

# Hydra: Generation and Tuning of parallel solutions for linear algebra equations

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The logo for Inria, featuring the word 'Inria' in a red, cursive script font. Below it, the tagline 'INVENTEURS DU MONDE NUMÉRIQUE' is written in a smaller, red, sans-serif font. The logo is set against a white, curved background that resembles a banner or a sign.

*Inria*  
INVENTEURS DU MONDE NUMÉRIQUE

# Collaborators

- Thesis Advisors
  - Denis Barthou (Labri/INRIA Bordeaux)
  - David Padua (University of Illinois at UC)
- Future collaboration
  - starPU team, INRIA Bordeaux



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Jointlab INRIA-UIUC



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Objectives and Contributions

# INTRODUCTION



# Objectives

- Compile linear algebra equations
  - Compute  $X$  for  $L * X - X * U = C$  [CTSY]
  - Compute  $L$  and  $U$  for  $L * U = A$  [LU]
- Generate efficient task parallel code
  - Identify tasks
  - Generate task dependence graph



# Motivation

- Focus is on linear algebra
  - Start from high level description
  - No code or algorithm
- Derivation through blocking of operands
  - Data centric approach
- Derivation for parallelism
  - Output is a parallel task graph



# Contributions

- A specification language
  - Express computation
  - Characterize operands (shapes)
  - Identify wanted result
- Derivation rules
  - Validity/applicability patterns
  - Operators symbolic execution rules
  - Dependence build engine



A detailed view of the generator

# SYSTEM DESCRIPTION



# Description Language - Operands

## %% Operands

X: Unknown Matrix

L: Lower Triangular Square Matrix

U: Upper Triangular Square Matrix

C: Square Matrix

## %% Equation

$L * X - X * U = C$

## %% Parameters

@name ctsy

- All operands
- (Type inference)



- Status
  - Known, Unknown
- Shape
  - Triangular, diagonal
- Type
  - Matrix, (vector, scalar)
- Modifiers (transpose)
- (Sizes)
- (Density)



# Description language - Equation

```
%% Operands
X: Unknown Matrix
L: Lower Triangular Square Matrix
U: Upper Triangular Square Matrix
C: Square Matrix

%% Equation
L*X-X*U=C

%% Parameters
@name ctsy
```

- Base for decomposition

- Simple equations
  - Assignments
    - $X = A*B$
- Solvers
  - LU
  - Triangular Sylvester
  - $L*X=B$
  - Cholesky



# Description language - Parameters

```
%% Operands
X: Unknown Matrix
L: Lower Triangular Square Matrix
U: Upper Triangular Square Matrix
C: Square Matrix

%% Equation
L*X-X*U=C

%% Parameters
@name ctsy
```

- Drive code generation
- Set of parameters
  - Name
  - Codelet
  - Order of operands
  - Data type
- For customization
  - Default values used



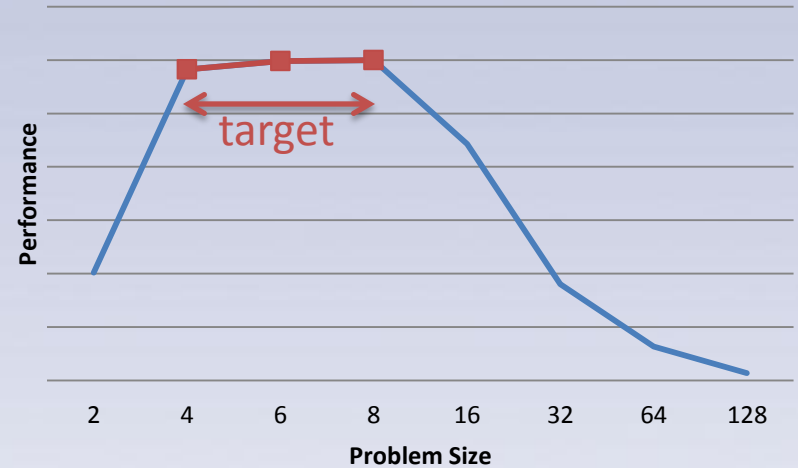
# Kernel Declaration

- Generate a full solution
  - Cost of full recursion
  - Usually not a good idea
- Use existing kernels and libraries
  - Already optimized



# Kernel Performance

- Measure performance
  - Depend on size
- Guide exploration
  - Optimal nodes
  - Similar to ATLAS



# Starpu Codelet

## Codelet declaration

```
void __gemm(void *buffers[], void *cl_arg);  
struct starpu_codelet gemm_cl = {  
    .where = STARPU_CPU,  
    .cpu_funcs = {__gemm, NULL},  
    .nbuffers = 3,  
    .modes = {STARPU_R, STARPU_R,  
STARPU_RW}  
};
```

## Kernel code

```
void __gemm(void *buffers[], void *cl_arg) {  
    struct params *params = cl_arg;  
    int n = params->n;  
    double *a = (double *)  
        STARPU_MATRIX_GET_PTR(buffers[0]);  
    // ...  
    cblas_dgemm(CblasRowMajor,  
        CblasNoTrans, CblasNoTrans,  
        n, n, n,  
        1.0,  
        a, n, b, n,  
        1.0,  
        c, n);  
}
```

