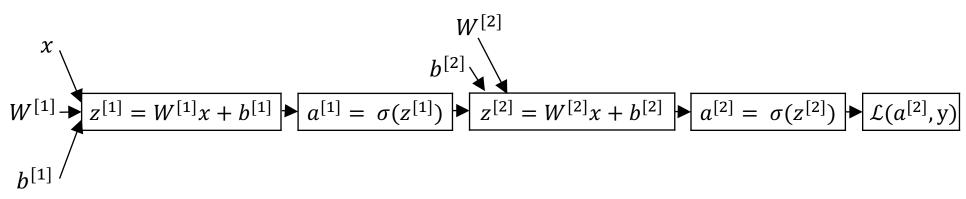
Computationally intractable

#### **Option 2: Analytical Derivatives**

#### Use Chain rule and compute analytical derivatives Reasonable turnaround times, 1000s of times cheaper



#### Neural Network Gradients



 $dZ^{[2]} = A^{[2]} - Y$  $dW^{[2]} = \frac{1}{m} dZ^{[2]} A^{[1]^T}$  $db^{[2]} = \frac{1}{m} np. sum(dZ^{[2]}, axis = 1, keepdims = True)$  $dZ^{[1]} = W^{[2]T} dZ^{[2]} * g^{[1]'}(Z^{[1]})$  $dW^{[1]} = \frac{1}{m} dZ^{[1]} X^T$  $db^{[1]} = \frac{1}{m} np. sum(dZ^{[1]}, axis = 1, keepdims = True)$ 

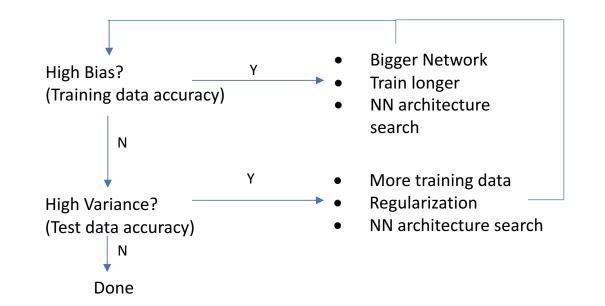
## Fully Connected Neural Network using Tensorflow

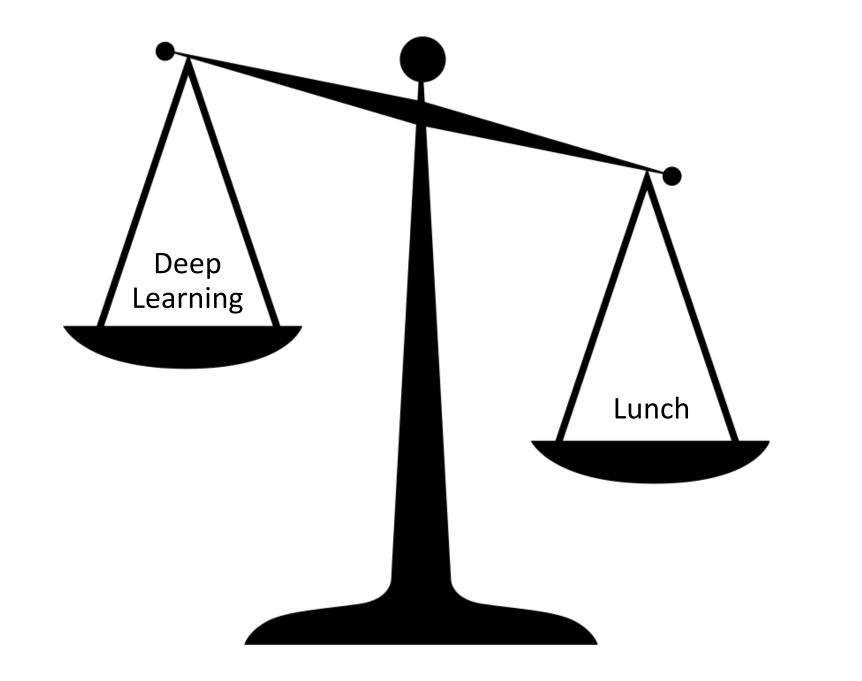
<u>https://github.com/aymericdamien/TensorFlow-</u>

