

ACR: **A**UTOMATIC **C**CHECKPOINT/ **R**ESTART FOR SOFT AND HARD ERROR PROTECTION.

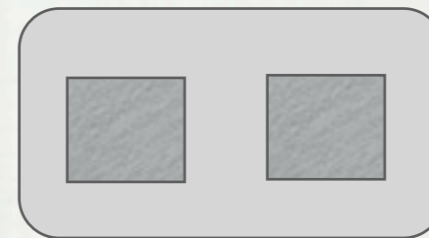
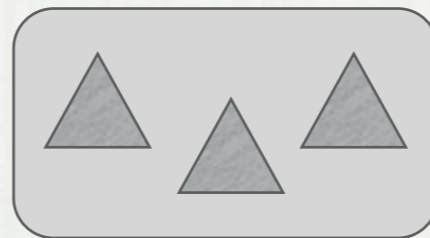
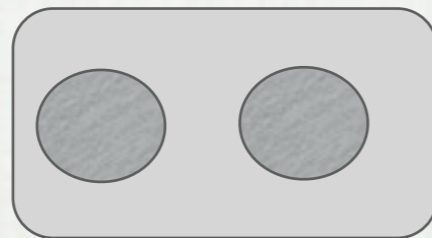
XIANG NI, ESTEBAN MENESES, NIKHIL JAIN, SANJAY KALE
PARALLEL PROGRAMMING LAB, UIUC

CONTENTS

- ☐ MOTIVATION
- ☐ ACR FRAMEWORK
- ☐ OPTIMIZATION
- ☐ EXPERIMENTAL RESULTS
- ☐ CONCLUSION

BACKGROUND

TASK

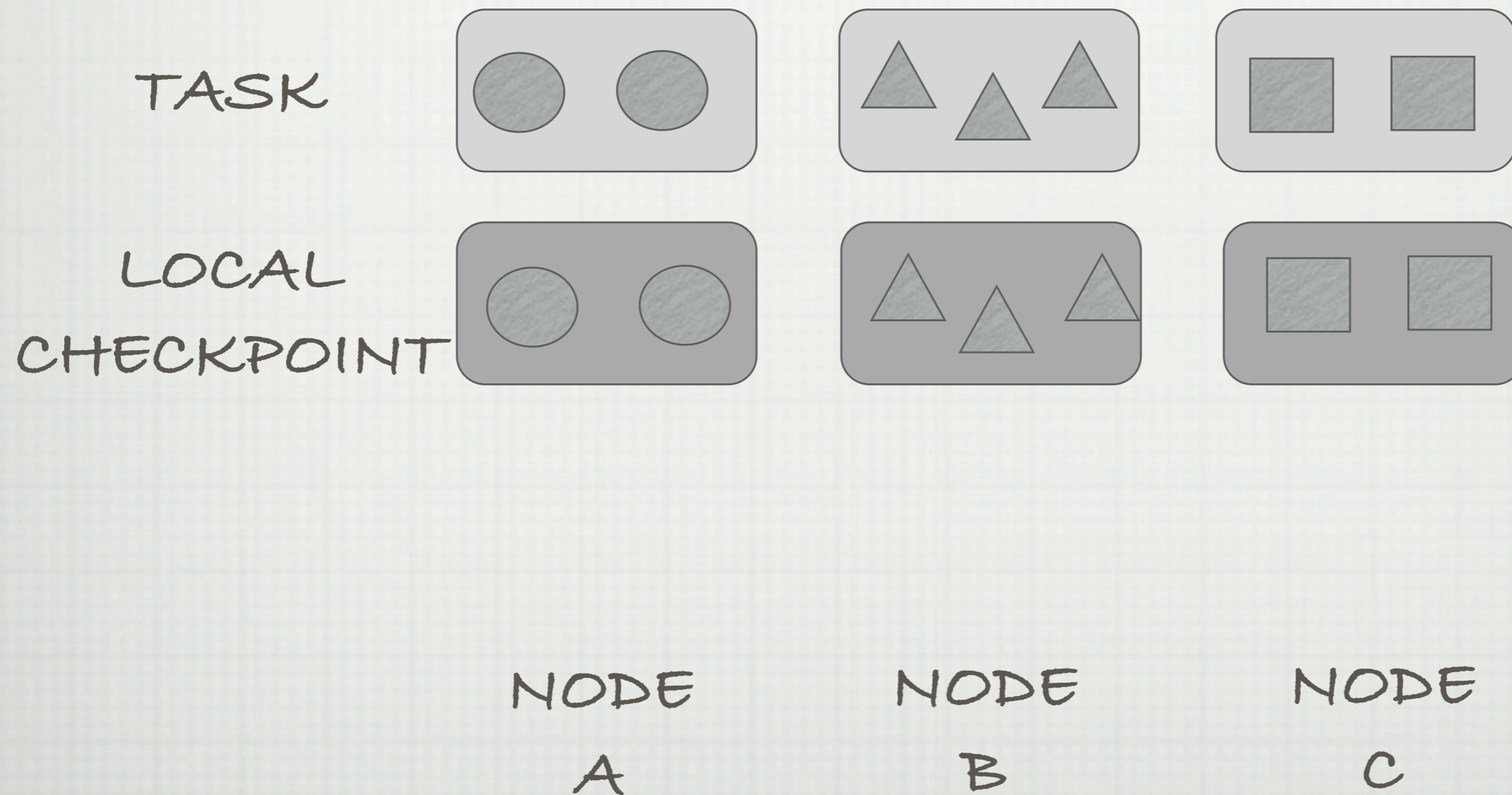


NODE
A

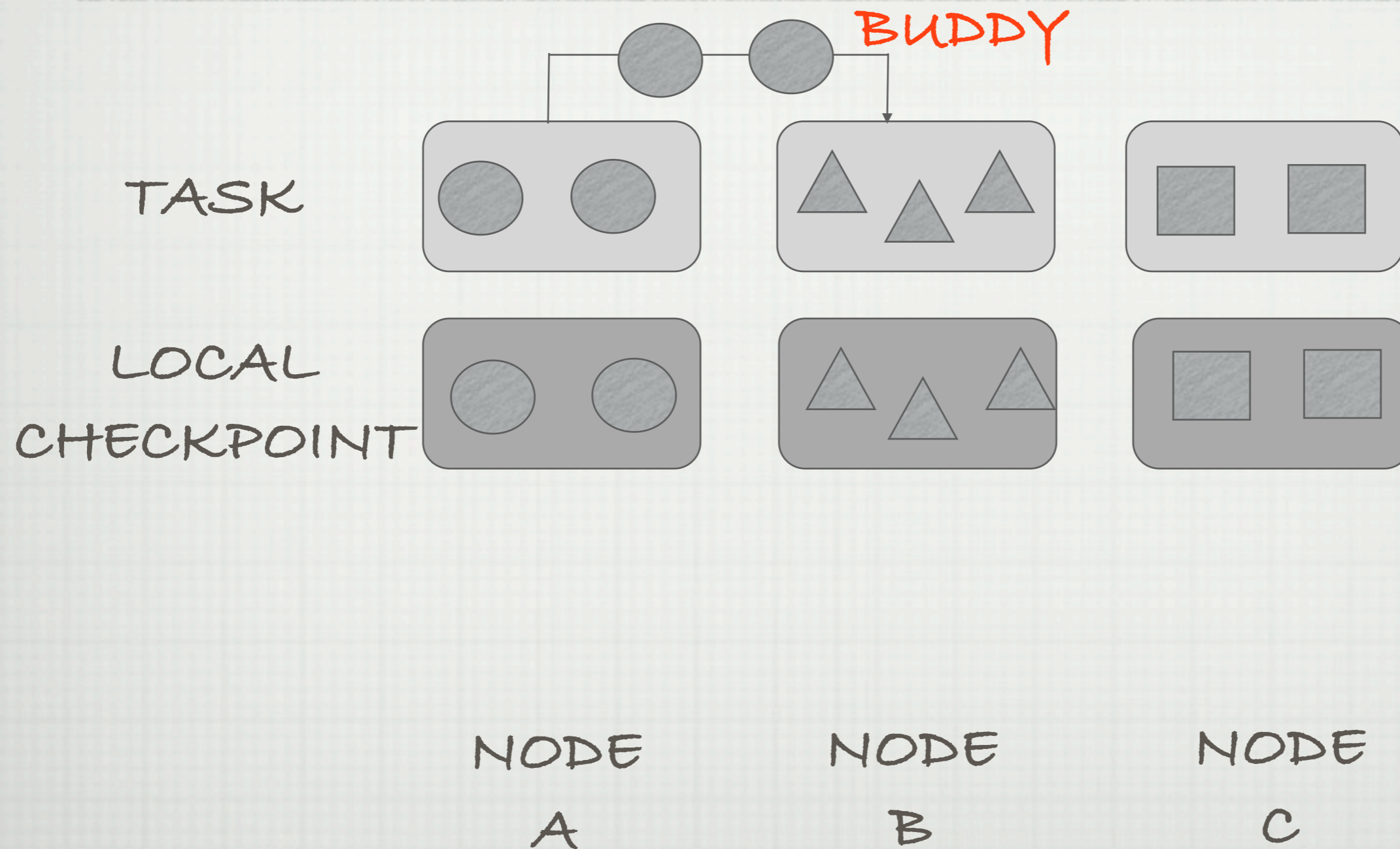
NODE
B

NODE
C

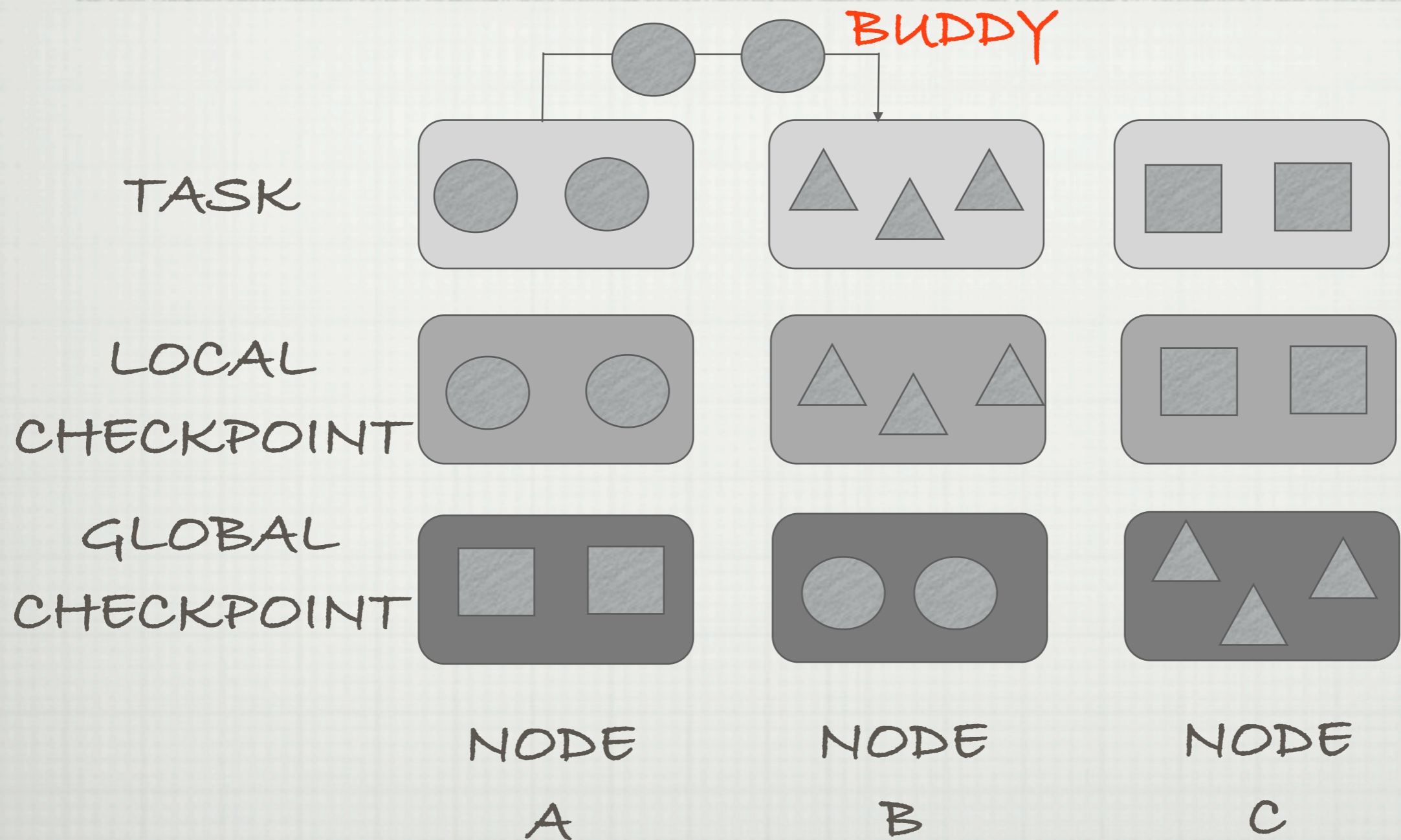
BACKGROUND



BACKGROUND



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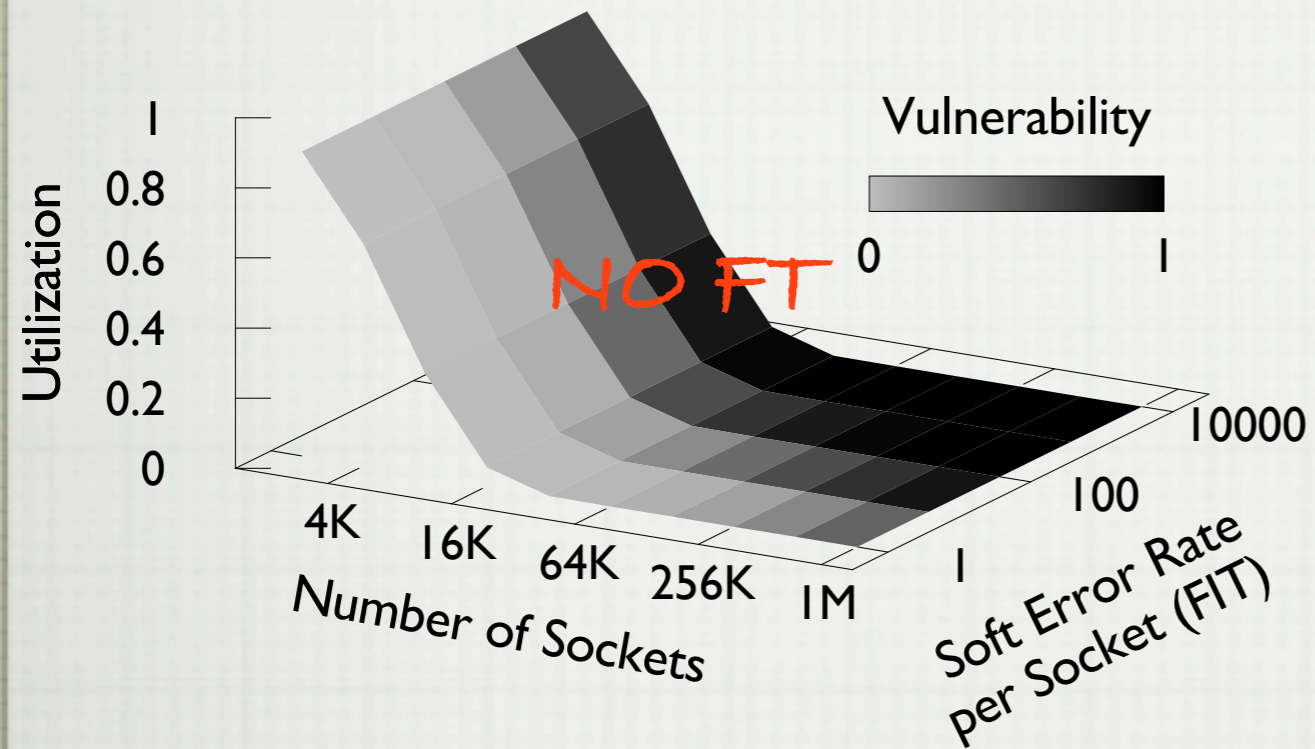
MOTIVATION

- ☐ New challenge: soft error.
- ☐ Computer electronic's sensitivity to radiation increases as their dimensions and operating voltage decreases
 - ☐ The requirements for high performance and low power.
- ☐ What may happen if soft failure rate keeps increasing?