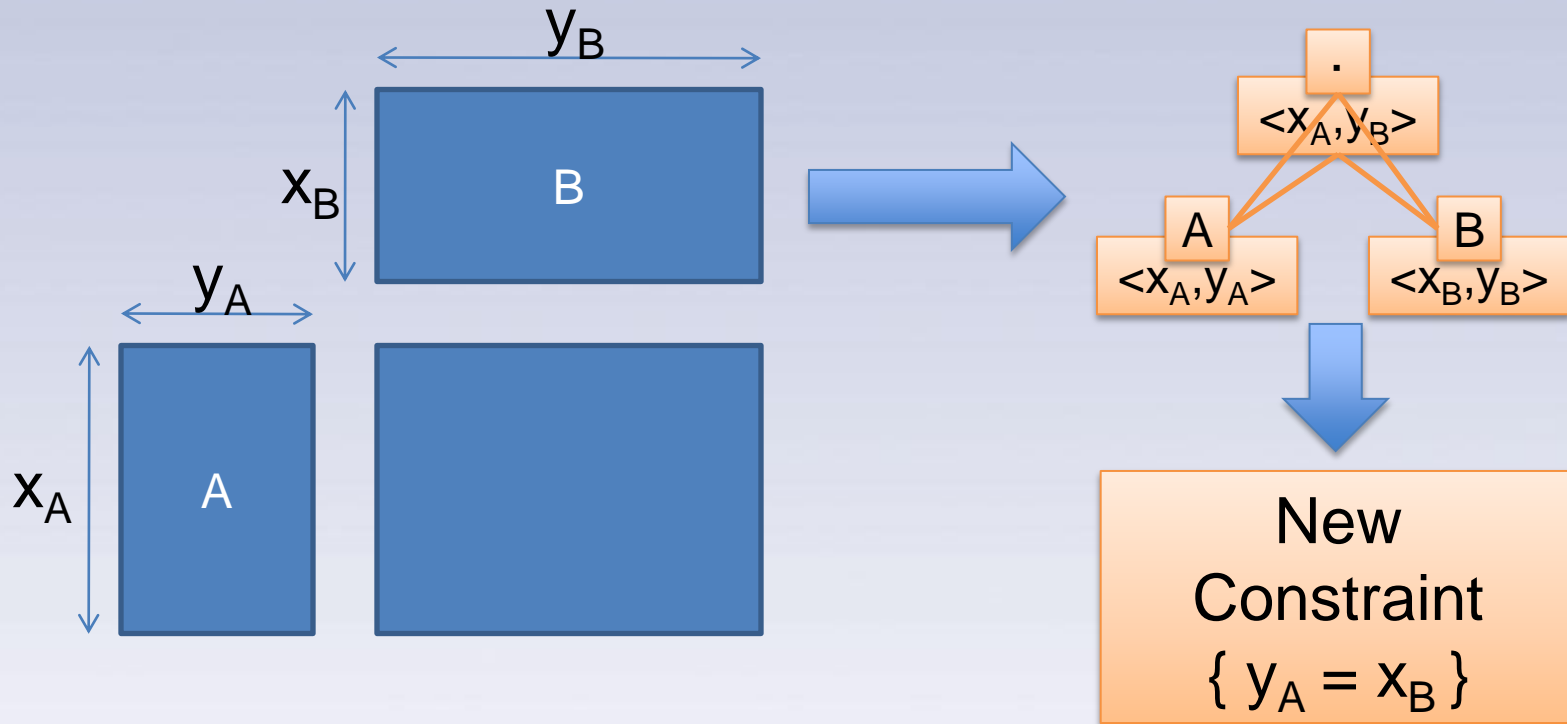


# Defining blocking space

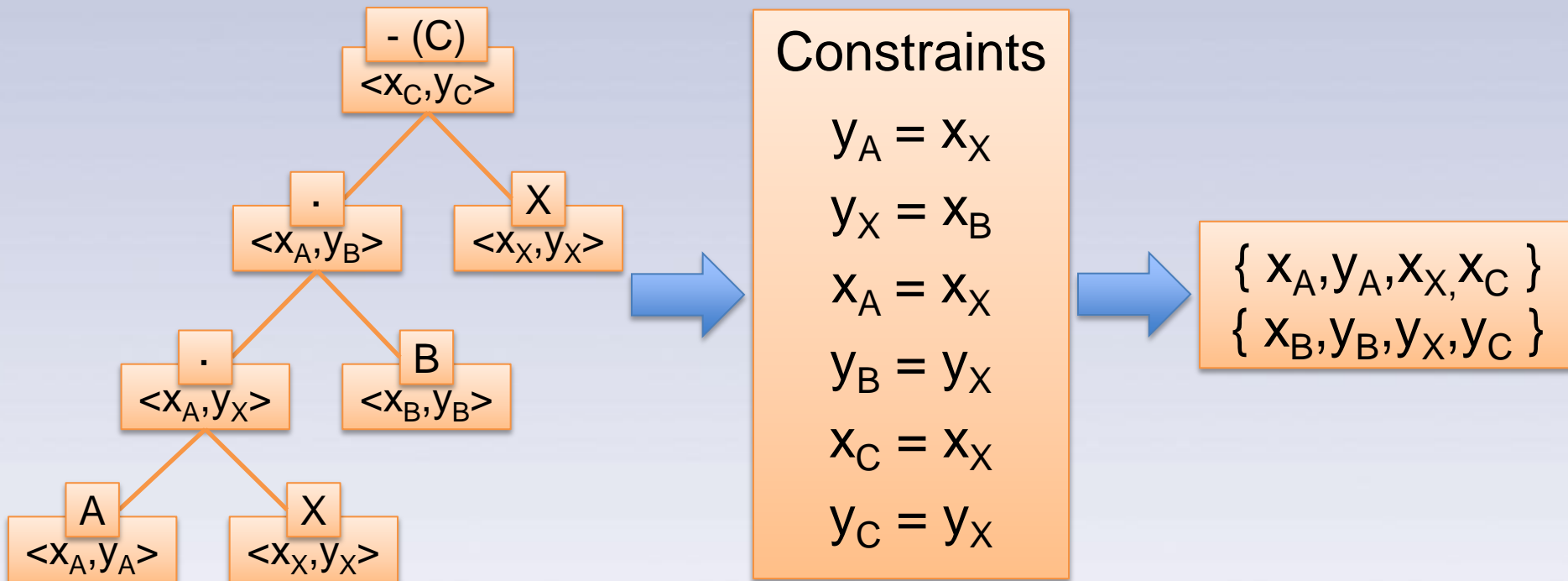
- Blocking defines the space of solutions
  - Must only generate valid solutions
- Look at the equation's operation tree
  - Each node gets a set of dimensions
  - Generate constraints depending on operation