Examples/blob/master/notebooks/3\_NeuralNetworks/neural\_network\_raw.ipynb

- Follow-up
- For the first 10 images in mnist.test.images
- Display Image
- Compute the prediction, then print the image and prediction by the model
- Change the number of neurons in hidden layers 1 and 2
- Change the activation function
- Change number of layers

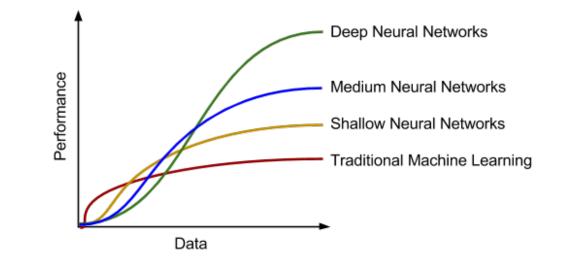
	High Bias (Underfitting)	High Variance (Overfitting)	High Bias & High Variance	Low Bias & Low Variance
Training Error	15%	5%	15%	5%
Testing Error	15%	15%	30%	5%



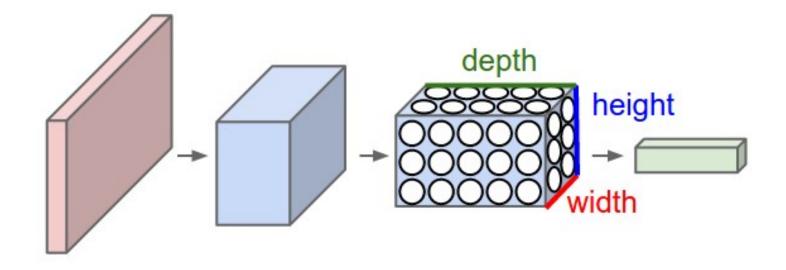


## Deep Learning

- Neural networks with lot more hidden layers (tens or hundreds)
- Types of Deep Neural Networks
  - Convolutional Neural Networks
  - Recurrent Neural Networks
  - Autoencoders
  - Restricted Boltzmann Machines
  - Generative Adversarial Networks
- Why now?
  - Data explosion
  - GPUs and other SIMD architectures
  - Some advancements in neural networks
- Nobody knows why it works but it works
- End-to-end Learning
  - No need for feature engineering



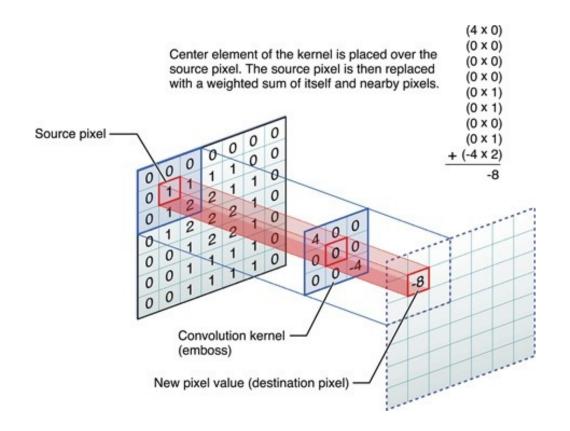
#### **Convolutional Neural Networks**



- Types of Layers:
  - Convolution Layer
  - ReLU Layer
  - Pooling Layer
  - Dropout Layer
  - Softmax Layer

#### http://cs231n.github.io/convolutional-networks/

## Convolution Operator in Convolutional Neural Networks

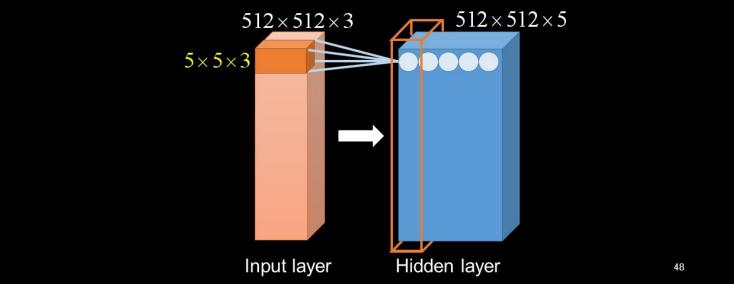


- CNN Hyper Parameters
  - Number of Filters (# of feature maps, depth of output layer)
  - Filter dimensions
  - Zero padding
  - Stride