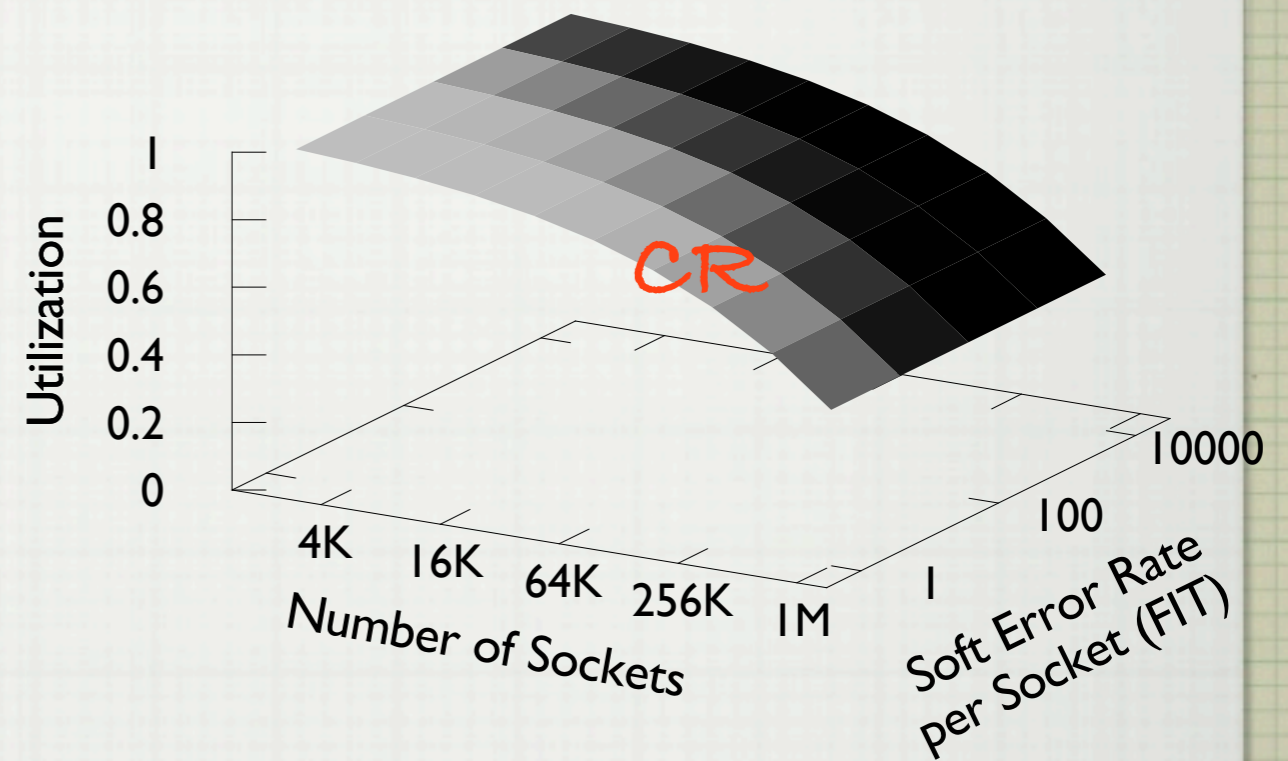
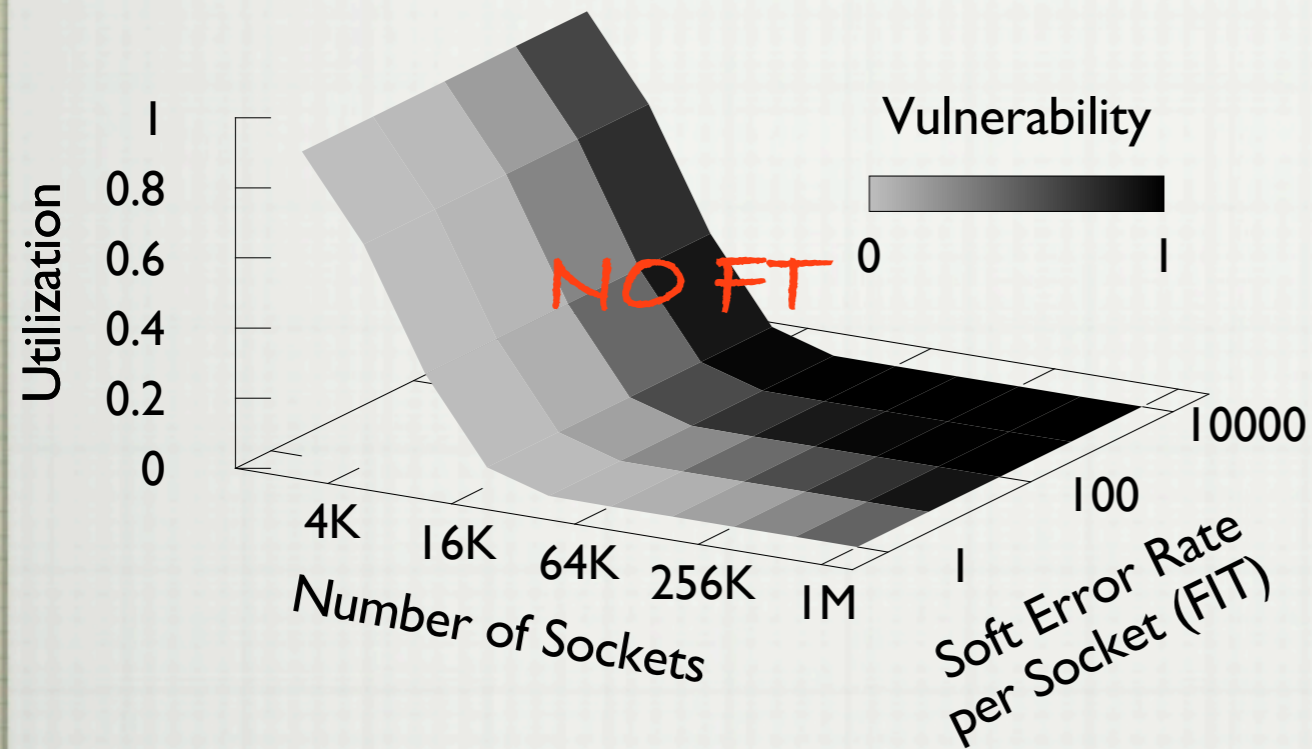
MOTIVATION