# Validity of Blocking



# Valid Blockings - DTSY

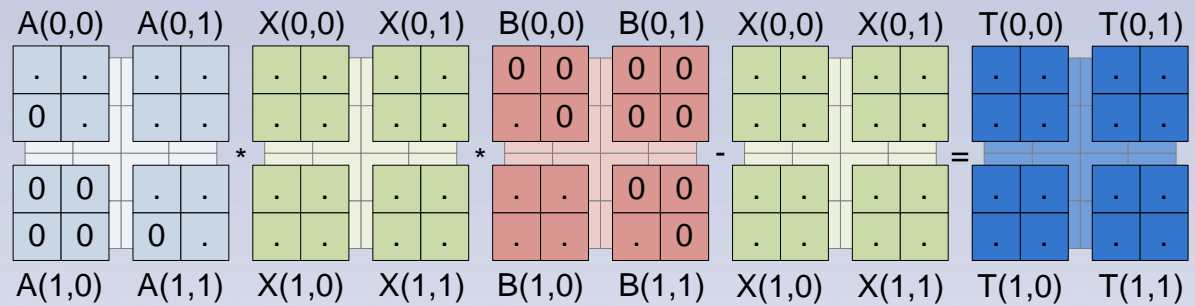




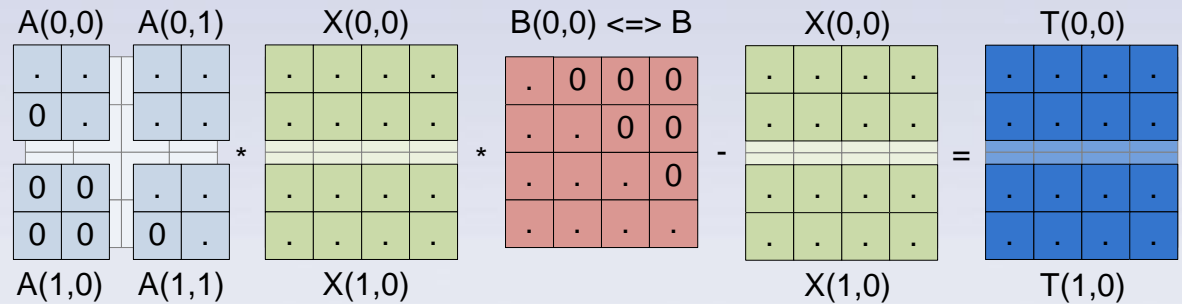
# Valid Blockings – DTSY (2)

$A * X * B - X = C$  | A lower triangular, B upper triangular

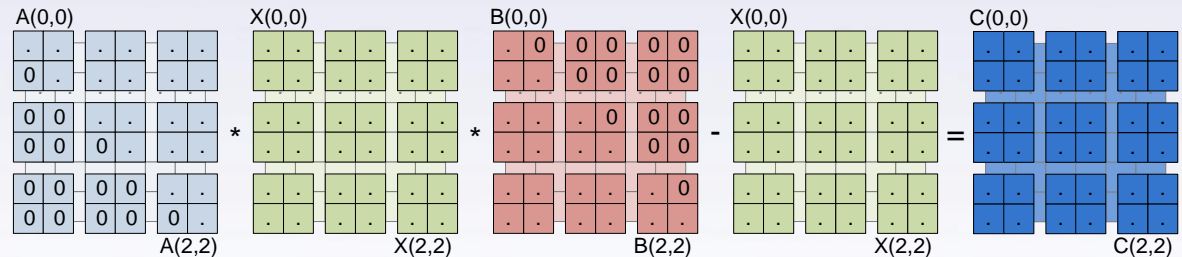
$x_A = y_A = x_X = 2$   
 $x_B = y_B = y_X = 2$



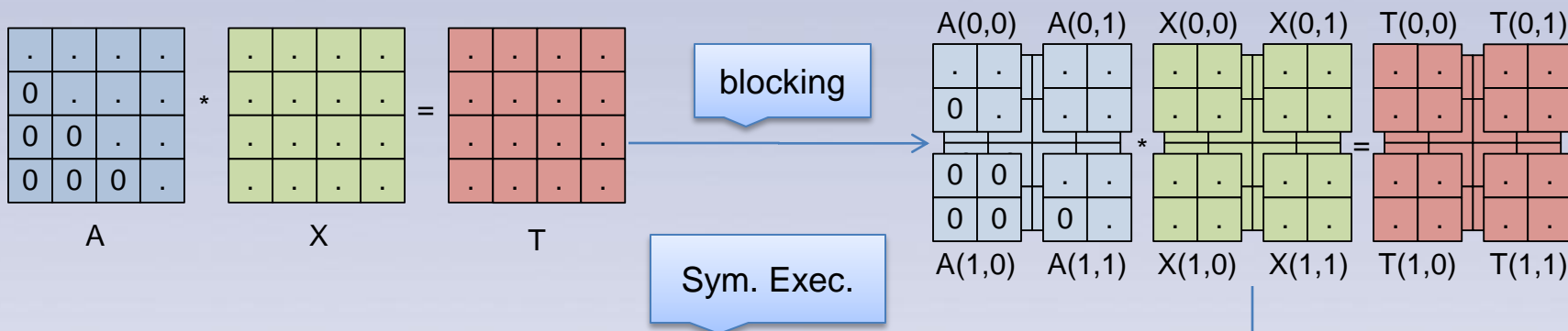
$x_A = y_A = x_X = 2$   
 $x_B = y_B = y_X = 1$