### Parameter Sharing

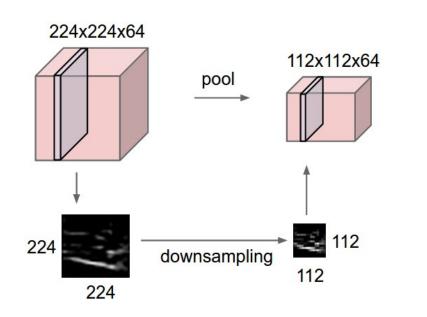
#### Parameter sharing

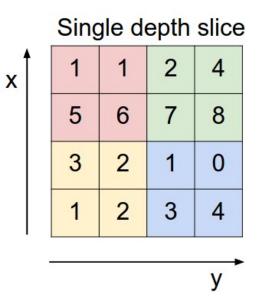
• We share parameter in the same depth.



- The kernel weights are shared across the image
- Reduces number of parameters
- Improves generalization capability of the model

## Pooling in CNN





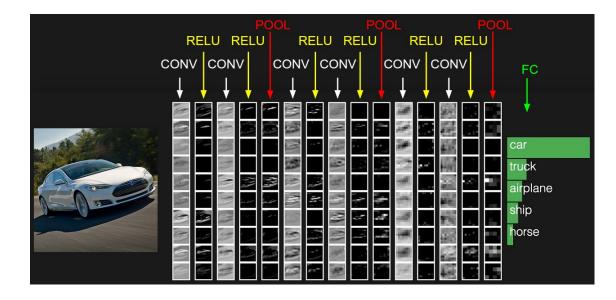
max pool with 2x2 filters and stride 2

6	8
3	4

## Convolutional Neural Networks

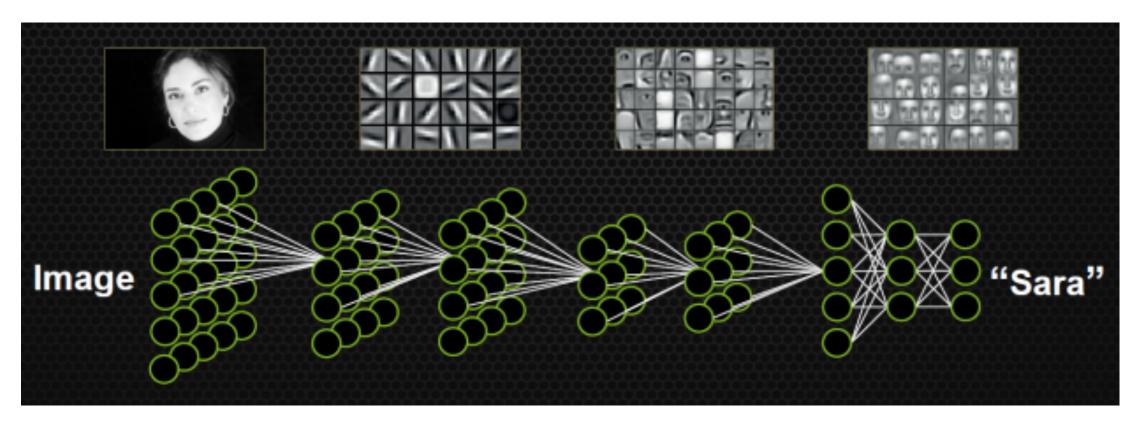
INPUT -> [[CONV -> RELU]\*N -> POOL?]\*M -> [FC -> RELU]\*K -> FC

* Indicates repitition	
POOL? – Optional pooling layer	
M >= 0	
N >= 0	
K >= 0	



https://community.arm.com/graphics/b/blog/posts/when-parallelism-gets-tricky-accelerating-floyd-steinberg-on-the-mali-gpu