MOTIVATION

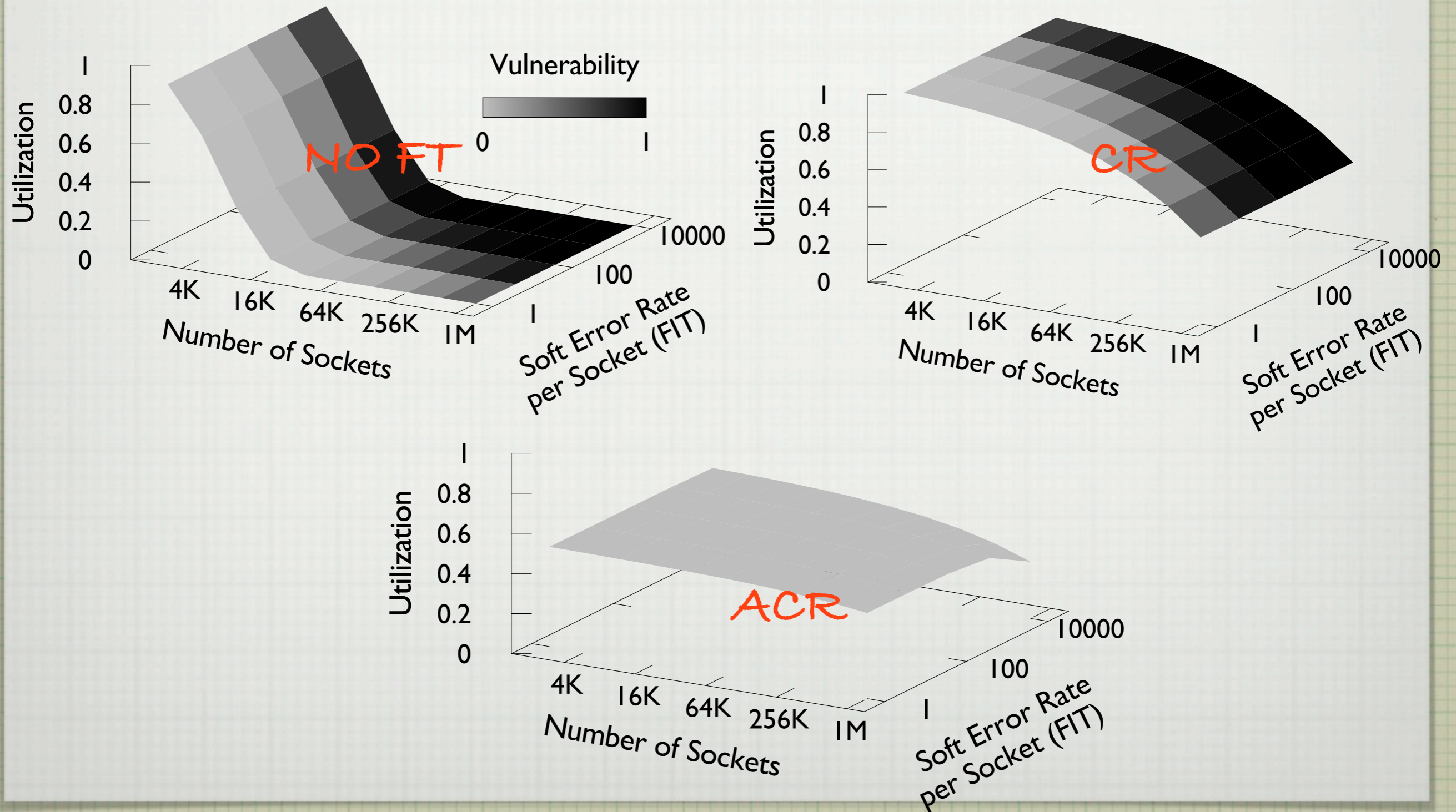
MOTIVATION



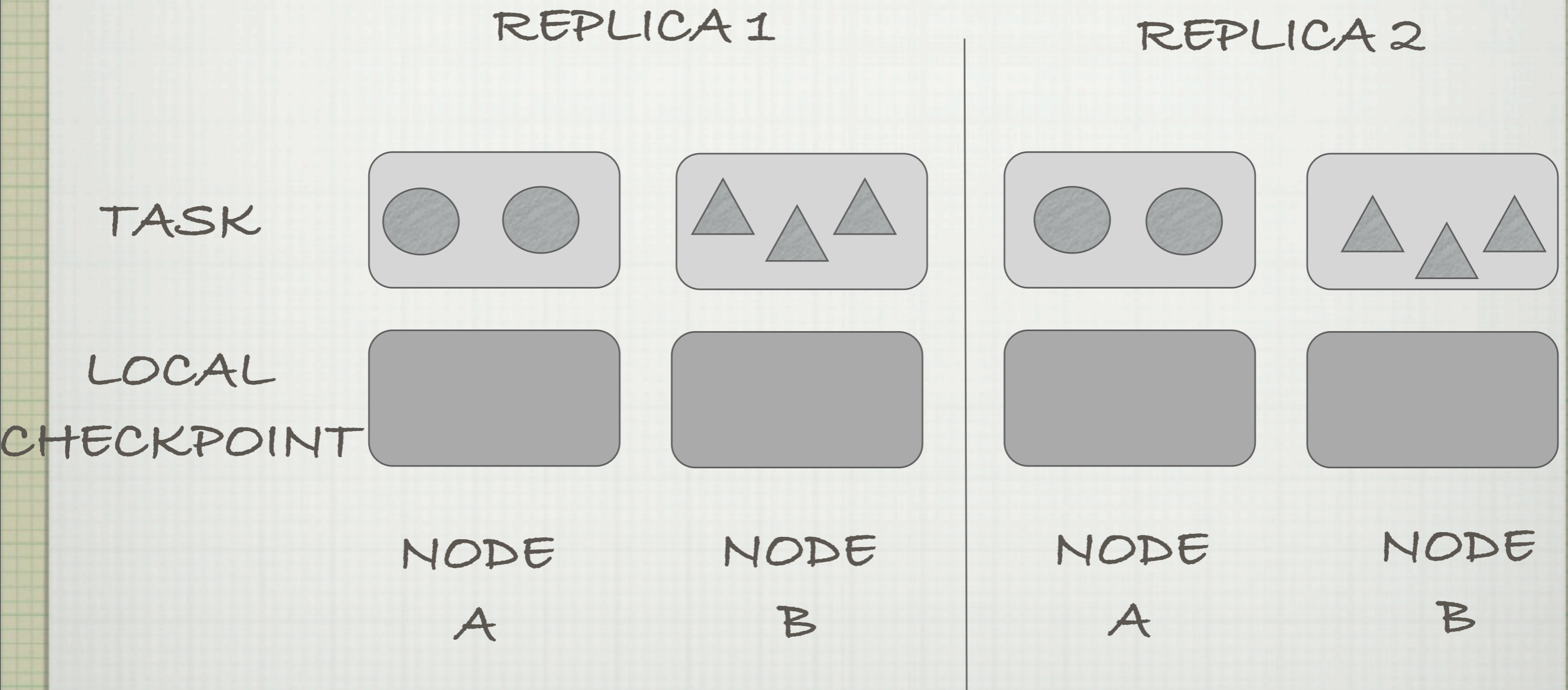
MOTIVATION



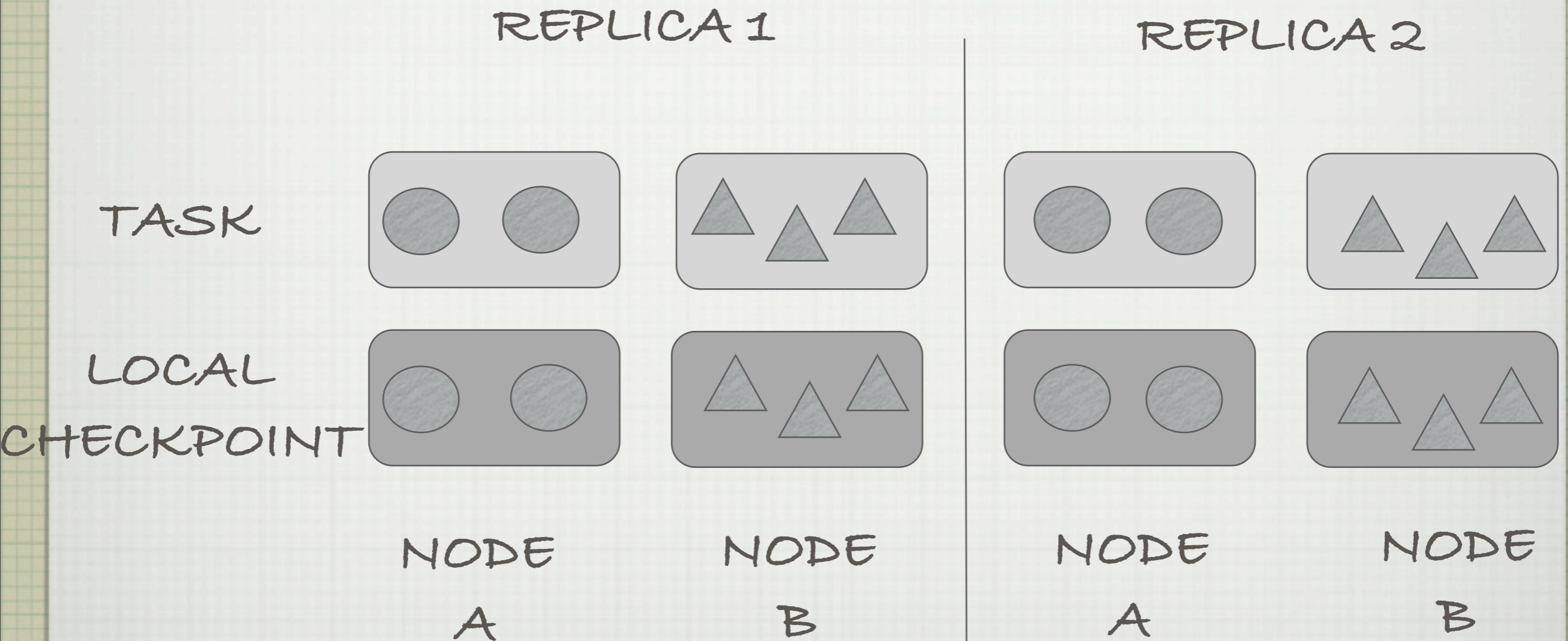
MOTIVATION



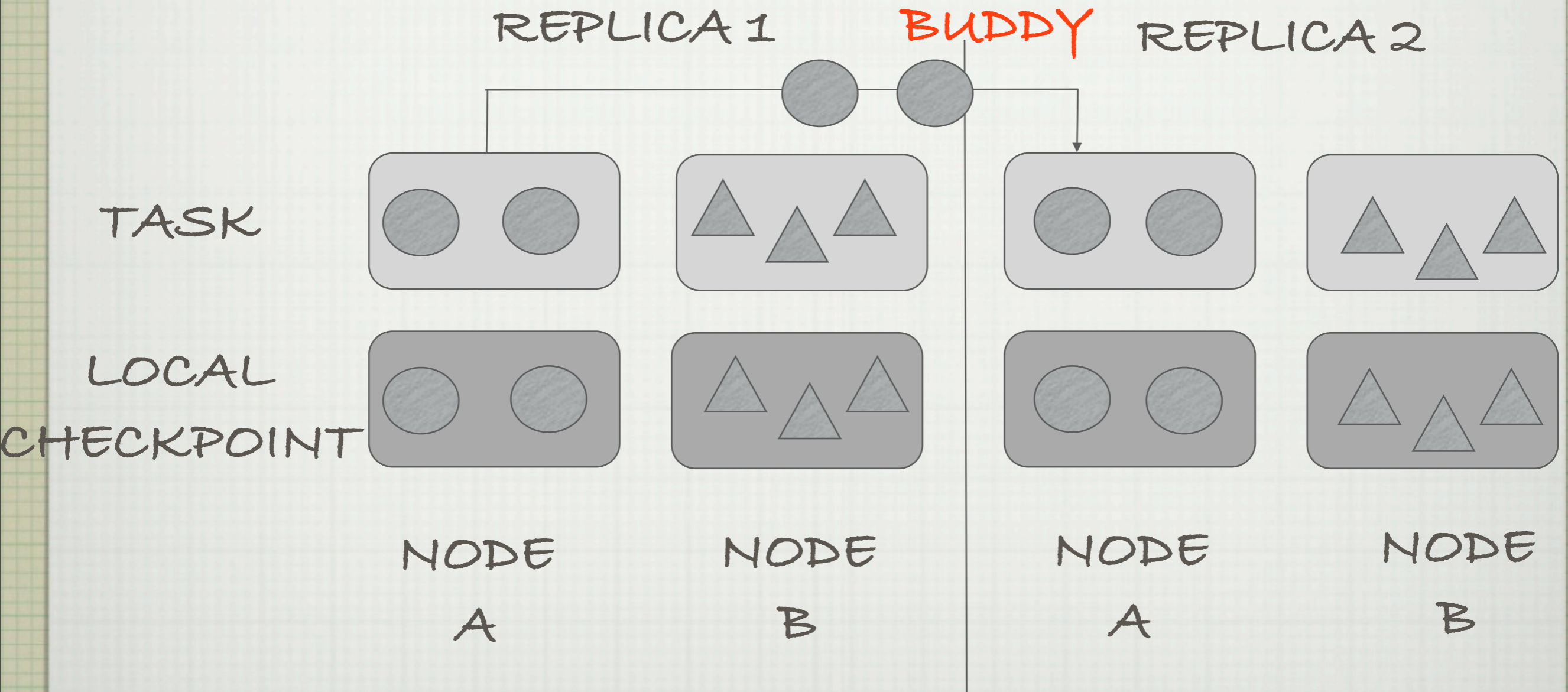
REPLICATION ENHANCED CHECKPOINTING



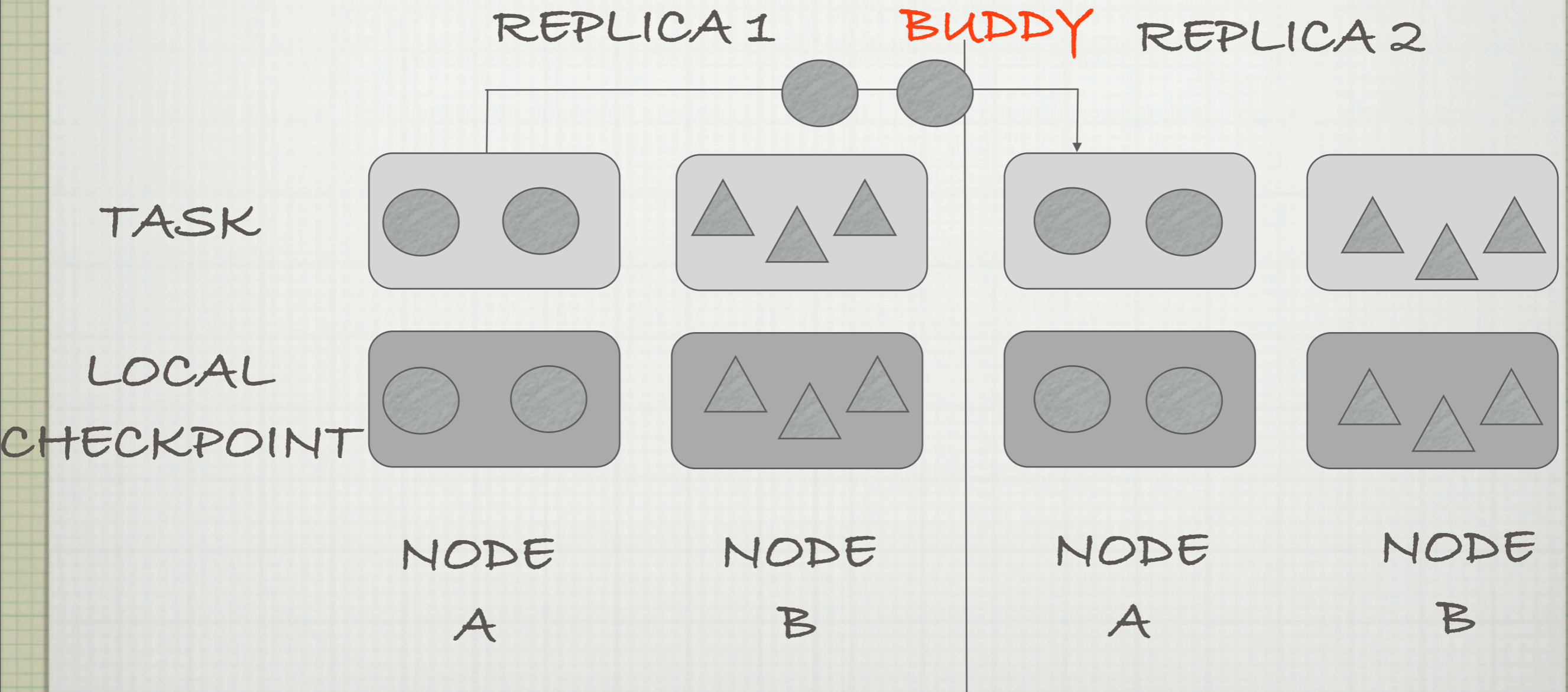
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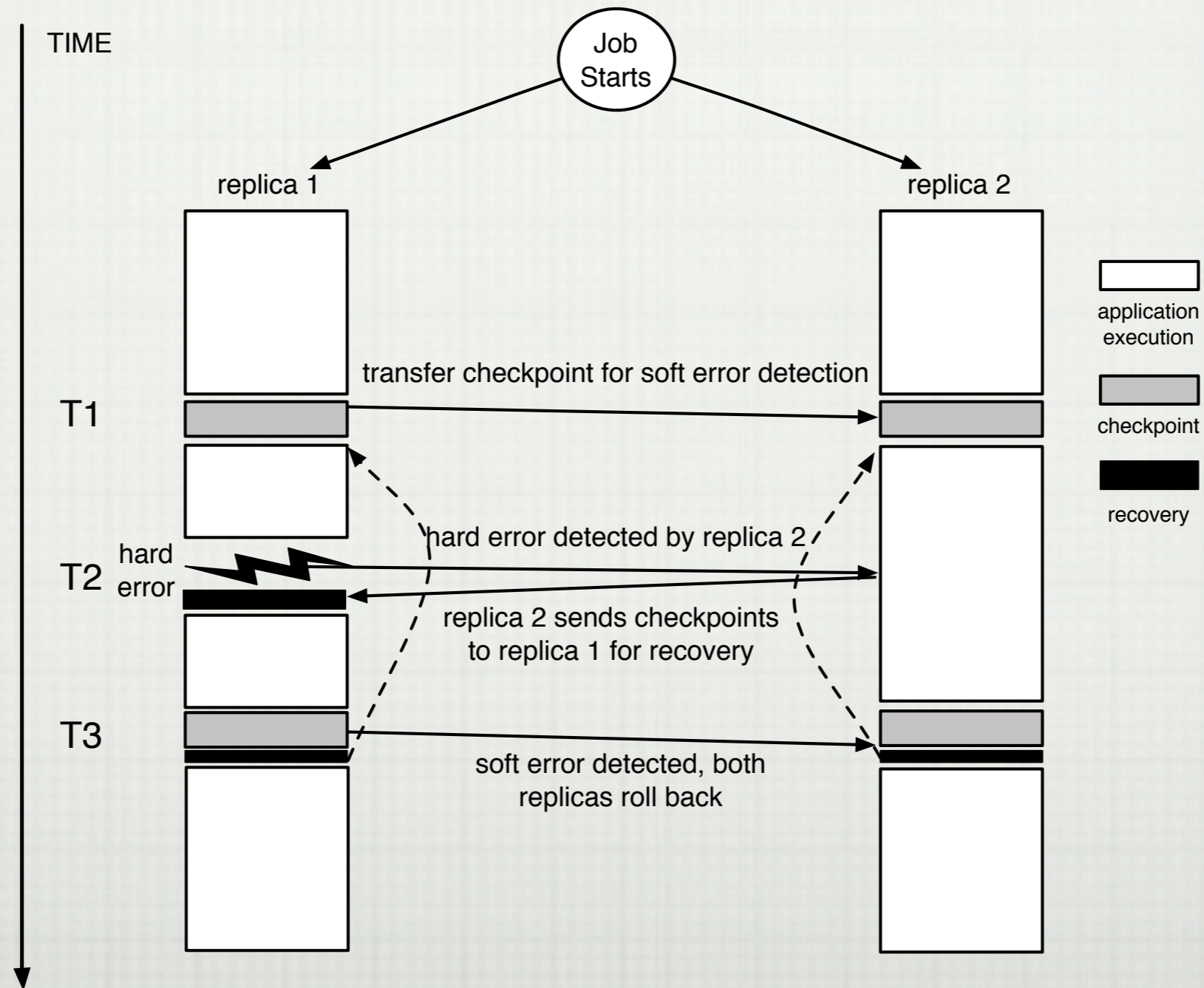