$x_A = y_A = x_X = 3$   
 $x_B = y_B = y_X = 3$



# Derivation example



$$\begin{aligned}
 T(0,0) &= A(0,0) * X(0,0) + A(0,1) * X(1,0) \\
 T(0,1) &= A(0,0) * X(0,1) + A(0,1) * X(1,1) \\
 T(1,0) &= \mathbf{A(1,0) * X(0,0)} + A(1,1) * X(1,0) \\
 T(1,1) &= \mathbf{A(1,0) * X(0,1)} + A(1,1) * X(1,1)
 \end{aligned}$$

Removal of 0-computation

$$\begin{aligned}
 T(0,0) &= A(0,0) * X(0,0) + A(0,1) * X(1,0) \\
 T(0,1) &= A(0,0) * X(0,1) + A(0,1) * X(1,1) \\
 T(1,0) &= \phantom{A(0,0) * X(0,0)} + A(1,1) * X(1,0) \\
 T(1,1) &= \phantom{A(0,0) * X(0,0)} + A(1,1) * X(1,1)
 \end{aligned}$$



# Operand characterization

- Blocks of  $X$  are outputs (unknown)
- $A(0,0)$  and  $A(1,1)$  are lower triangular

Equation	Input	Output
$T(1,1) = A(1,1) * X(1,1)$	$T(1,1) A(1,1)$	$X(1,1)$
$T(1,0) = A(1,1) * X(1,0)$	$T(1,0) A(1,1)$	$X(1,0)$
$T(0,1) = A(0,0) * X(0,1) + A(0,1) * X(1,1)$	$T(0,1) A(0,0) A(0,1)$	$X(0,1) X(1,1)$
$T(0,0) = A(0,0) * X(0,0) + A(0,1) * X(1,0)$	$T(0,0) A(0,0) A(0,1)$	$X(0,0) X(1,0)$



# Equation Signature

- Need to identify equations
- Identification through types and operators

$$- A * X = T : LT * UNK = MT$$

- Set of simplification rules

$$- UNK + MT * MT \Rightarrow UNK + MT$$



# Identify task

- $T(1,1) = A(1,1) * X(1,1)$ 
  - Signature :  $LT * UNK = MT$
- Instance of original problem
  - Solvable
- $X(1,1)$  can now be considered known



# Building dependence

- Find instances of  $X(1,1)$ 
  - Shift in input set
  - Add dependence edge

Equation	Input	Output
$T(0,1) = A(0,0) * X(0,1) + A(0,1) * X(1,1)$	$T(0,1)$ $A(0,0)$ $A(0,1)$ $X(1,1)$	$X(0,1)$

## New Dependence

$$\{ T(1,1) = A(1,1) * X(1,1) \rightarrow T(0,1) = A(0,0) * X(0,1) + A(0,1) * X(1,1) \}$$



# Signature Simplification

- $T(0,1) = A(0,0) * X(0,1) + A(0,1) * X(1,1)$ 
  1.  $MT = LT * UNK + MT * MT$
  2.  $MT = LT * UNK + MT$
  3.  $MT - MT = LT * UNK$
  4.  $MT = LT * UNK$
- Match to the original problem !