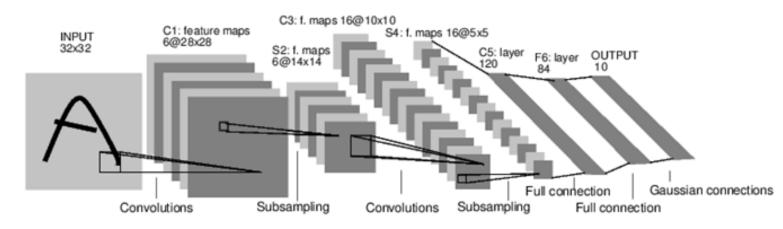
#### Features learned in CNN



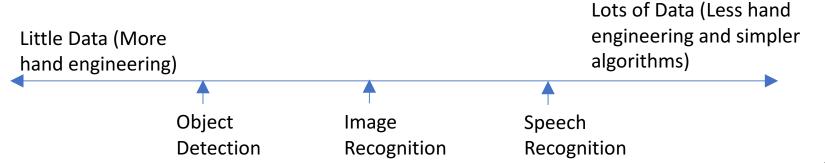
https://devblogs.nvidia.com/parallelforall/accelerate-machine-learning-cudnn-deep-neural-network-library/

### Some Popular CNNs

- LeNet (1990)
- AlexNet (2012)
- ZF net (2013)
- GoogLeNet (2014)
- VGGNet (2014)
- ResNet (2015)



A Full Convolutional Neural Network (LeNet)



Source Andrew Ng

#### AlexNet Exercise with IBM-Caffe

/opt/DL/caffe-ibm/examples/00-classification.ipynb

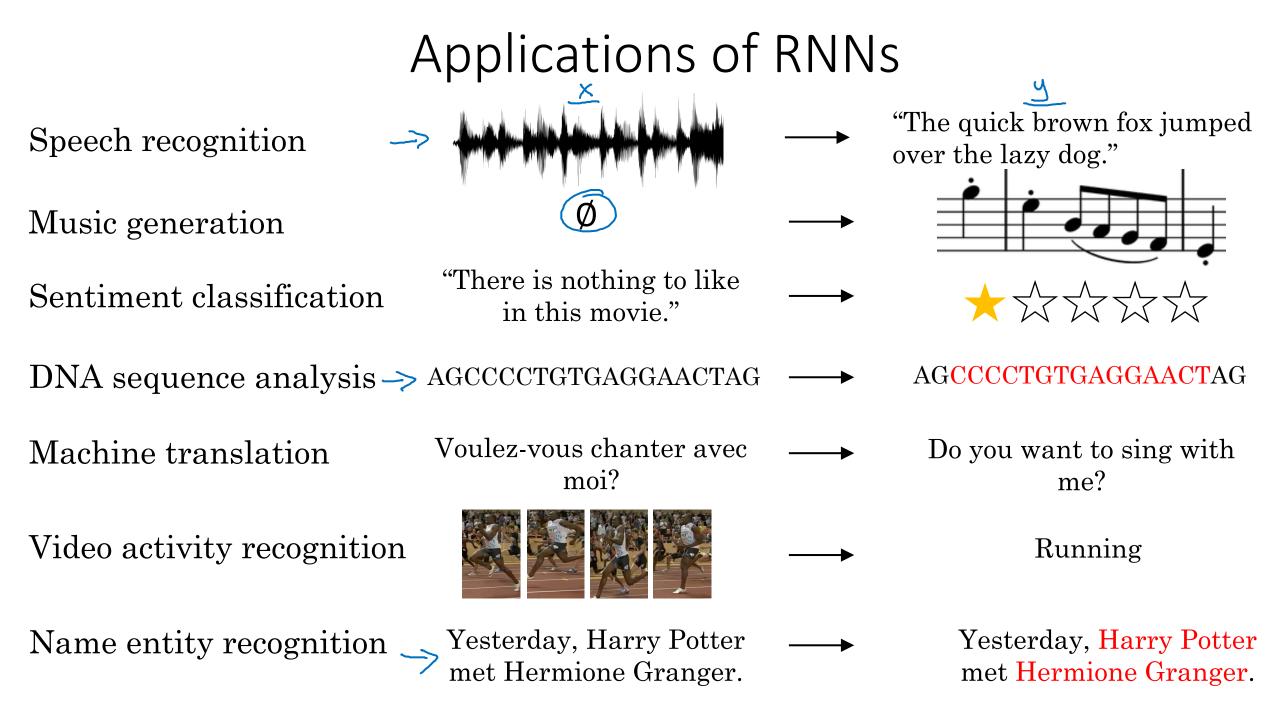
### Transfer Learning

#### **Transfer Learning Scenarios**

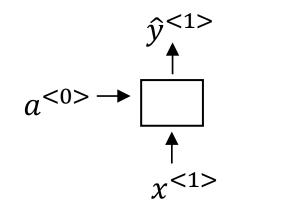
- Fixed Feature Extractor
- Fine Tuning the ConvNet
  - Train entire or part of the network
- Caffe-Zoo

