

Shared memory parallel algorithms in South 6

François Pellegrini

EQUIPE PROJET BACCHUS

Bordeaux Sud-Ouest

Outline of the talk

- Context
- Why shared-memory parallelism in **Scotch**



- How to implement it
- Next steps

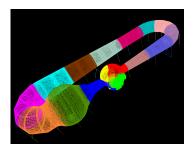


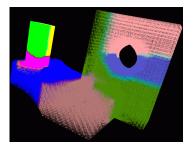
Context

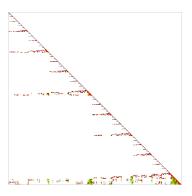


The **Scotch** project

- Toolbox of graph partitioning, static mapping and clustering methods
- Sequential **Scotch** library
 - Graph and mesh partitioning
 - Static mapping (edge dilation)
 - Graph and mesh reordering
 - Graph repartitioning and remapping [v6.0]
- Parallel **PT-Scotch** library
 - Graph partitioning (edge)
 - Static mapping (edge dilation) [v6.1]
 - Graph reordering
 - Graph repartitioning and remapping [v6.1]



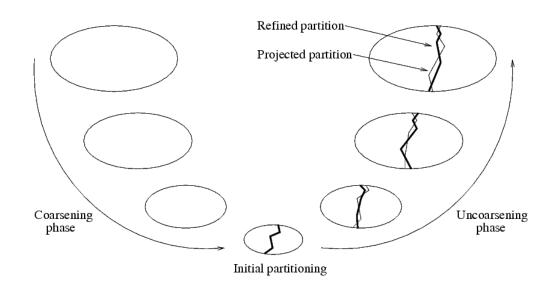






Multilevel framework

- Each partitioning is computed using a multilevel framework
 - Successive coarsenings by quotienting (matching)
 - Initial partitioning of the smallest graph
 - Prolongation of the result with local refinement



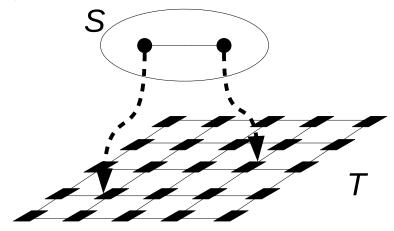


Static mapping

- Compute a mapping of V(S) and E(S) of source graph S to V(T) and E(T) of target architecture graph T, respectively
- Communication cost function accounts for distance

$$f_C(\tau_{S,T}, \rho_{S,T}) \stackrel{\text{def}}{=} \sum_{e_S \in E(S)} w(e_S) \left| \rho_{S,T}(e_S) \right|$$

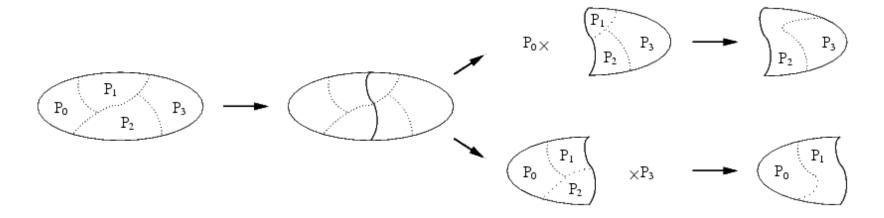
- Static mapping features are present in the sequential
 Static mapping features are present in the sequential
 Ilbrary since its inception
 - Now in PT-Scotch v6
 - PhD of Sébastien
 Fourestier





Parallelism in Scotch v5 (1)

- Distributed-memory parallelism in PT-Scotch only
 - Only very limited use of shared-memory threads for recursive bipartitioning

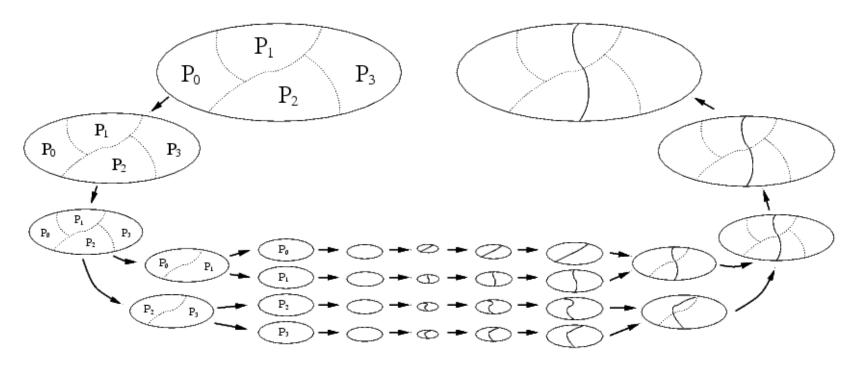


- Yet we wanted to move to direct k-way partitioning
 - Recursive bipartitioning useful only for sparse matrix ordering by nested dissection



Parallelism in Scotch v5 (2)

- The bulk of the work is performed during the coarsening and the uncoarsening phases
 - Not strictly uncoarsening but local optimization