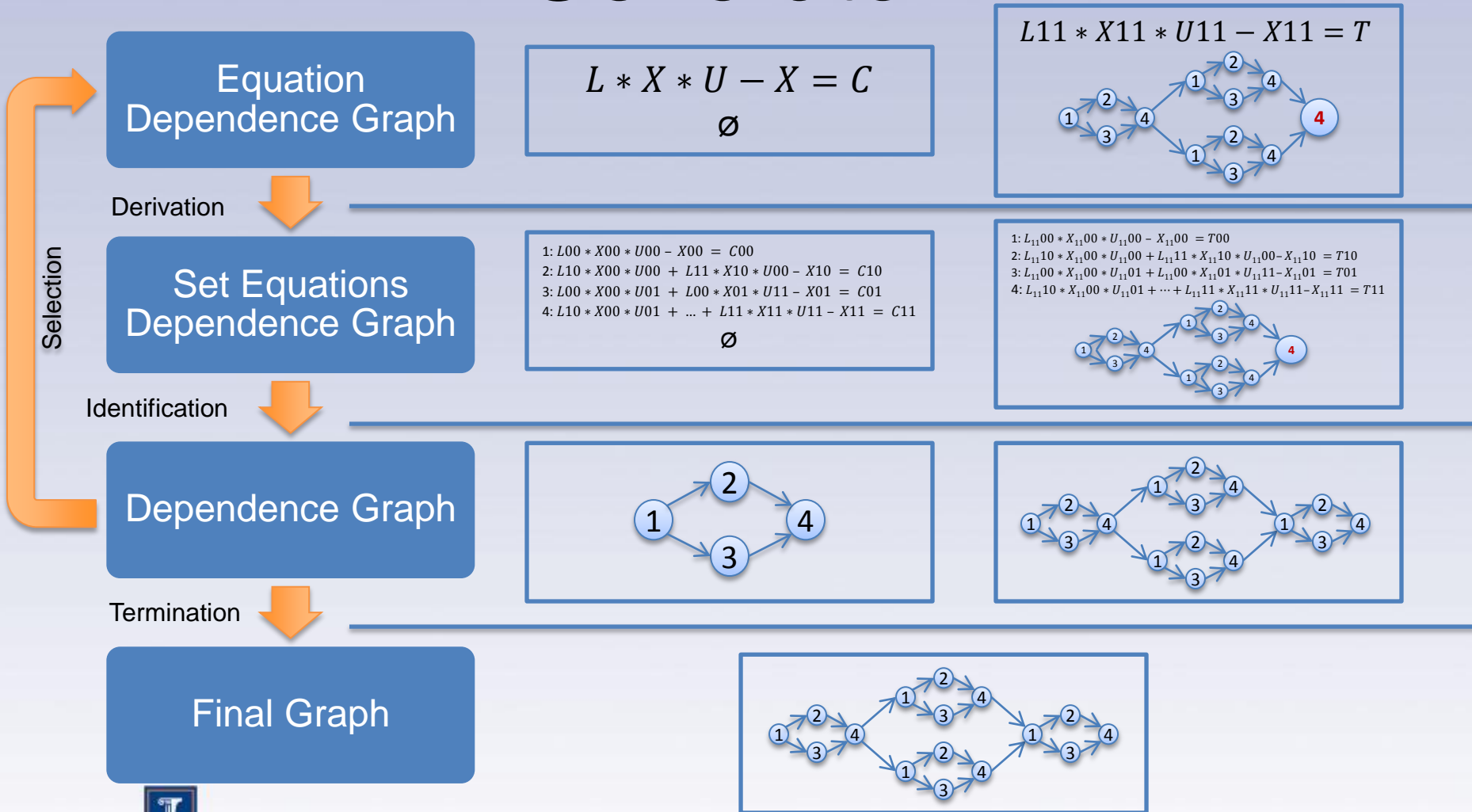
# Post identification expansion

Simplification step	Corresponding equation
$MT = LT * UNK + MT * MT$	$T(0,1) = A(0,0) * X(0,1) + A(0,1) * X(1,1)$
$MT = LT * UNK + MT$	$T1 = A(01) * X(1,1)$ $T(0,1) = A(0,0) * X(0,1) + T1$
$MT - MT = LT * UNK$	
$MT = LT * UNK$	<b><math>T1 = A(01) * X(1,1)</math></b> <b><math>T2 = T(0,1) - T1</math></b> <b><math>T2 = A(0,0) * X(0,1)</math></b>