REPLICATION ENHANCED CHECKPOINTING



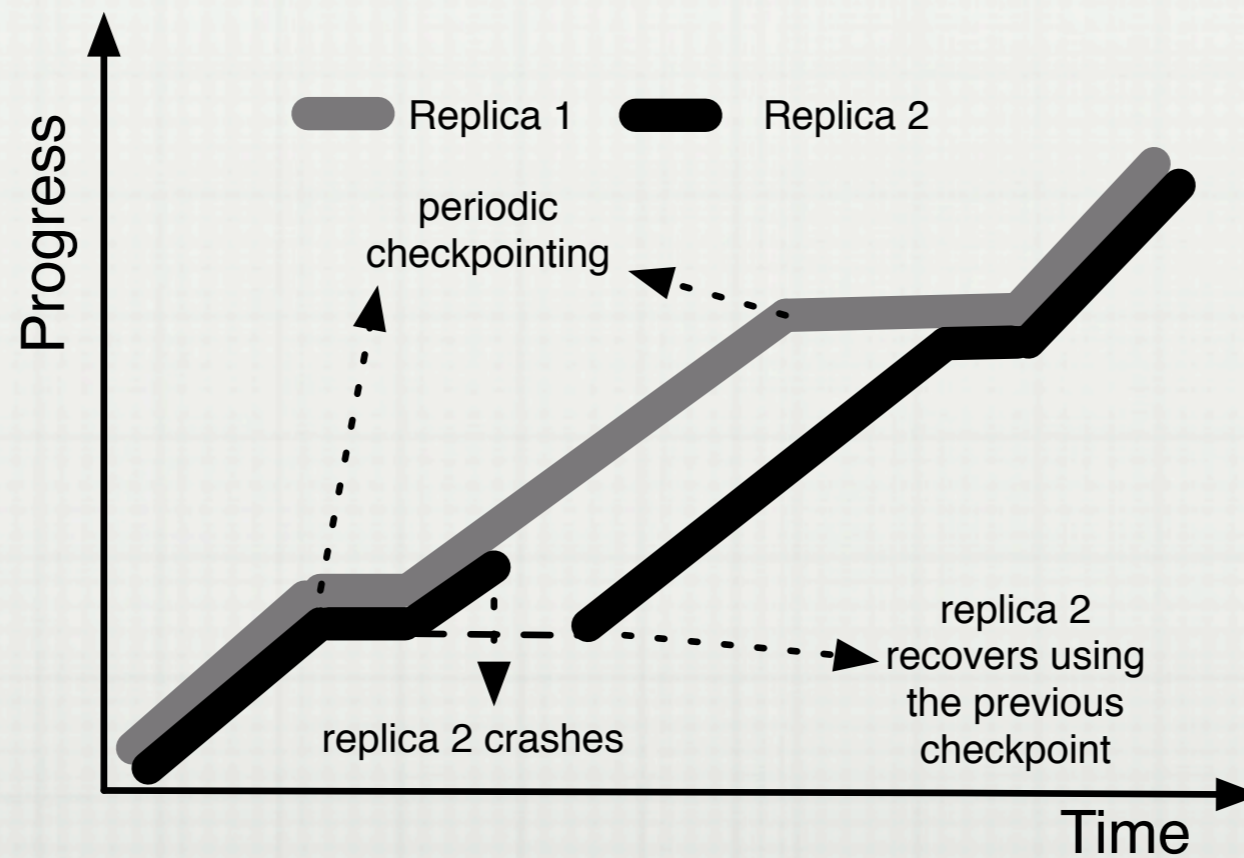
Comparison for soft data corruption

REPLICATION ENHANCED CHECKPOINTING

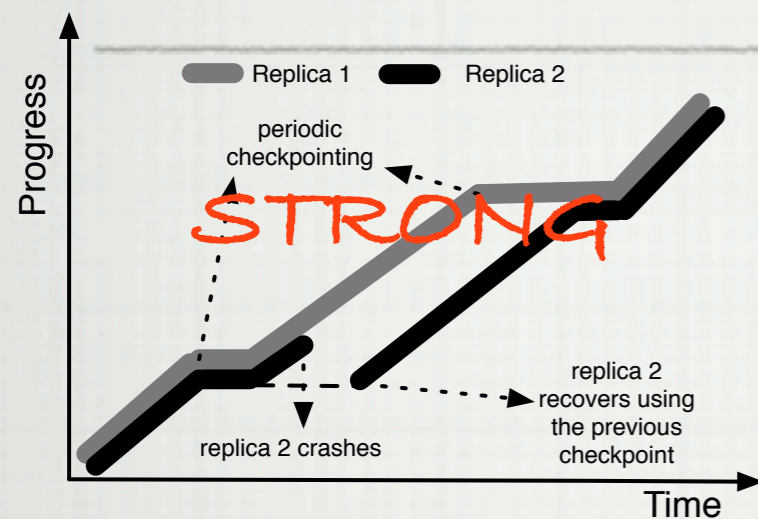


DIFFERENT WAYS TO RESTART FROM HARD ERROR

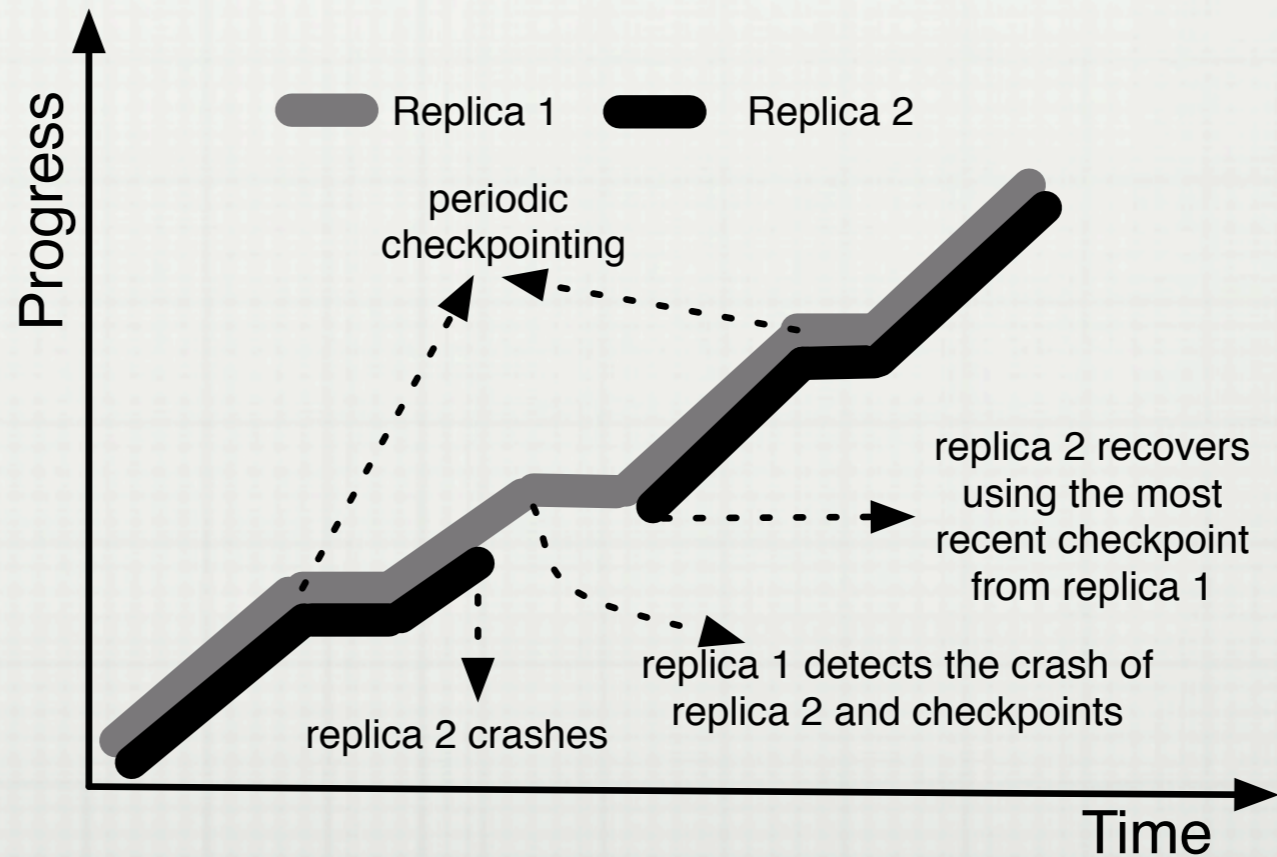
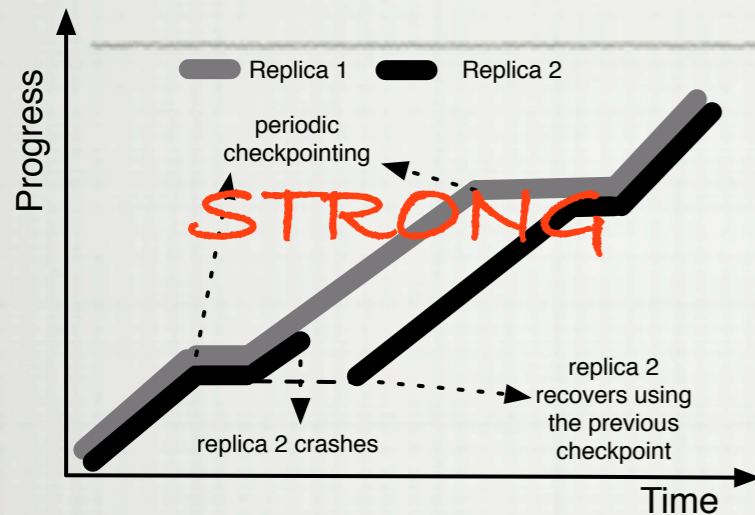
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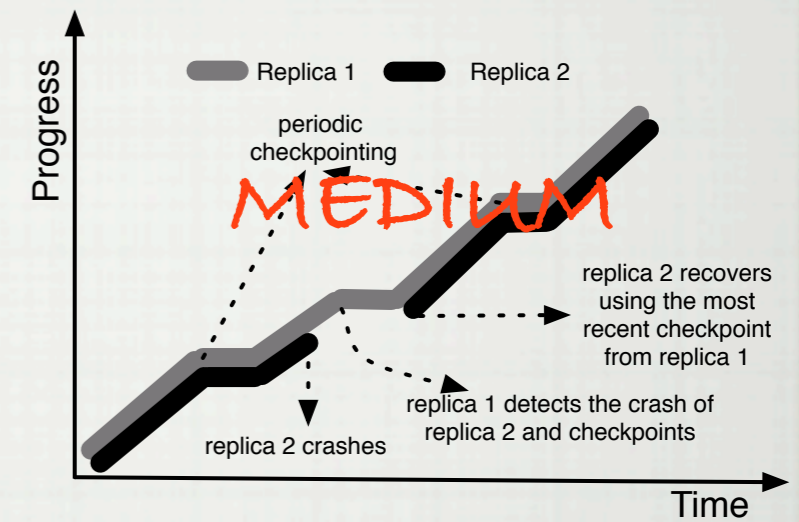
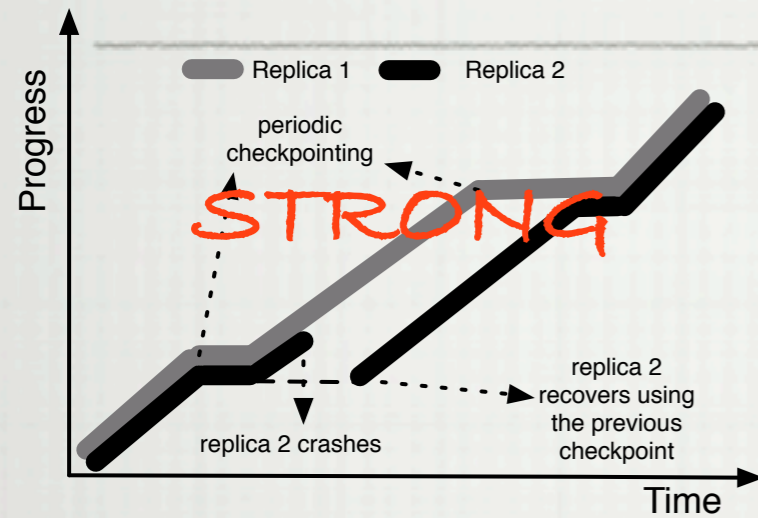
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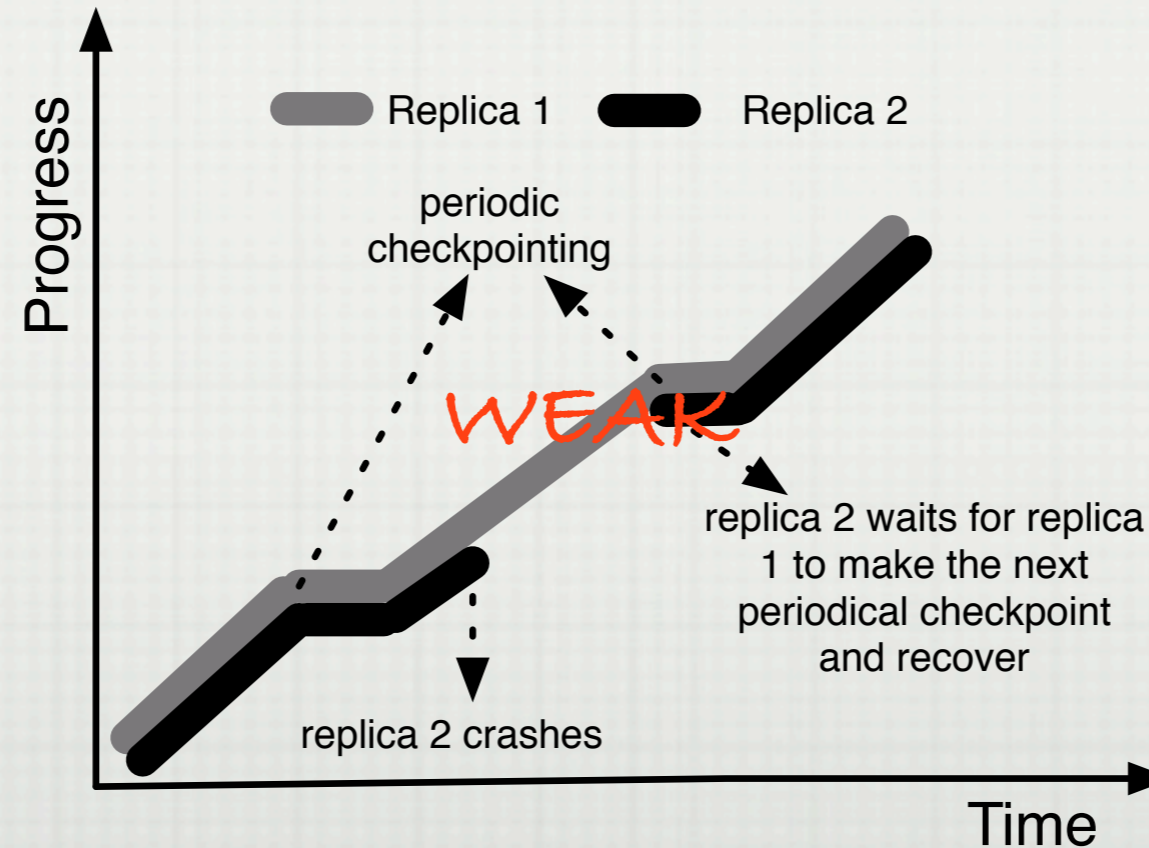
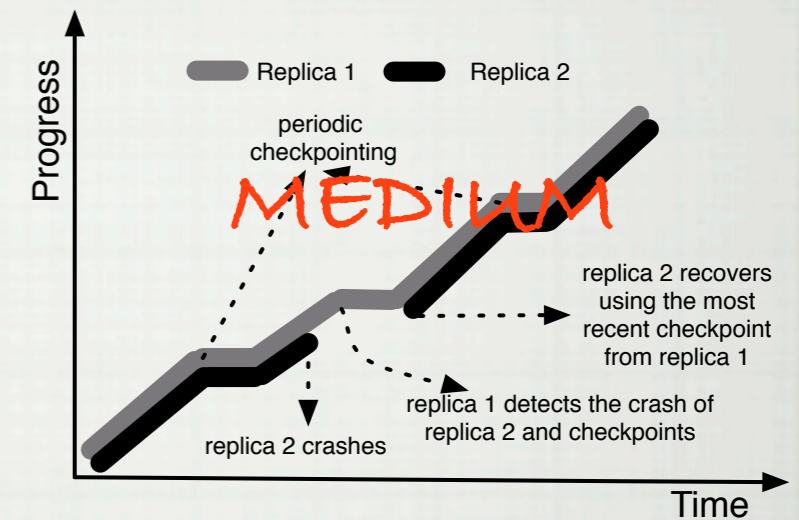
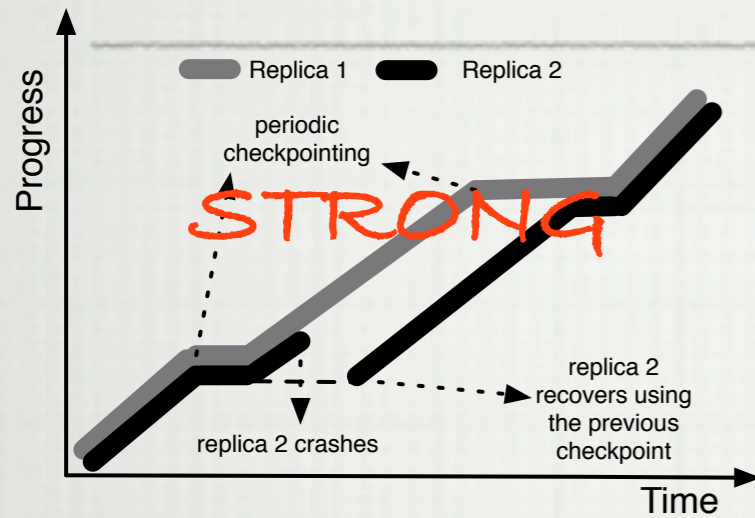
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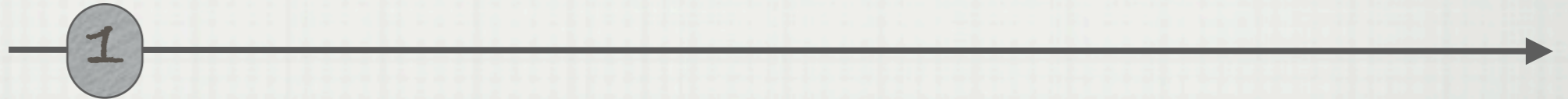
DIFFERENT WAYS TO RESTART FROM HARD ERROR