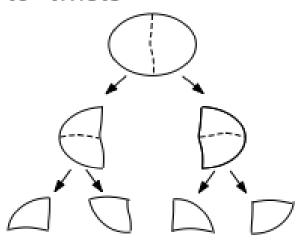




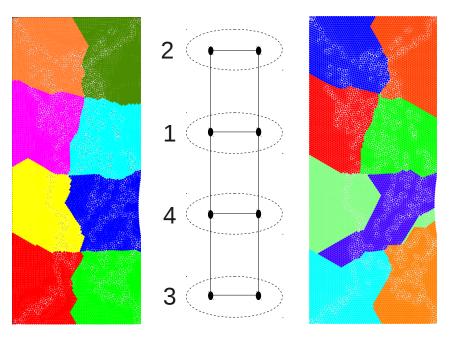
Parallel static mapping

- Recursive bi-mapping won't do in parallel
 - All subgraphs at some level are supposed to be processed simultaneously for parallel efficiency
 - Yet, ignoring decisions in neighboring subgraphs can lead

to "twists"

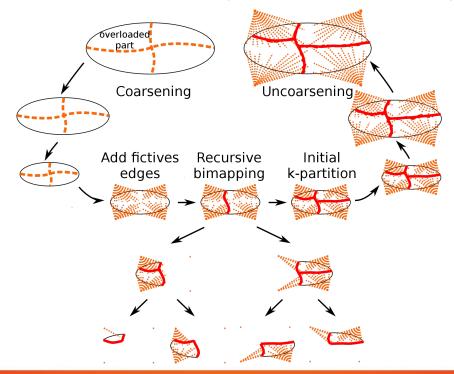


Sequential processing only!



Parallel dynamic remapping

- Bias cut cost function with fictitious edges [Devine et al.]
- Take advantage of the k-way multilevel framework
 - Initial mapping is computed sequentially (no twists!)
 - Take dilation into account during k-way refinement
 - Sequential initial task may become too large some day





Why shared-memory parallelism?



Reasons for shared-memory parallelism

- For the "sequential" version:
 - It is too bad not to take advantage of multi-core processors on "sequential" computers and workstations
 - Users don't want to meddle with new interfaces and third-party libraries they do not know
- For the parallel version :
 - It is too bad to resort only to distributed-memory parallelism when parallel architectures possess shared-memory nodes
 - Critical for exascale-class machines



How to proceed?

- Three criteria to consider :
 - Locality, locality, locality!
- We are already bad at that :
 - Our op/byte rate is low
 - Initial graph data may be randomly distributed



How to implement it



Basic blocks

- Use of two (hopefully common) technologies :
 - POSIX Pthreads
 - Atomic built-ins
 - -__sync_lock_test_and_set () and its friends...
- OpenMP is cool, but sometimes our algorithms require fine synchronization and complex primitives
 - E.g. MPI-like reduction operations, scan, etc.
 - We may lose some cycles when launching threads wrt. OpenMP, though



First experiments in the sequential realm

- We started with the sequential coarsening algorithms:
 - Matching
 - Graph coarsening
 - Diffusion-based local optimization
- Implementation already available in Scotch 6.0.0
 - 37% overall improvement in run time on 8 threads



And in the parallel realm?

- When computing an initial partitioning, data can be distributed arbitrarily
 - We already knew that for the sequential case
 - Some works on GPU algorithms [Fagginger Auer]
 - Matching algorithms are likely to be here just to compete to fill mating request buffers...
 - Coarsened graph building routines may behave better
 - Yet not much shared-memory locality to expect
 - Local optimization algorithms are expected to be scalable, though
- The situation should improve for dynamic repartitioning



(Not so) trivial aspects



Better handling of threading issues

- Integrate the « hwloc » library
 - Library designed within the RUNTIME Inria Project-Team
 - Will allow us to handle thread locality issues in a platform-independent way
 - First third-party library in **Scotch** ever
 - Its use would be parametrized, though
 - We already do this for the Linux threads that we added in Scatch 6.0
- Provide threading on Windows
 - Compatibility library provided by Samuel Thibault
- All of the above in **Scotch** v6.1



How not to change the interface... (1)

- The Scotch API routines handle opaque SCOTCH_Graph and SCOTCH_Dgraph objects only
 - No additional « options » structure passed, that could hold threading information
- Such an optional argument would have been irrelevant for most publicized API routines
 - Graph coarsening, graph induction, graph coloring, etc...
- Yet, we want these algorithms to be run in parallel



How not to change the interface... (2)

- Handling of multi-threading cannot be performed in the strategy string
 - Because it also concerns the aforementioned routines
 - We must provide a homogeneous mechanism
- Handling of multi-threading should not be attached to the graph structures
 - Because several algorithms can be applied in parallel to the same graph structure
- We don't want to change the interface!



How not to change the interface... (3)

- We plan to create a SCOTCH_Context opaque data structure, that will:
 - Refer internally to the SCOTCH_Graph and SCOTCH_Dgraph data structures
 - Hold optional data such as the number of threads
- Scotch API routines will:
 - Still accept SCOTCH_Graph's and SCOTCH_Dgraph's when default behavior is expected
 - Use of all threads available to the calling thread
 - Accept SCOTCH_Context's when specific behavior is expected



Next steps



In the context of the JLPC

- Seeking early users for the parallel repartitioning (and remapping!) features of the upcoming v6.1
 - Sanjay's group on Charm++
 - Other volunteers?



Thank you for your attention!

Any questions?

http://scotch.gforge.inria.fr/