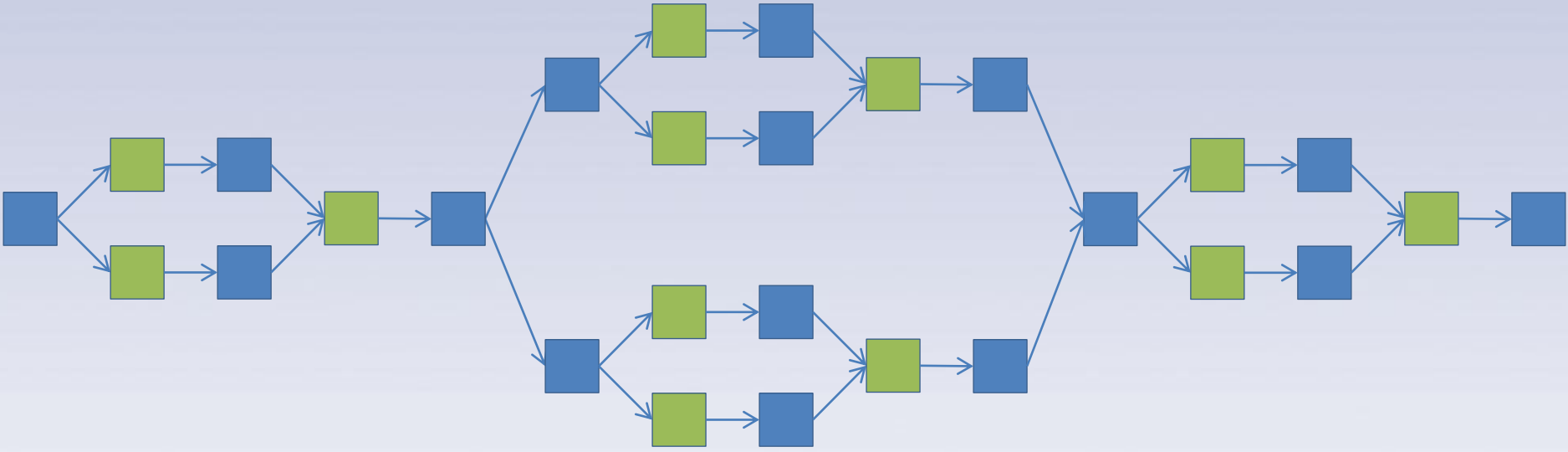




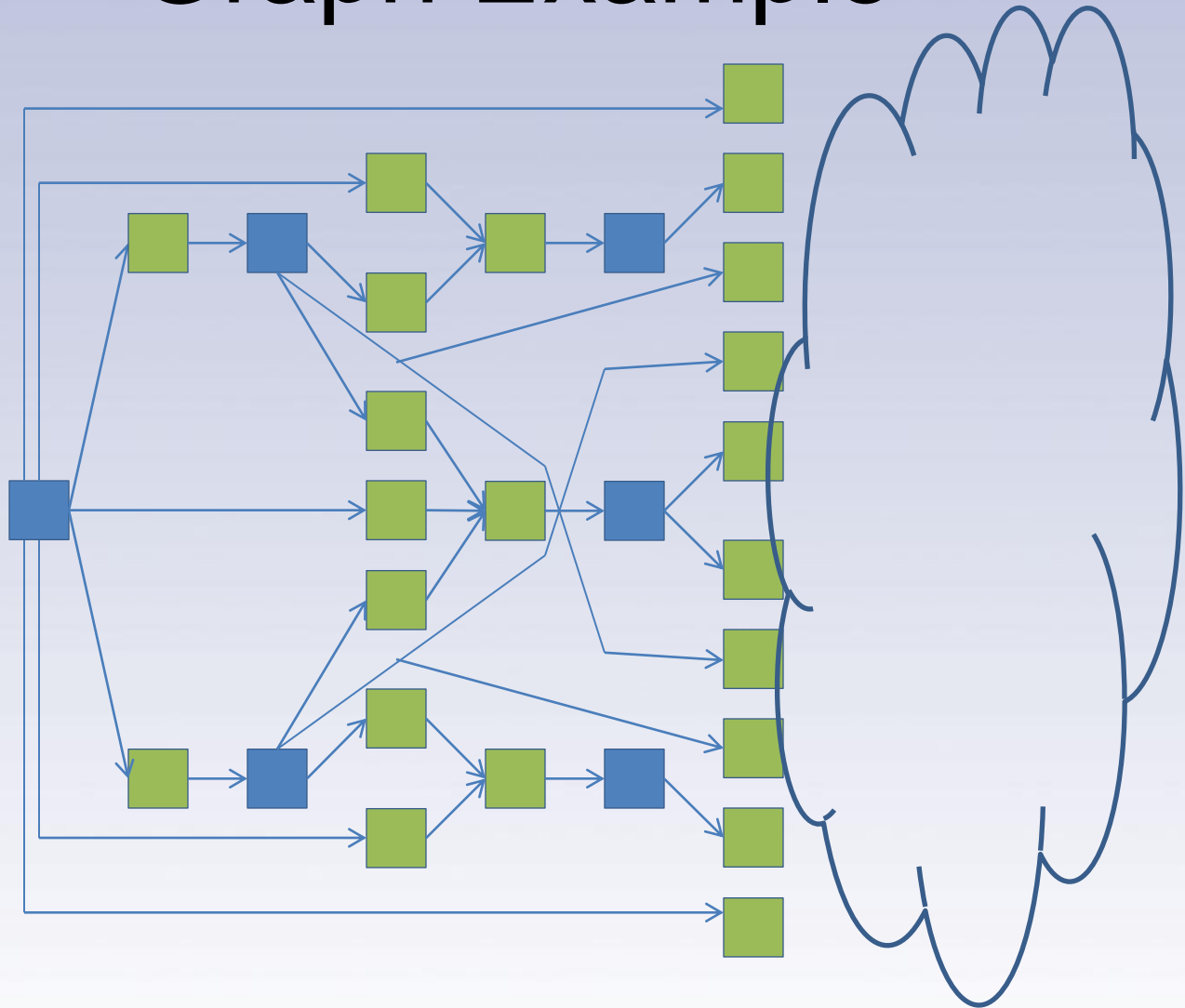
# Generator



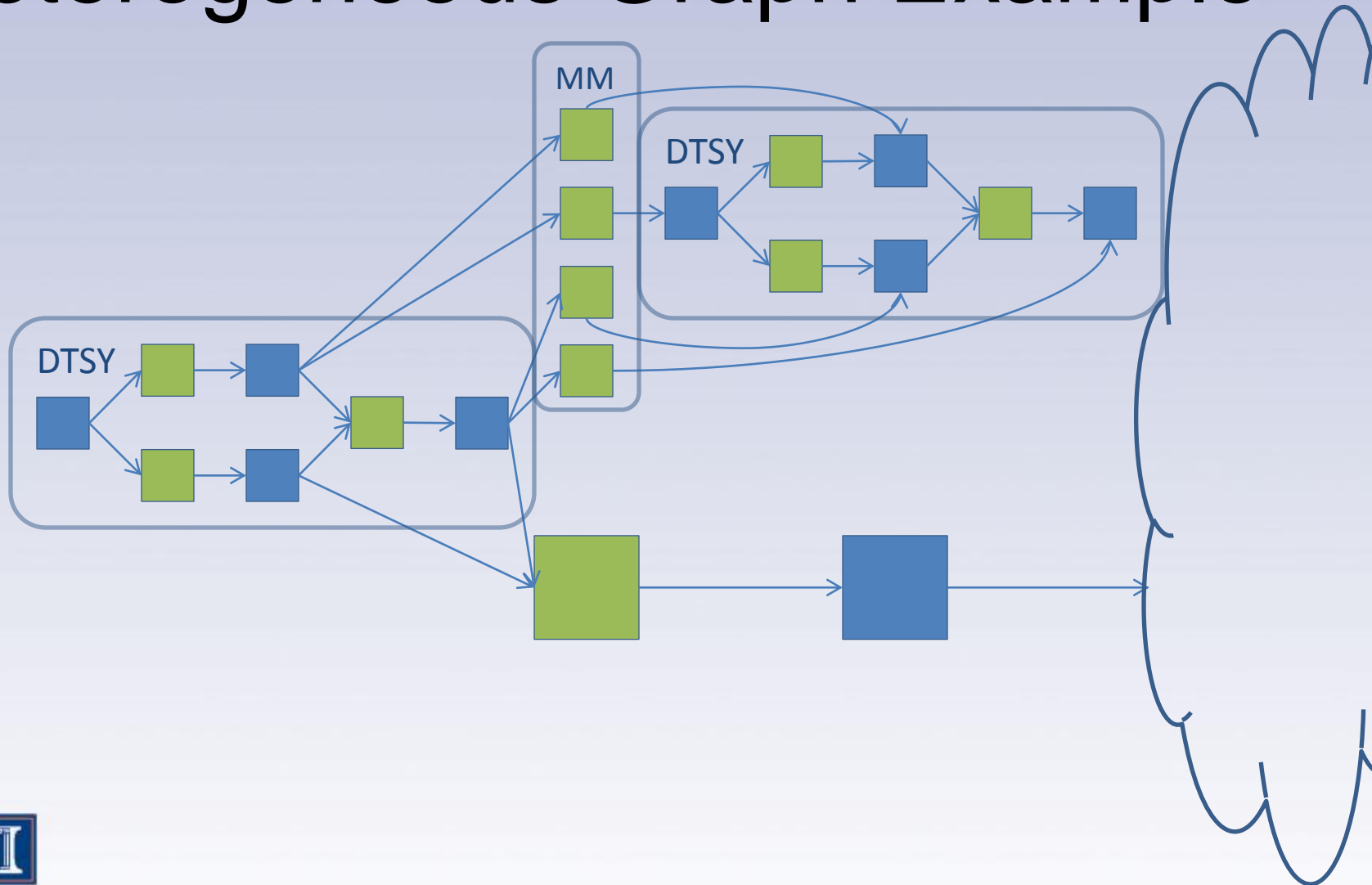
# Simple graph example



# Graph Example



# Heterogeneous Graph Example



# INITIAL RESULTS AND CHALLENGES

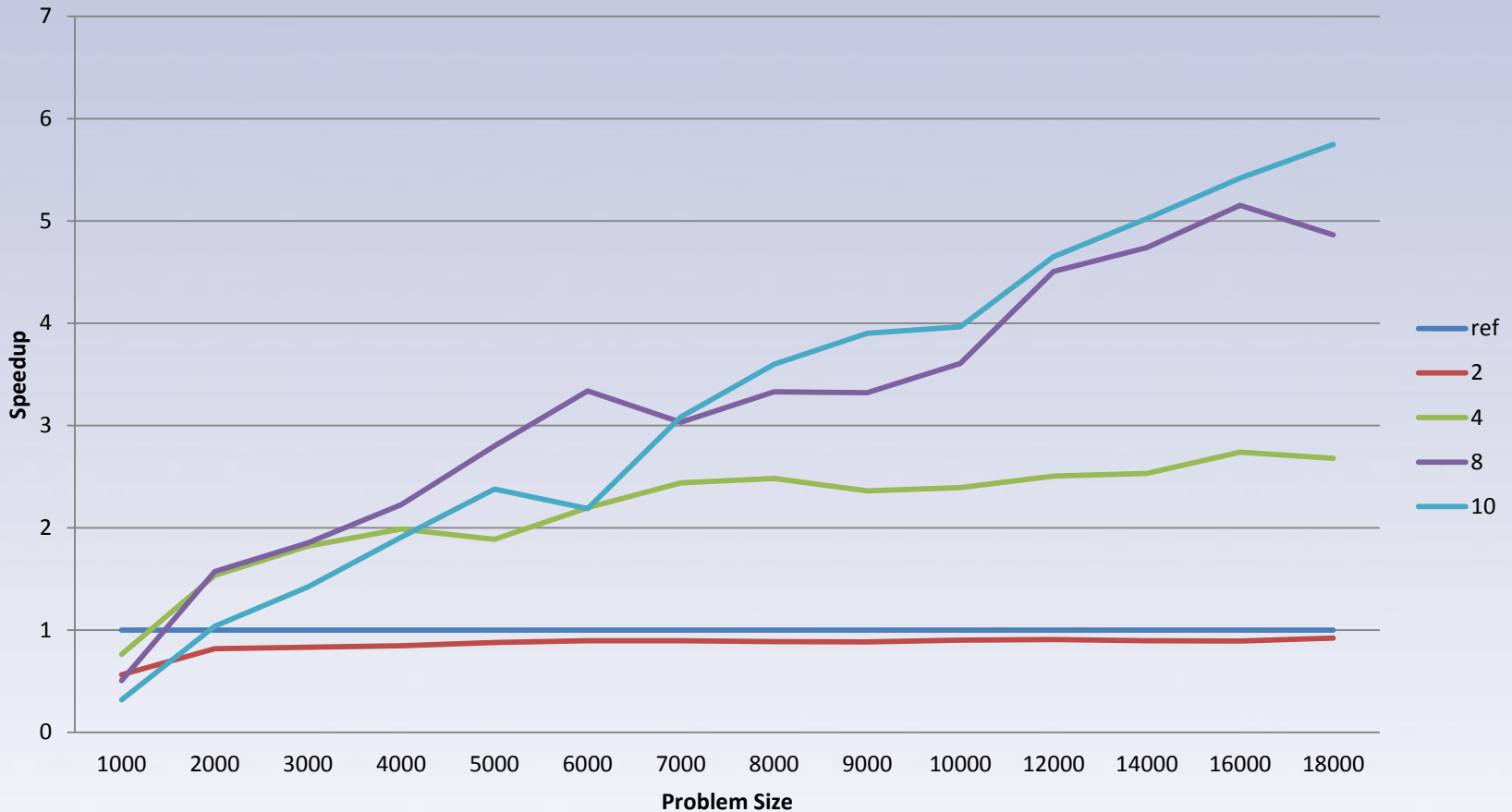


# Challenges

- Version generation time
  - 5 minutes in generator
  - 20 minutes compiling
- Generated code size
  - 500k lines of code in single function
  - (icc segfaults)



# Trisolve ( $L * X = B$ )



# Conclusion

- Faster development cycle for architectures
  - No time to hand-tune everything anymore
  - Can't hand tune for every HW iteration
- Increased complexity
  - Heterogeneous systems
- Description of an automatic methodology
  - Leverage existing “small scale” libraries