AUTOMATIC CHECKPOINT DECISION

ACR: UPDATE
LOCAL MAXIMUM
PROGRESS

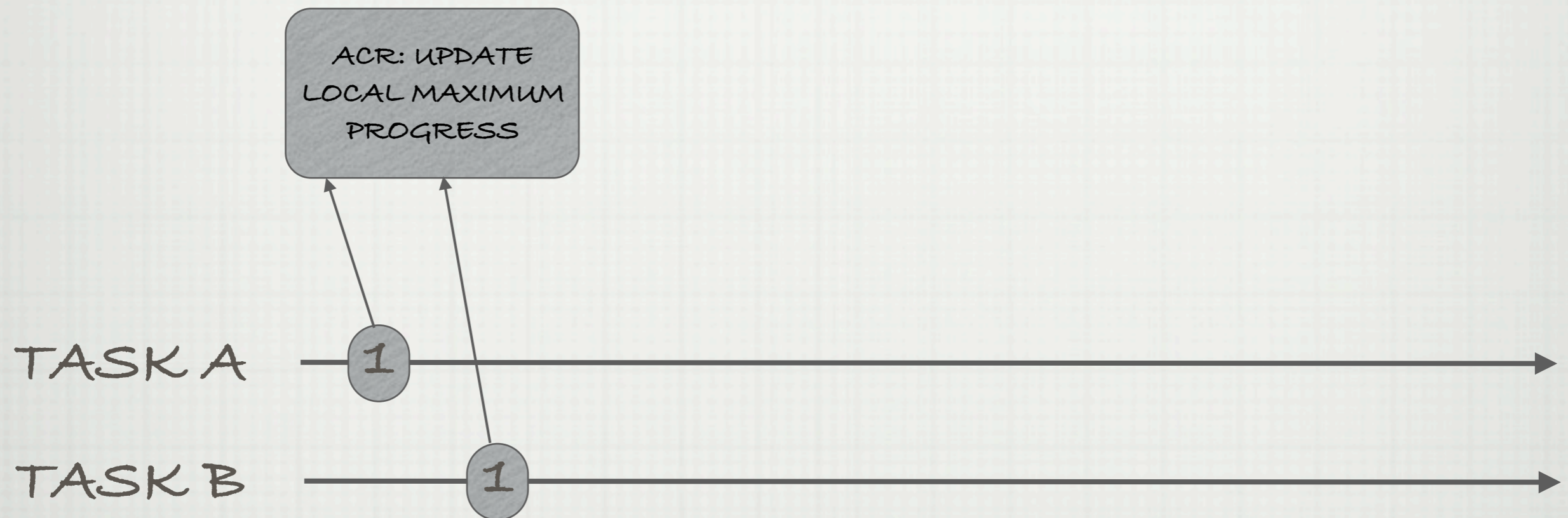
TASK A



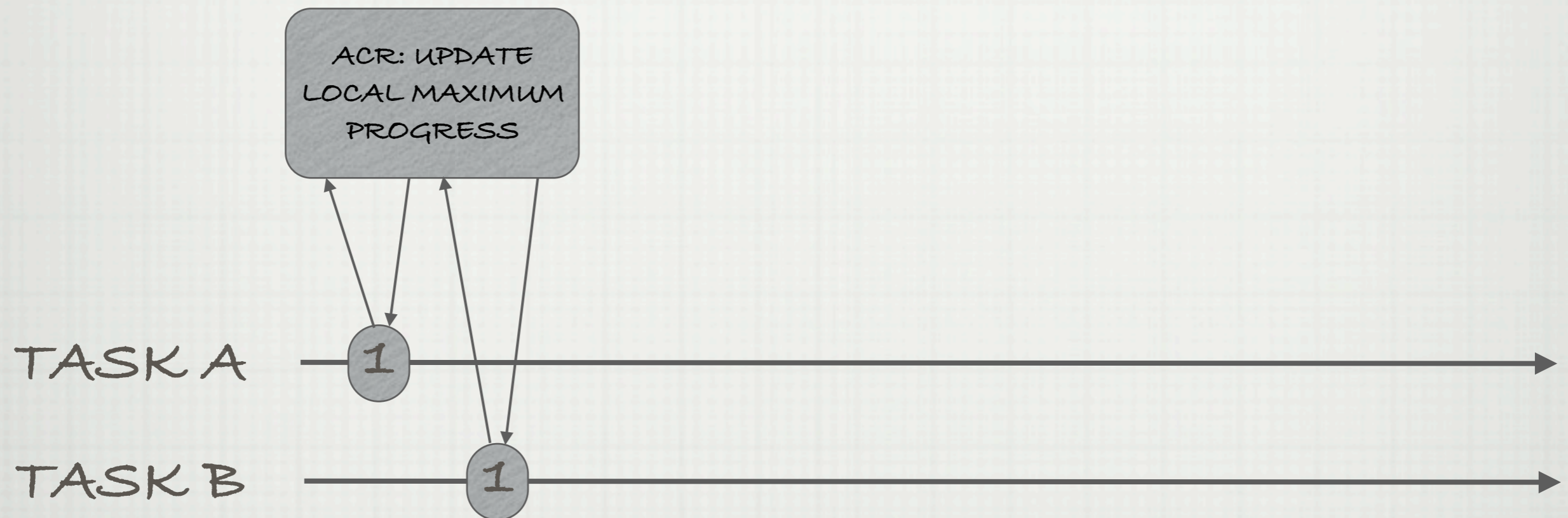
TASK B



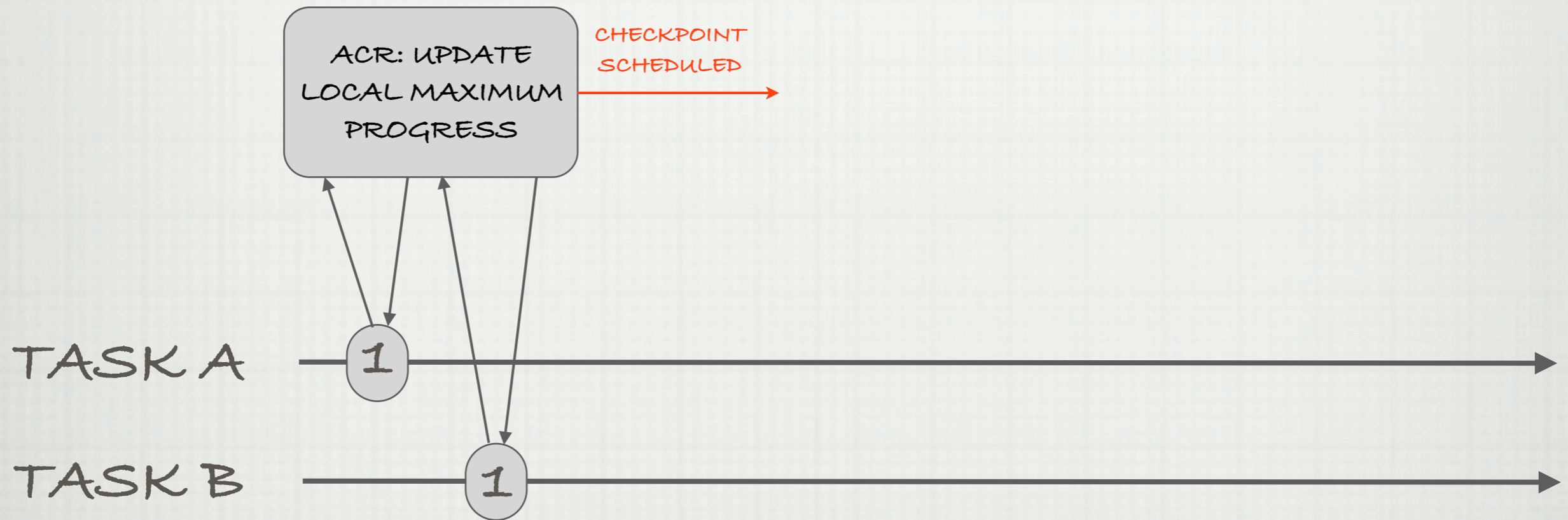
AUTOMATIC CHECKPOINT DECISION



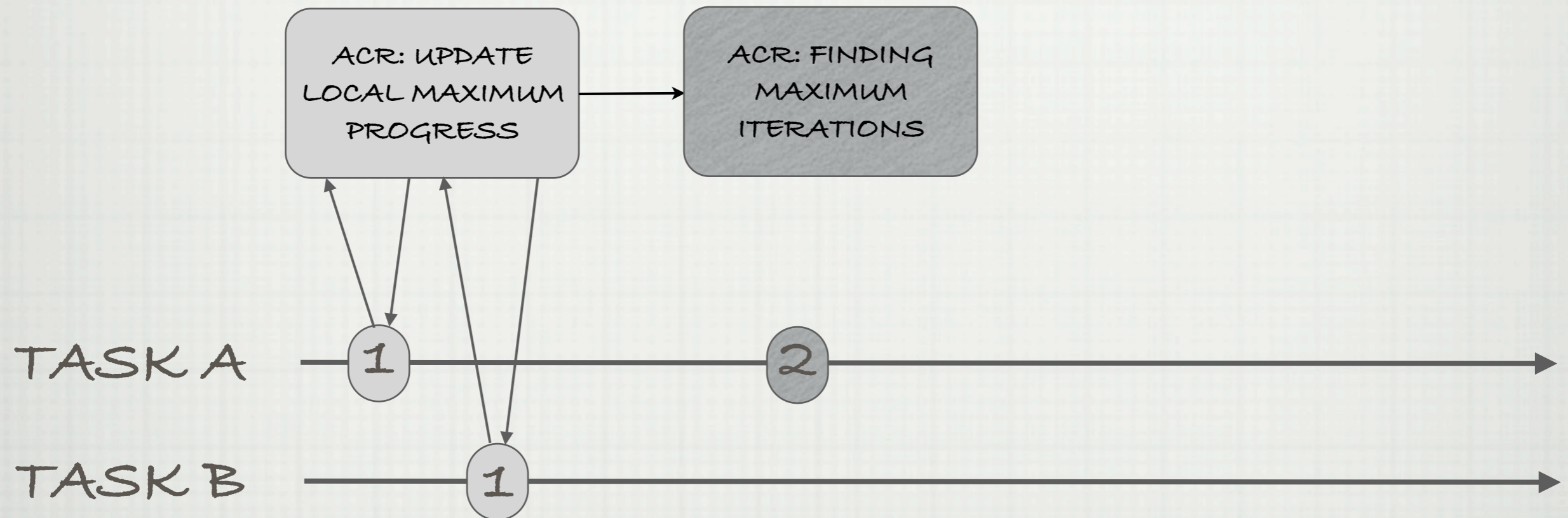
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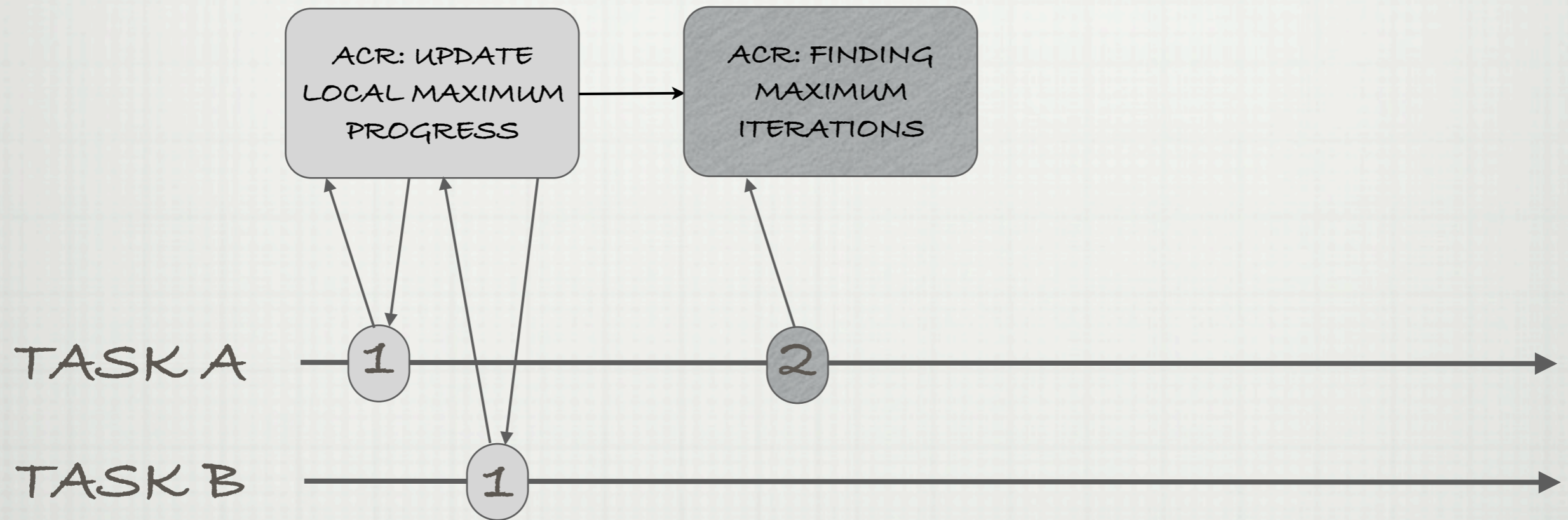
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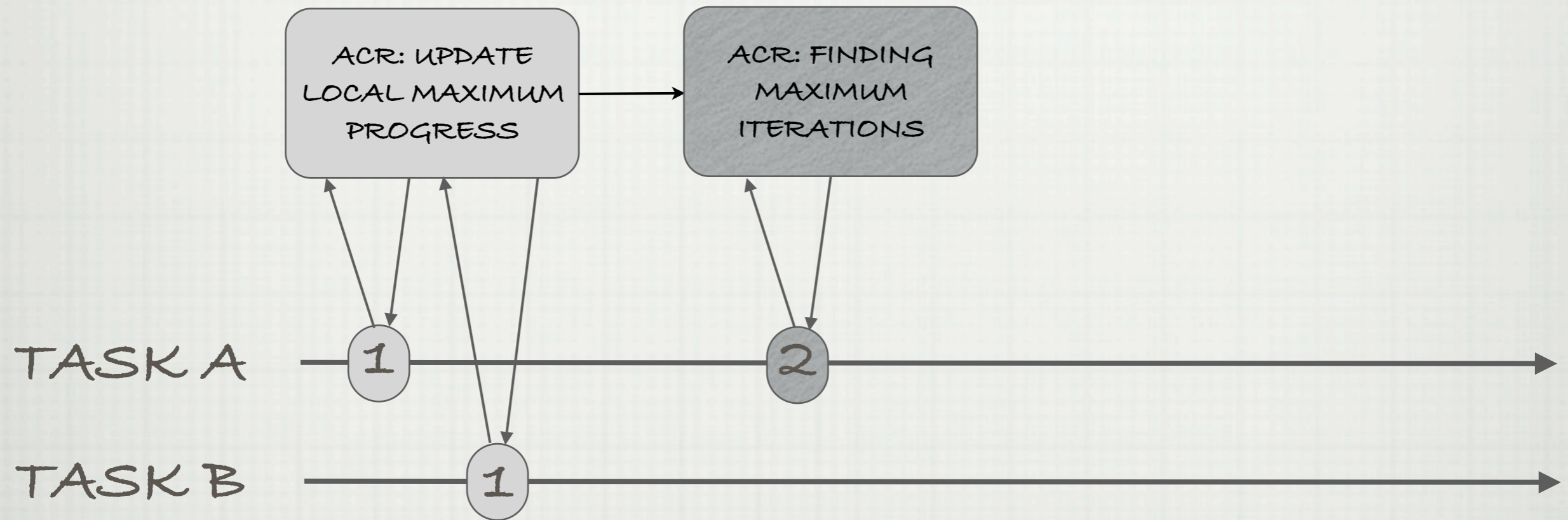
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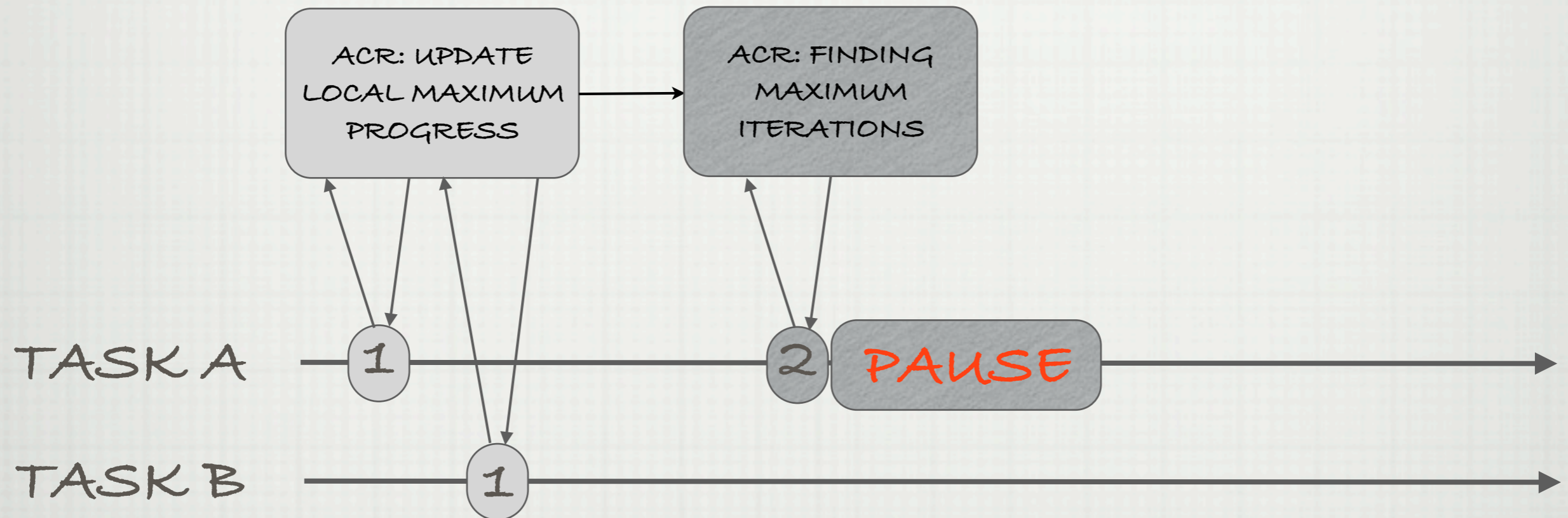
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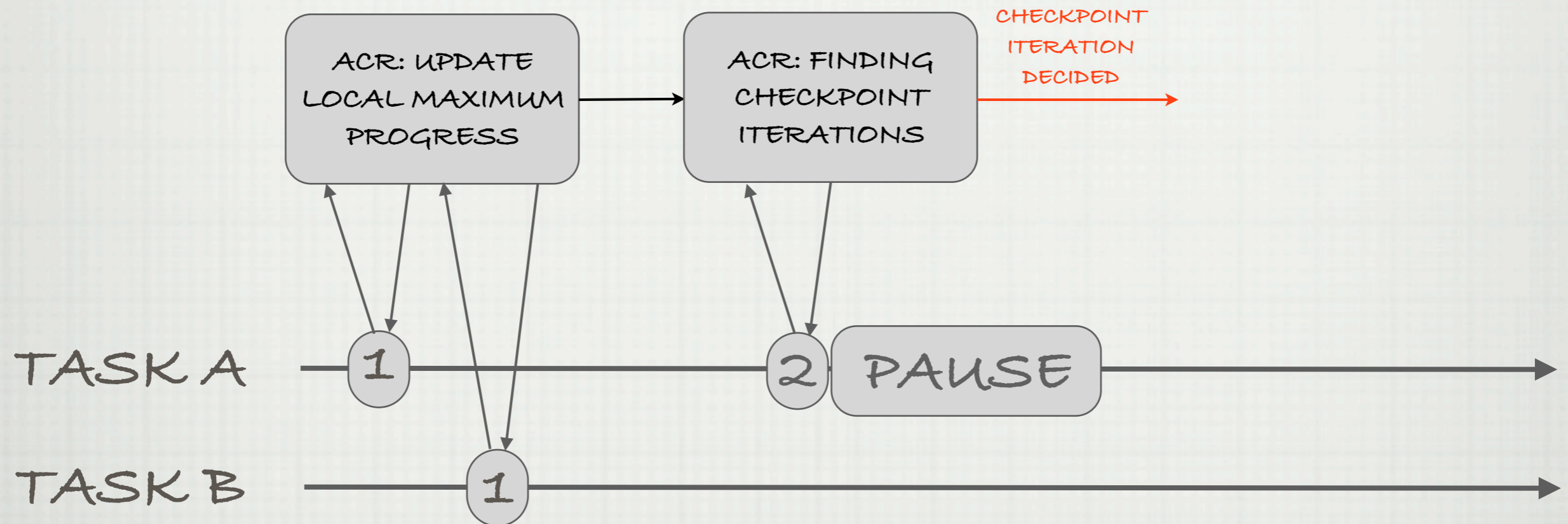
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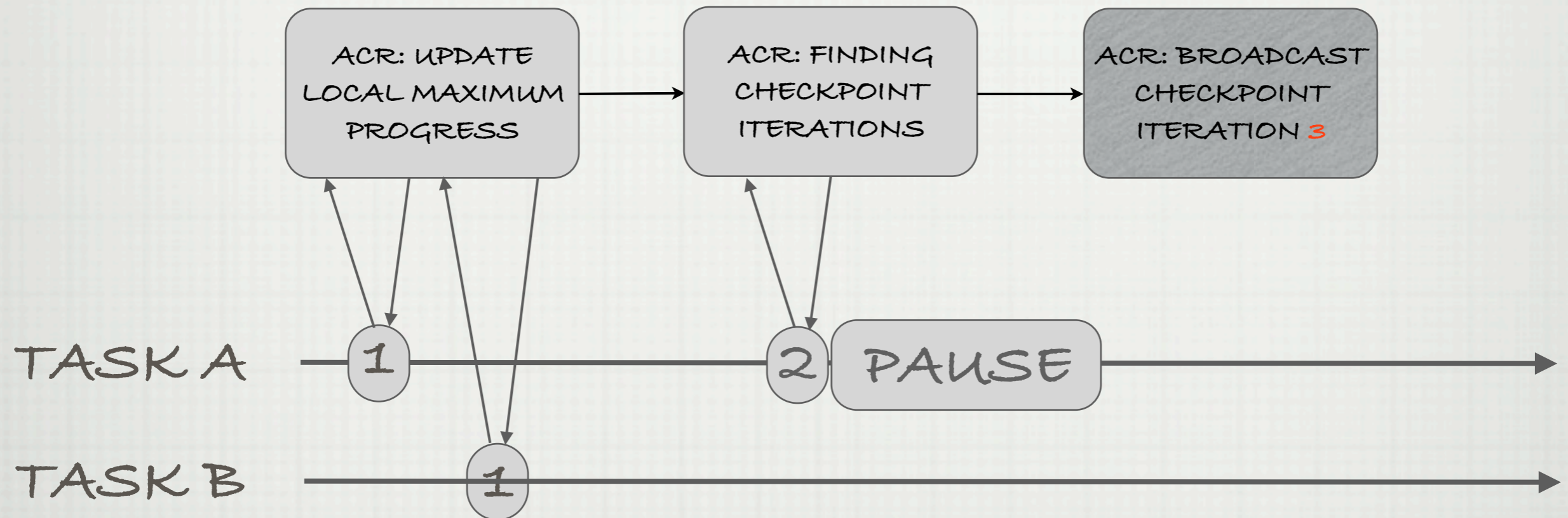
AUTOMATIC CHECKPOINT DECISION