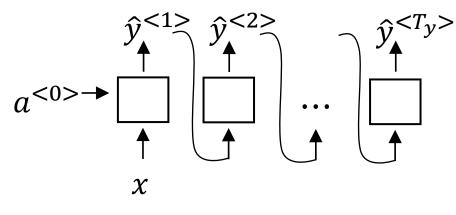
#### Transfer Learning Exercise Using Caffe

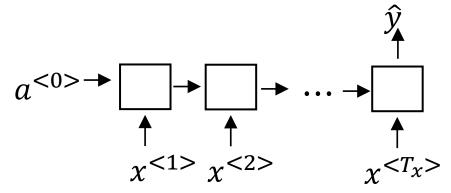
- /opt/DL/caffe-ibm/examples/02-fine-tuning.ipynb
- Follow-up
  - Try different images



## Summary of RNN types



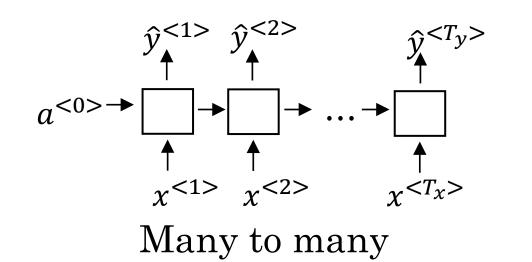


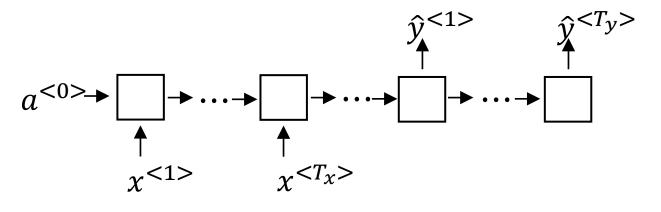


One to one

One to many

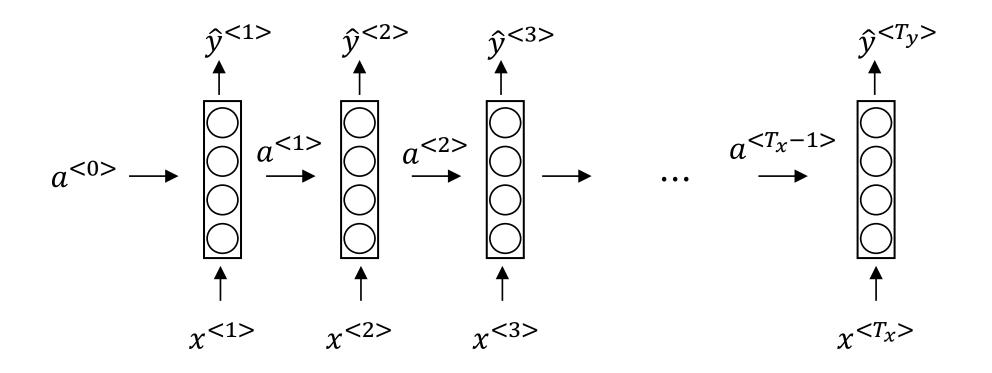
Many to one





Many to many

## **RNN Forward Propagation**



### **RNN** Parameters

$$a^{} = g(W_{aa}a^{} + W_{ax}x^{} + b_a)$$

$$\hat{y}^{} = g(W_{ya}a^{} + b_y)$$

#### Recurrent Neural Networks

https://github.com/nfmcclure/tensorflow\_cookbook/blob/master/09\_Recurre nt\_Neural\_Networks/03\_Implementing\_LSTM/03\_implementing\_lstm.ipynb

# Thank You