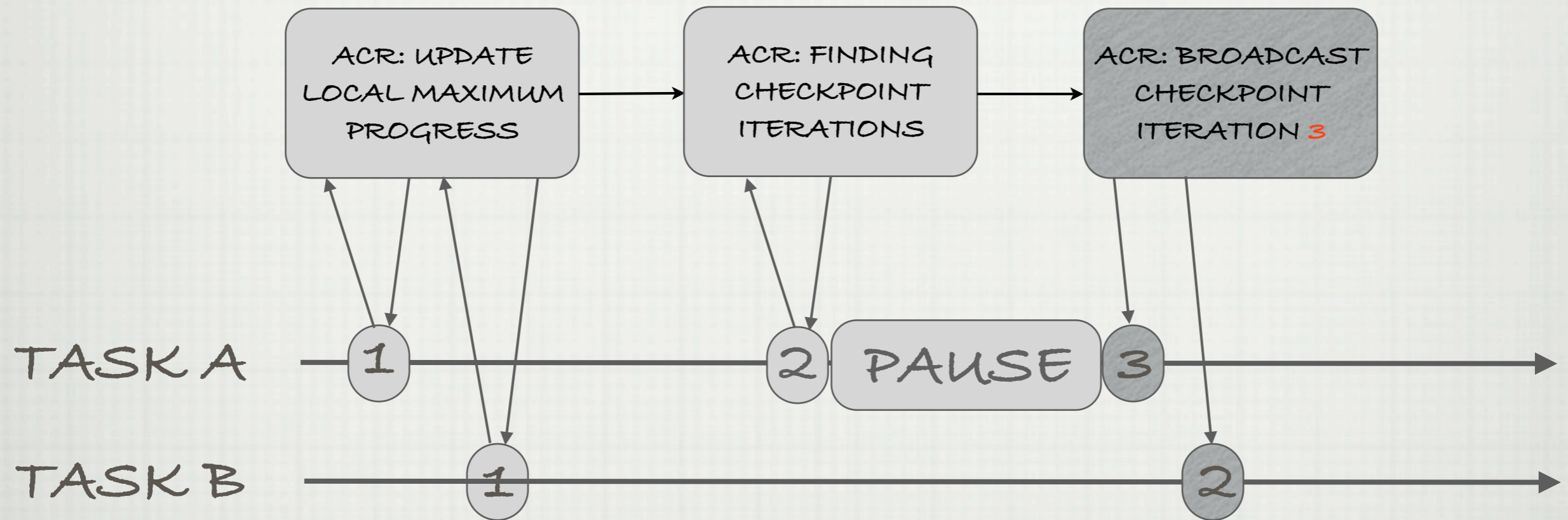
AUTOMATIC CHECKPOINT DECISION



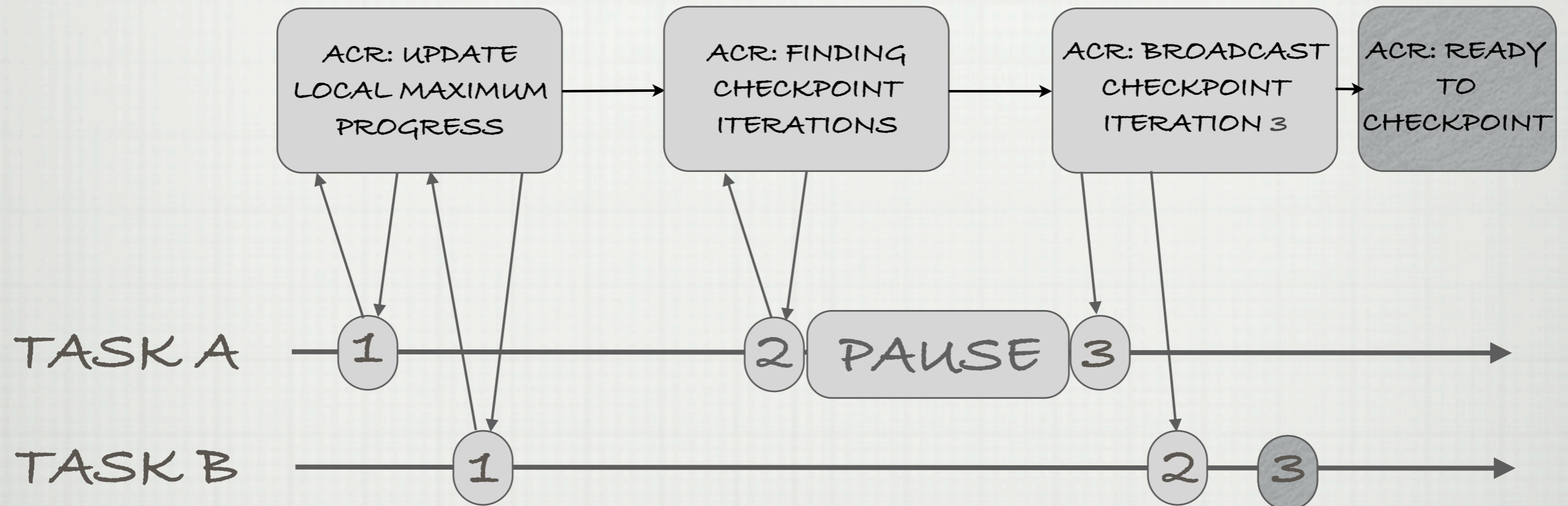
AUTOMATIC CHECKPOINT DECISION



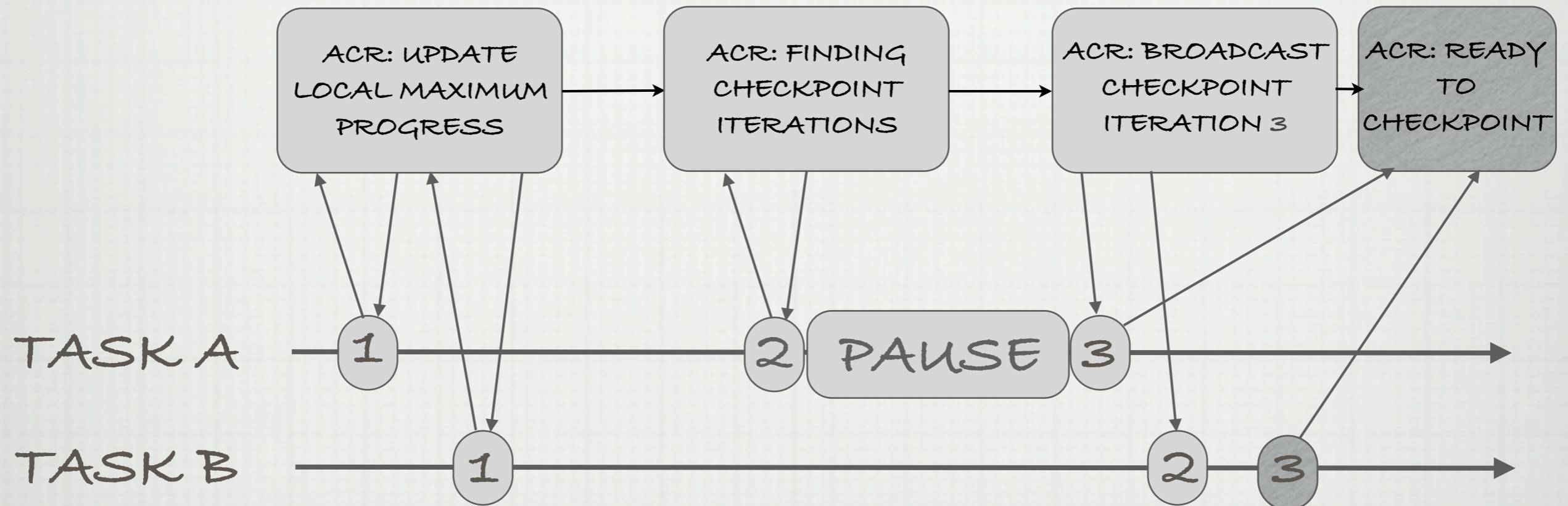
AUTOMATIC CHECKPOINT DECISION



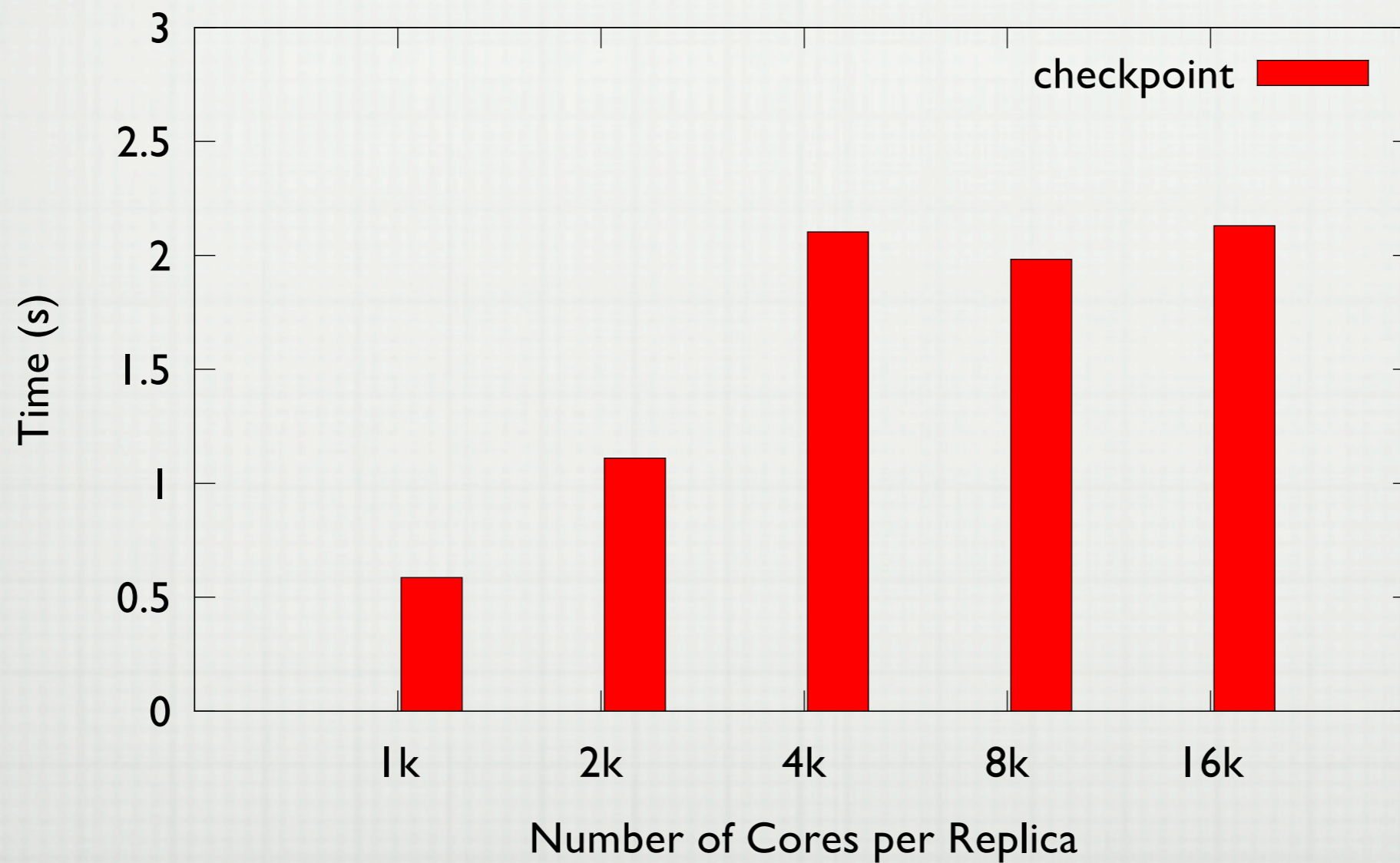
AUTOMATIC CHECKPOINT DECISION



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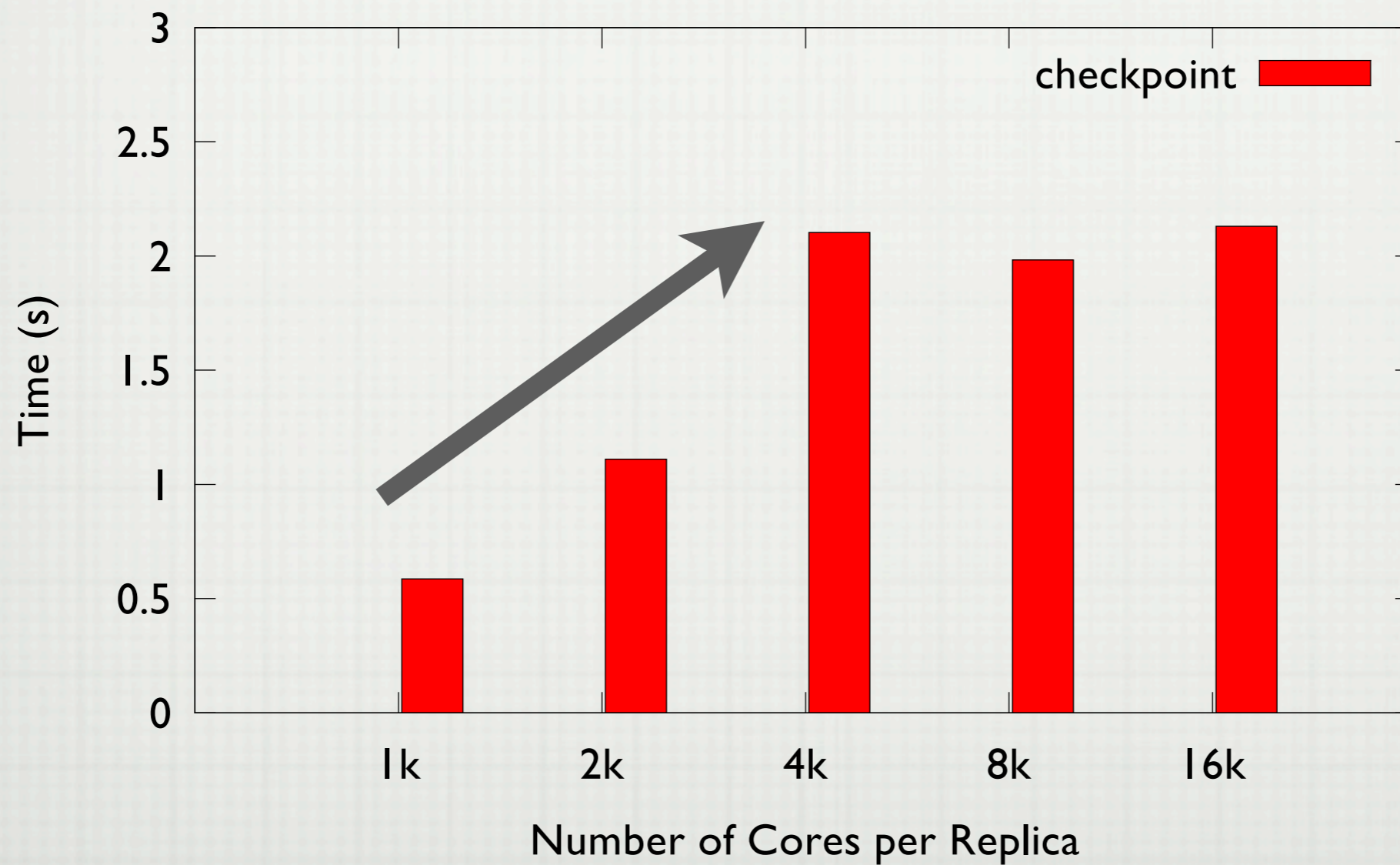


BASE PERFORMANCE



JACOBI3D BGP

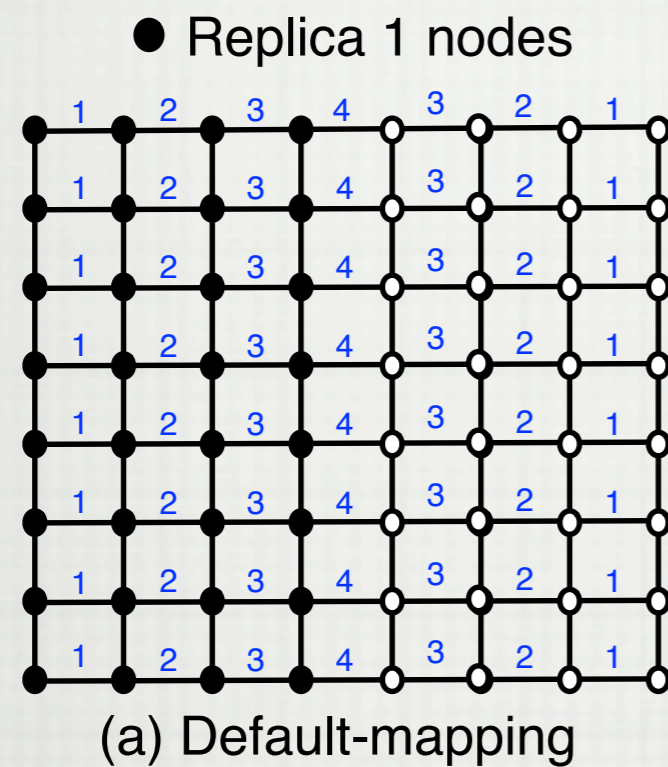
BASE PERFORMANCE



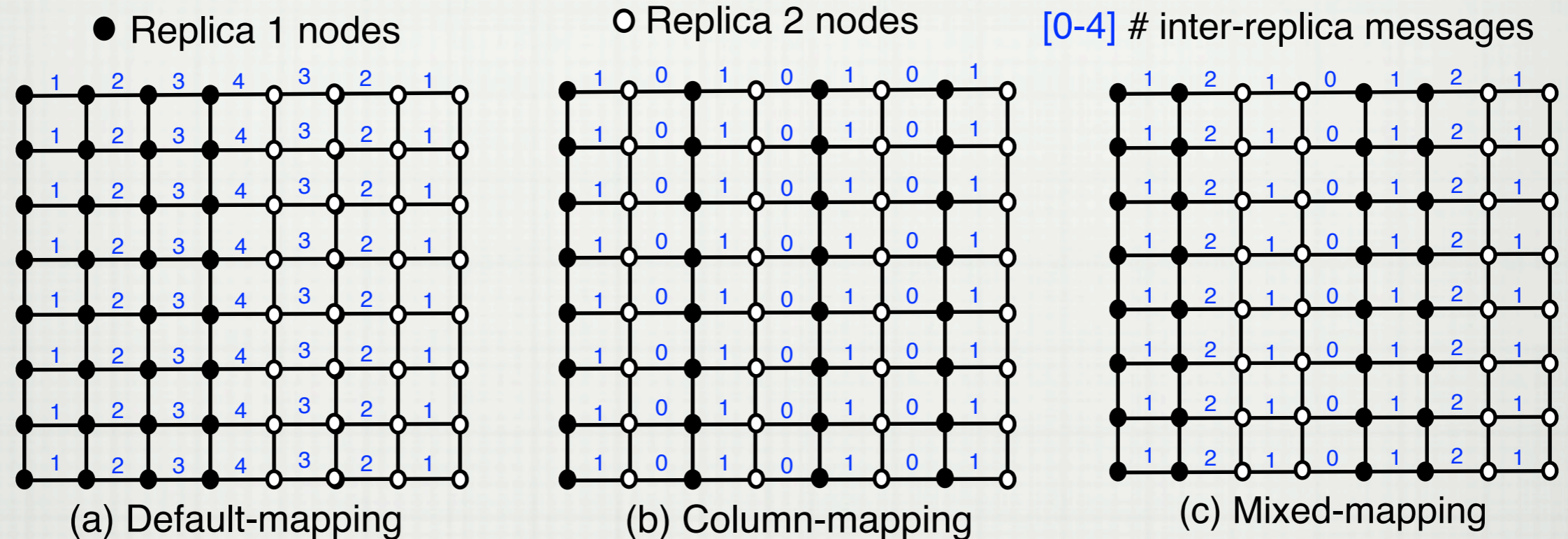
JACOBI3D BGP

OPTIMIZATION: TOPOLOGY AWARE MAPPING

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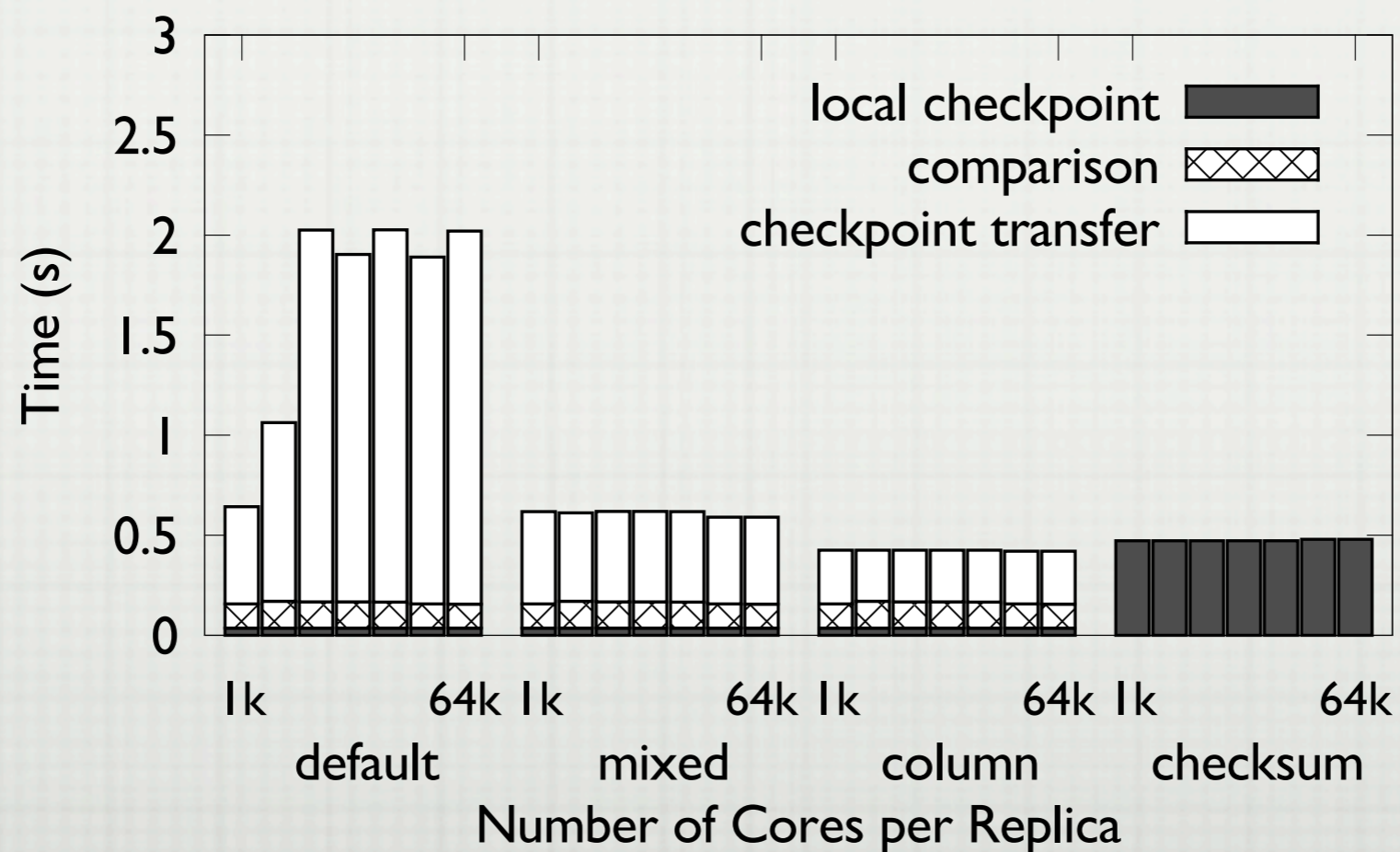
OPTIMIZATION: TOPOLOGY AWARE MAPPING



- 1) Reduce the inter-replica communication distance.
- 2) Trade-off between inter and intra replica communication.

OPTIMIZATION: CHECKSUM

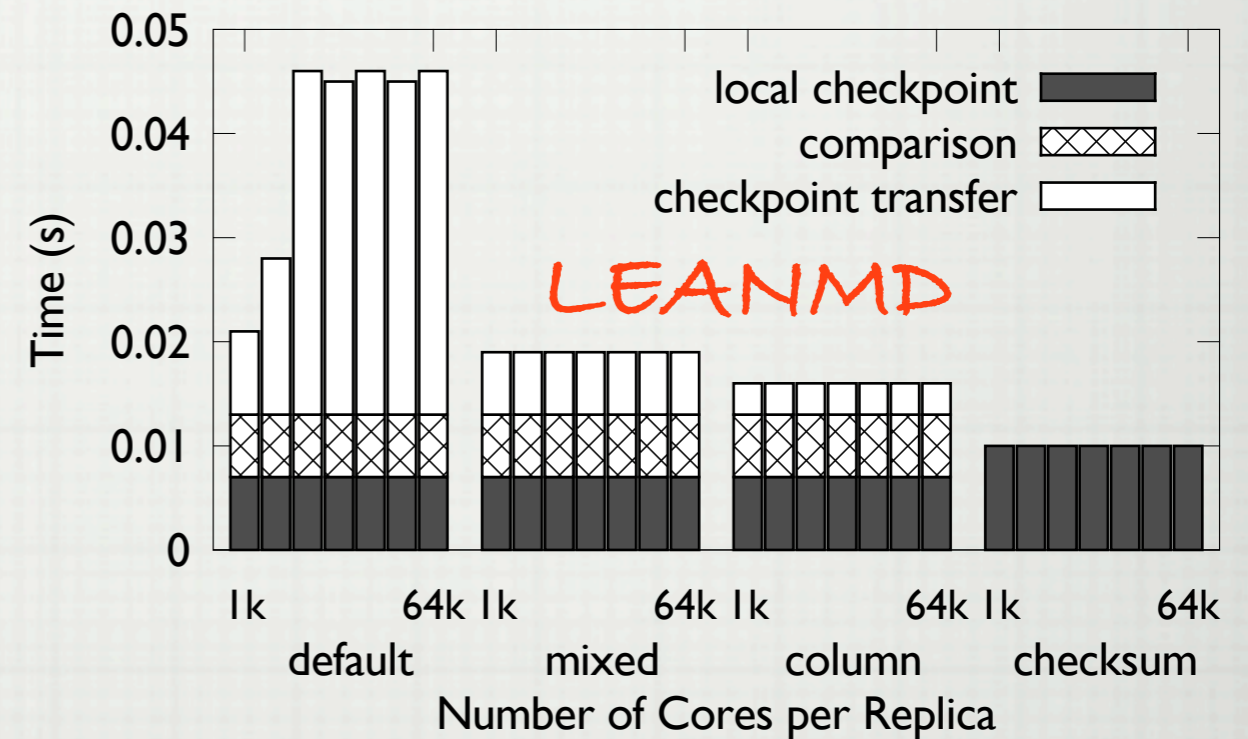
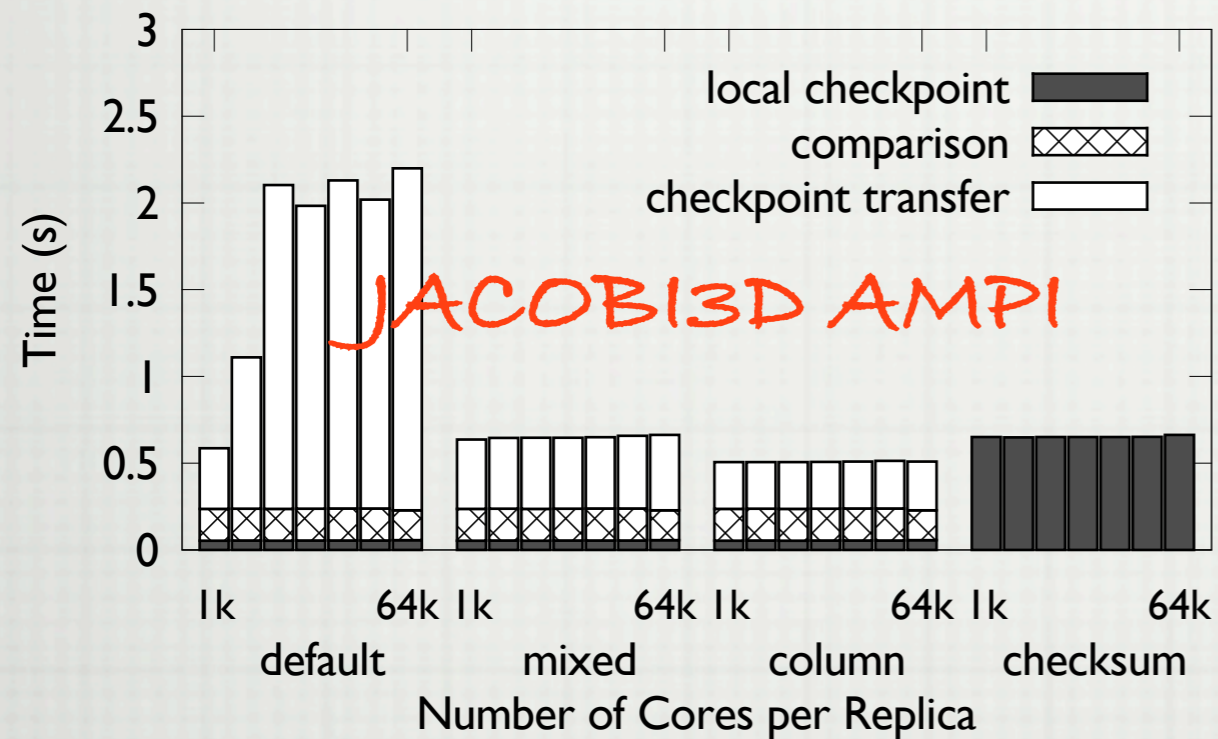
- TRANSFER THE CHECKSUM OF **1 INTEGER** INSTEAD OF THE WHOLE CHECKPOINTS
- FLOATING POINT ROUND-OFF ERROR



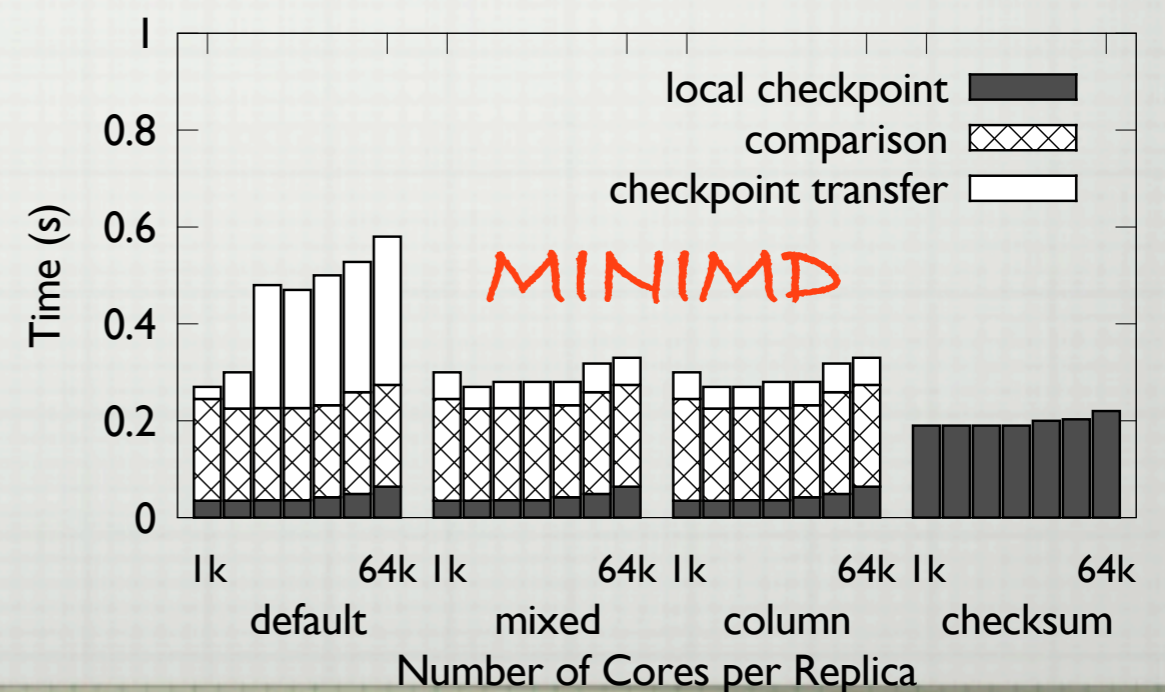
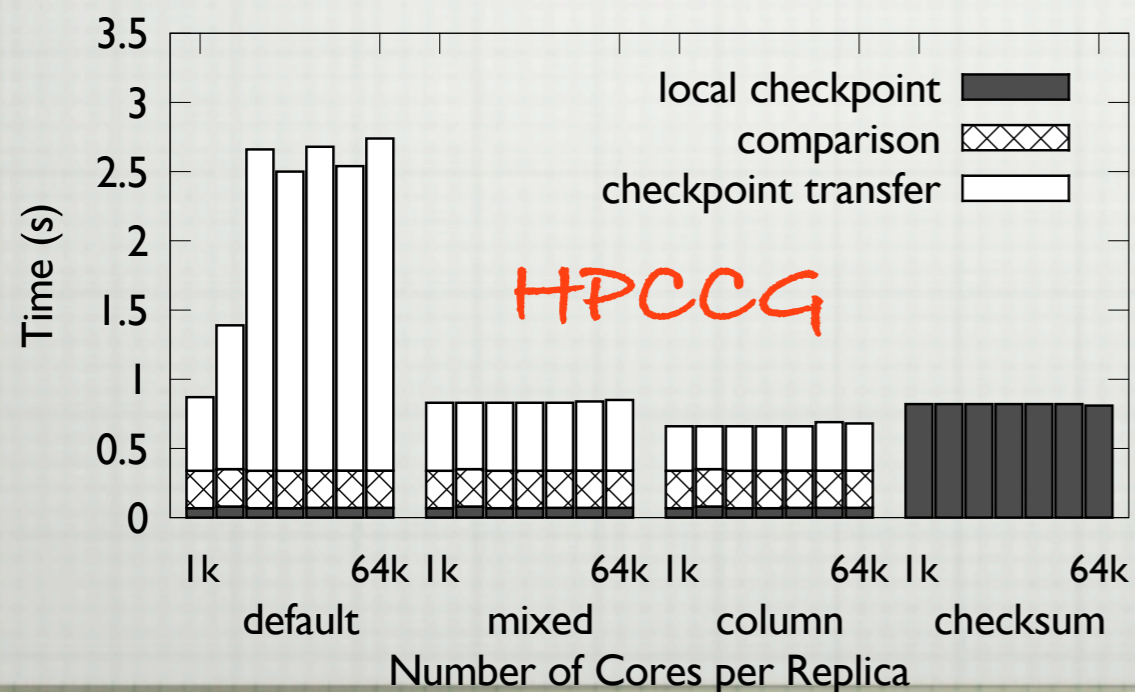
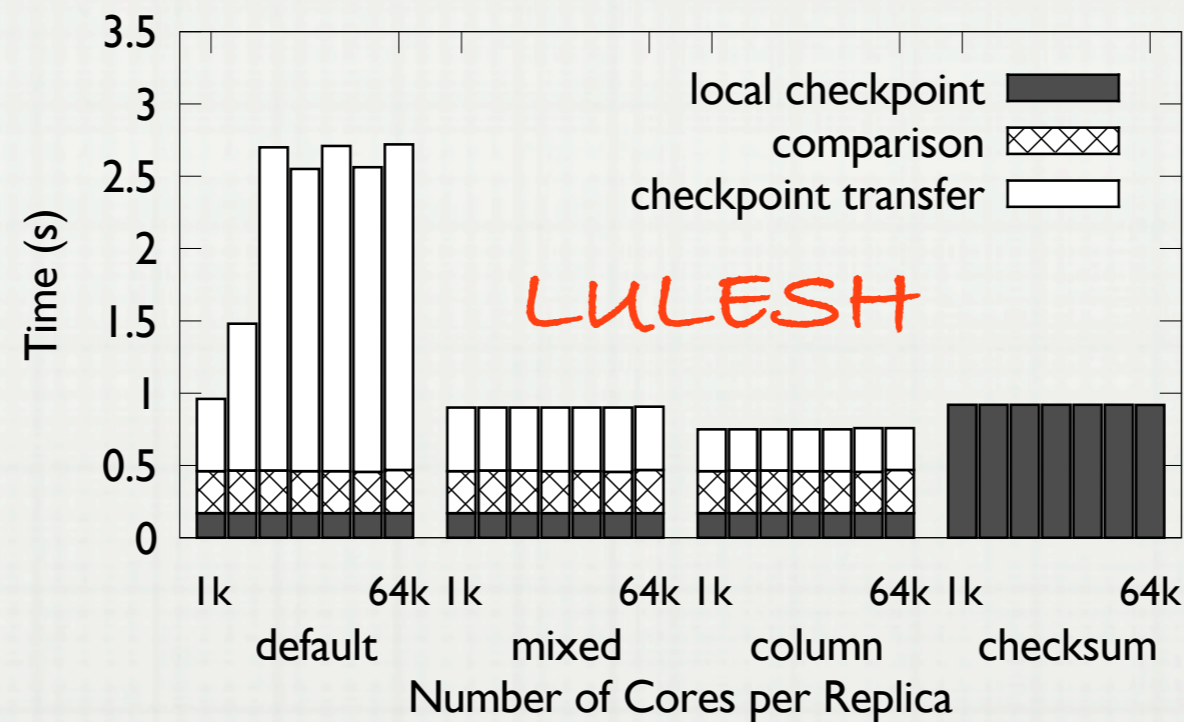
EXPERIMENTAL RESULTS: MINI-APPLICATIONS

Benchmark	Description	Configuration per core	Memory Pressure
Jacobi3D	7-point stencil	64*64*128	High
HPCCG	Unstructured implicit finite element method	40*40*40	High
LULESH	Unstructured explicit mesh	32*32*64	High
LeanMD	Short-range non-bonded force calculation in NAMD	4000 atoms	Low
miniMD	Mimic the performance in LAMMPS	1000 atoms	Low

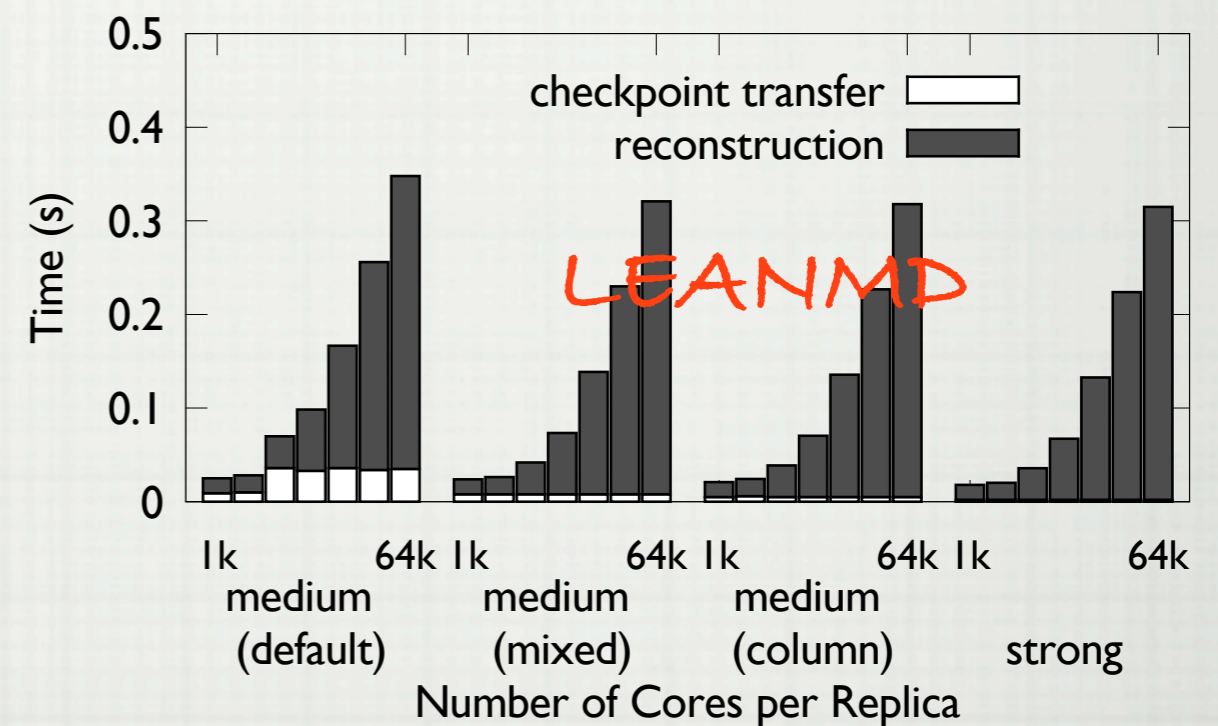
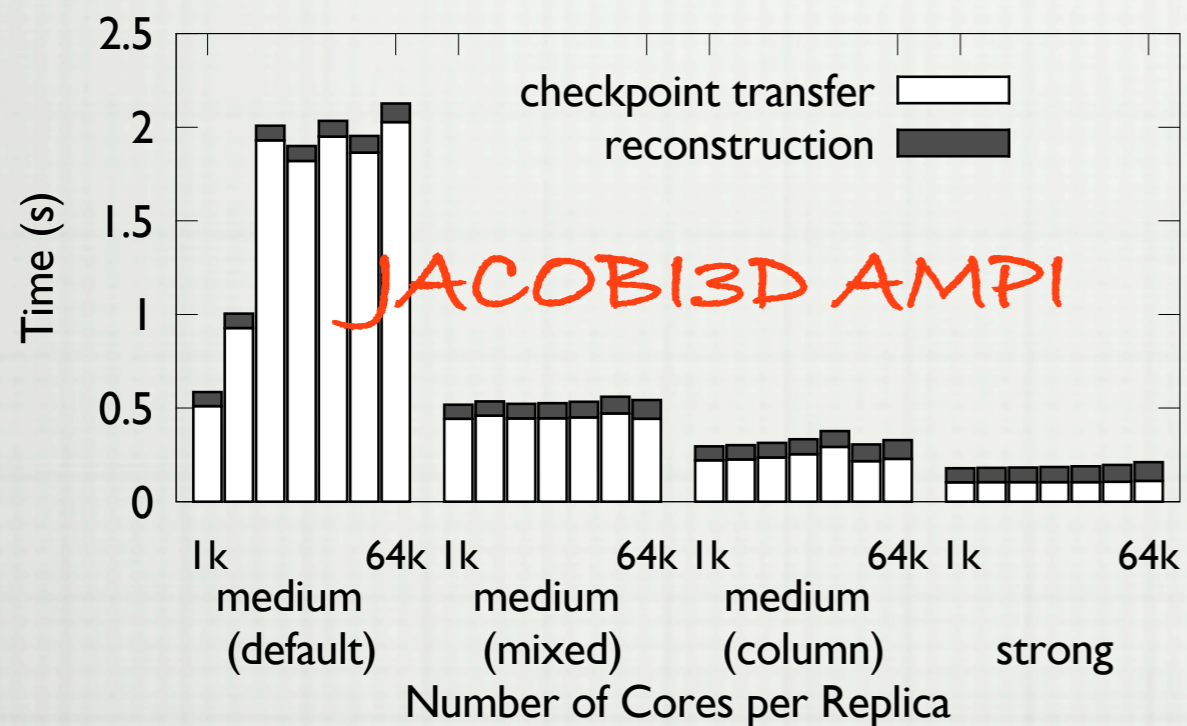
EXPERIMENTAL RESULTS: CHECKPOINT



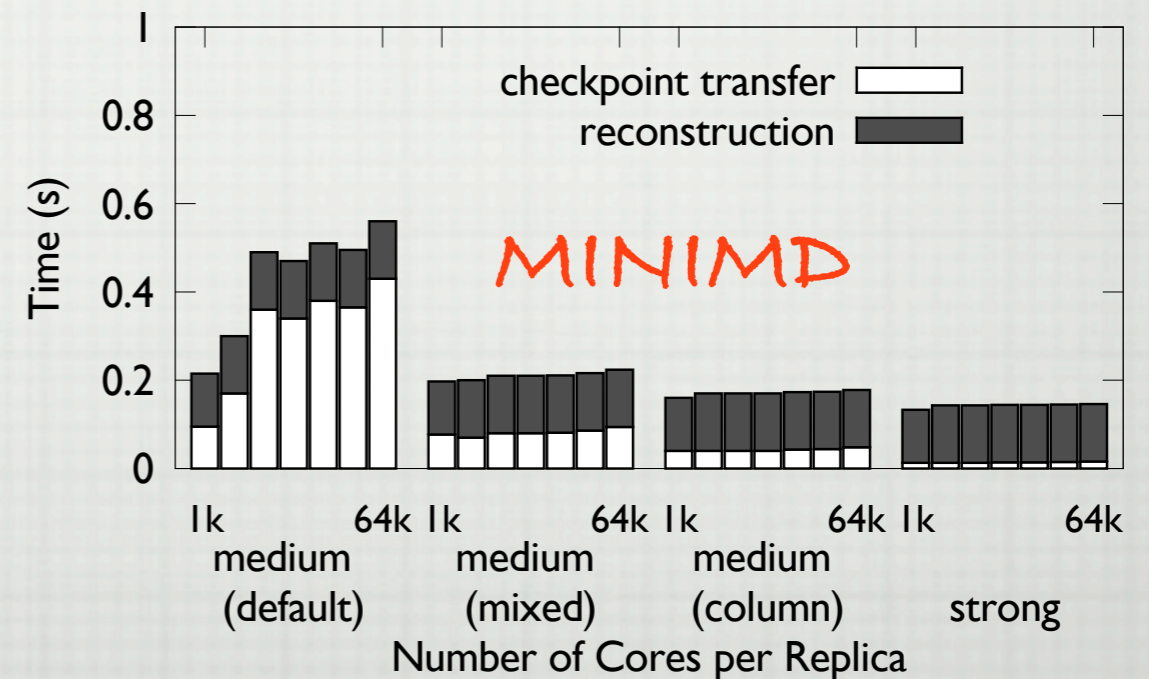
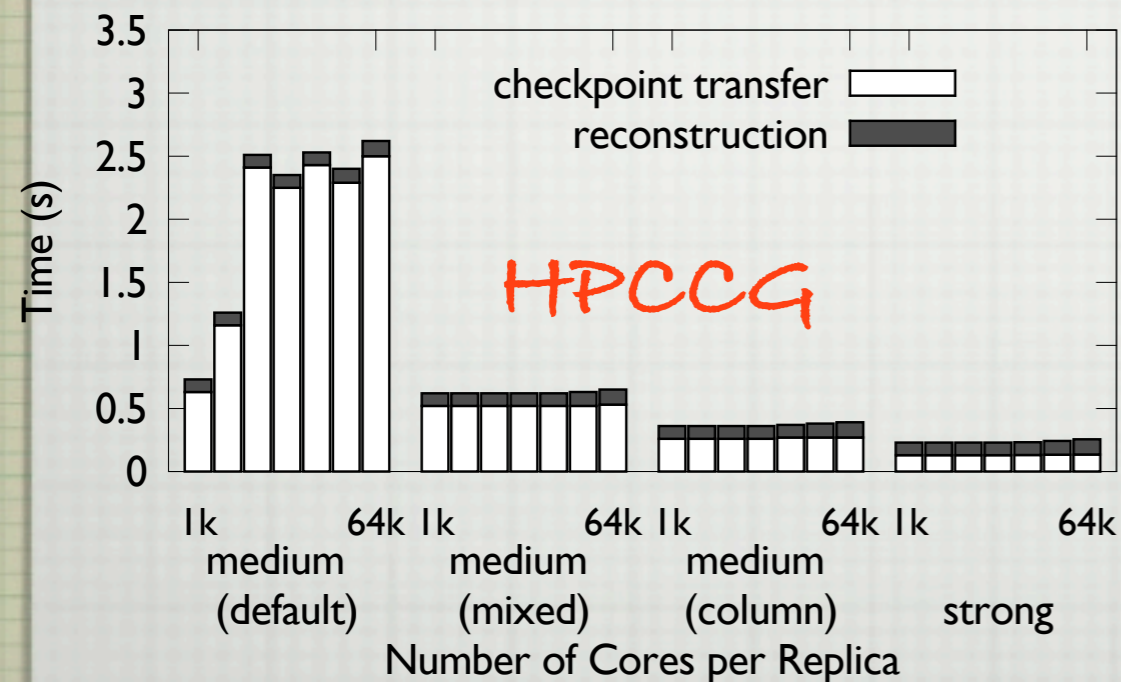
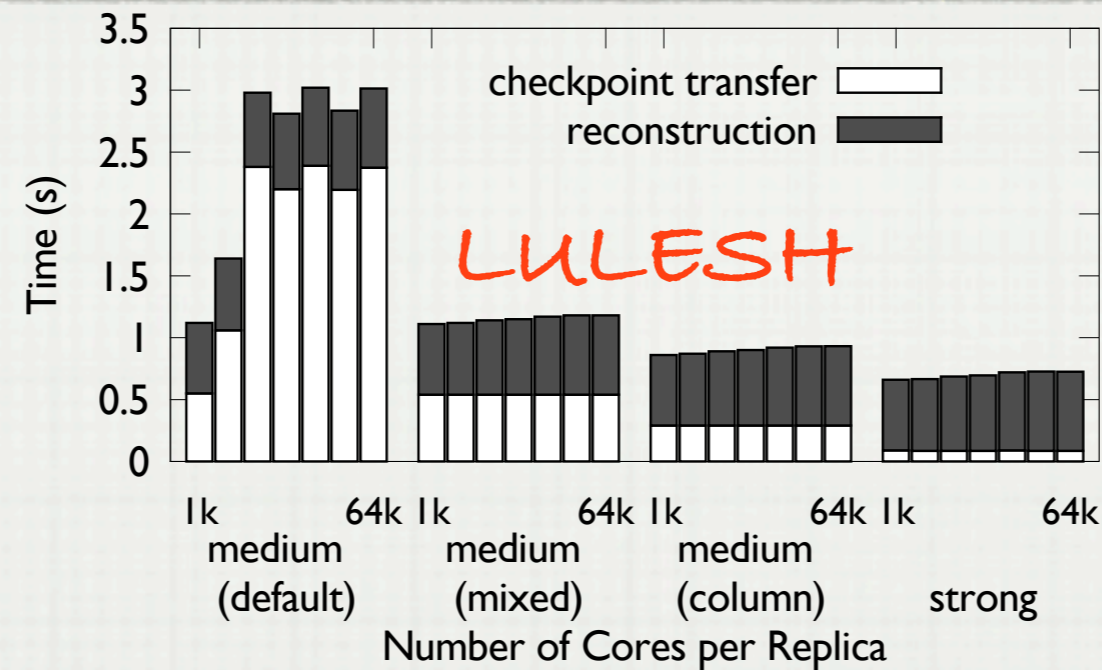
EXPERIMENTAL RESULTS: CHECKPOINT



EXPERIMENTAL RESULTS: RESTART

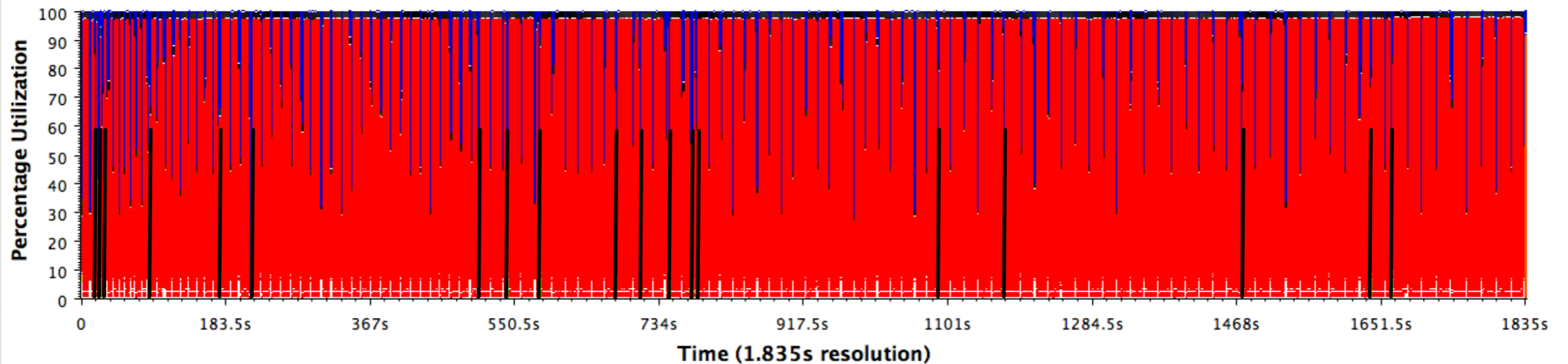


EXPERIMENTAL RESULTS: RESTART



ADAPTING TO FAILURES

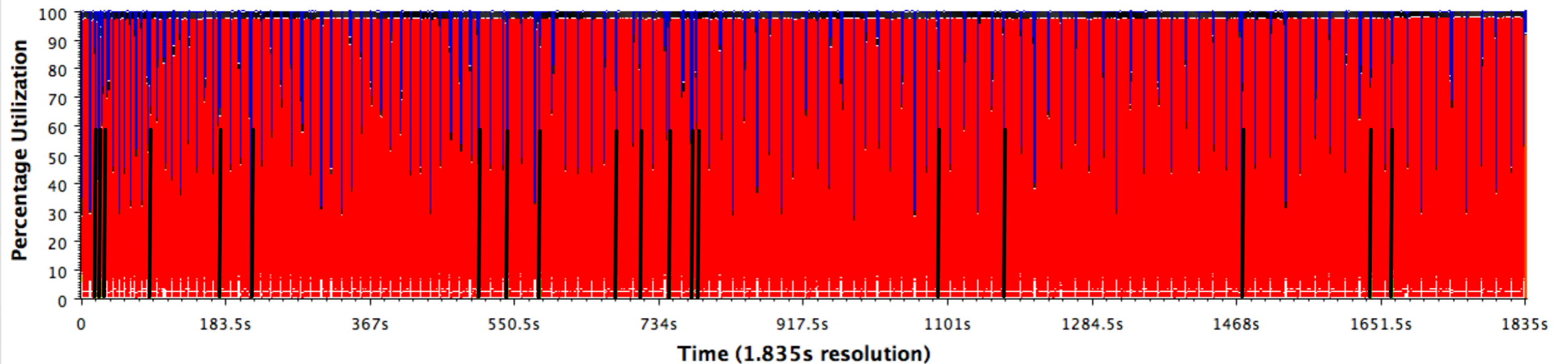
Time Profile



- Failures are injected according to Weibull process: shape parameter 0.6
- Changing Checkpoint period

ADAPTING TO FAILURES

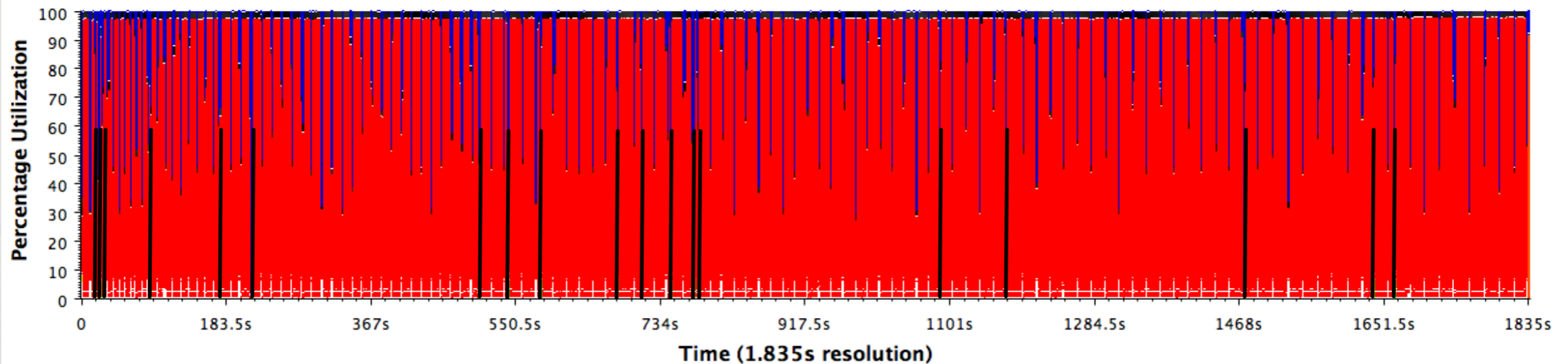
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ADAPTING TO FAILURES

Time Profile



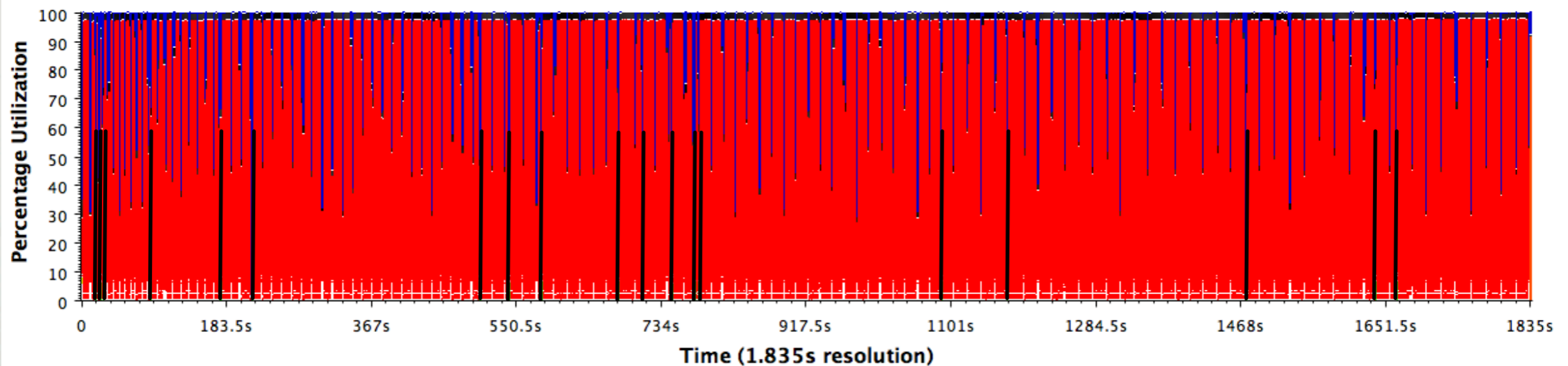
6S

- Failures are injected according to Weibull process: shape parameter 0.6
- Changing Checkpoint period

17S

ADAPTING TO FAILURES

Time Profile



6S

- Failures are injected according to Weibull process: shape parameter 0.6
- Changing Checkpoint period

17S

- Real failures injected: node becomes unresponsive
- Automatic restart: with the support of spare nodes and thus no need to submit the job again

CONCLUSION

- ☐ Automatic checkpoint decision
 - ☐ Restart from hard errors
 - ☐ Adapting to different failure distributions
- ☐ Protection for both hard and soft errors
- ☐ Good scalability

THANKS!

☐ QUESTIONS?