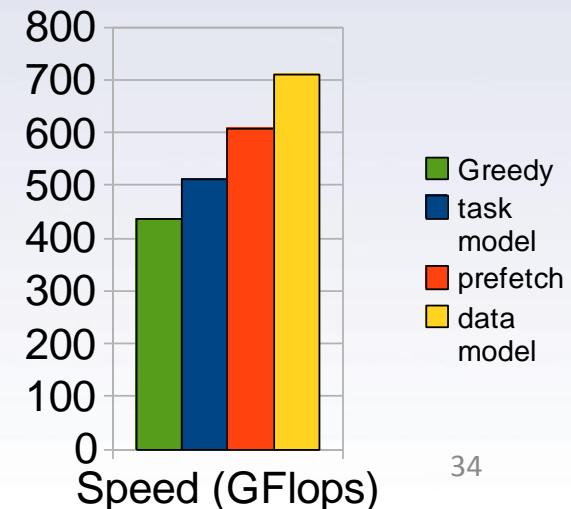
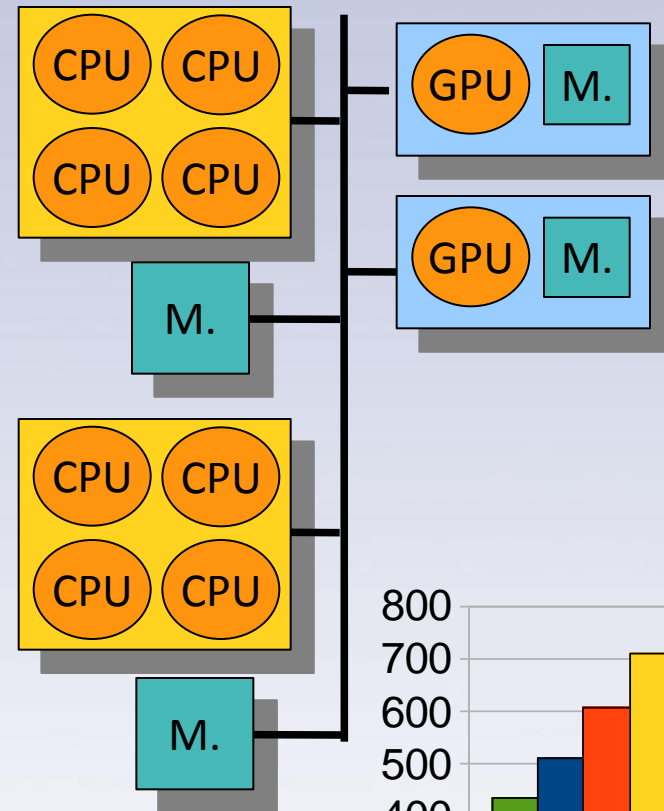


# AU CAS OU



# Exploiting heterogeneous machines : starPU Runtime

- Goal: Scheduling ( $\neq$  offloading) tasks over heterogeneous machines
  - CPU + GPU + SPU = \*PU
  - Auto-tuning of performance models
  - Optimization of memory transfers
- Target for
  - Compilers
    - StarSs [UPC], HMPP [CAPS]
  - Libraries
    - PLASMA/MAGMA [UTK]
  - Applications
    - Fast multipole methods [CESTA]
- StarPU provides an Open Scheduling platform
  - Scheduling algorithm = plugins

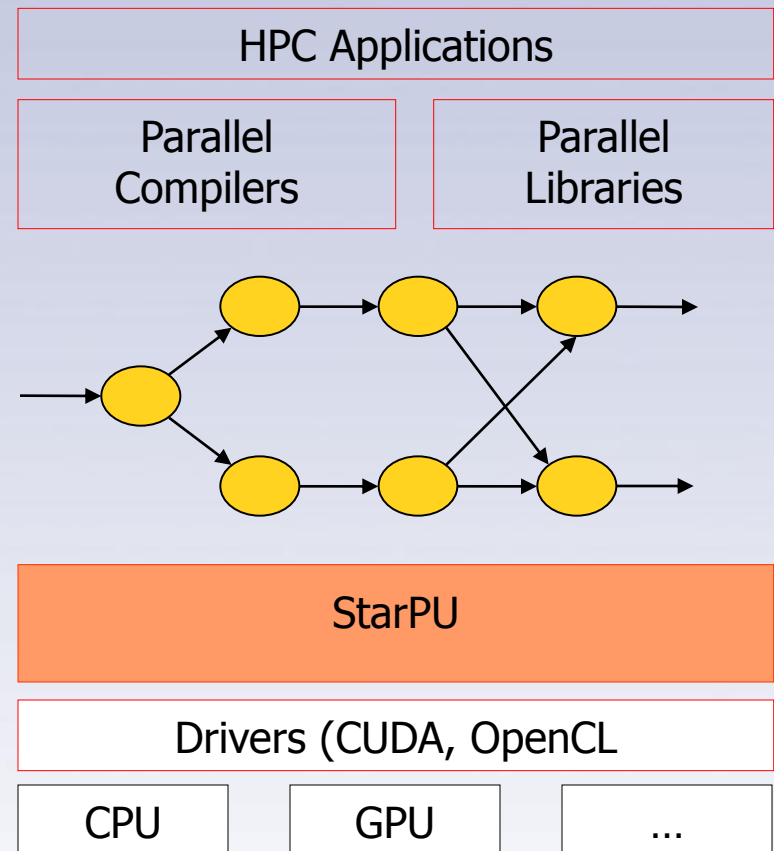


# Overview of StarPU

Maximizing PU occupancy, minimizing data transfers

- Principle

- Accept tasks that may have multiple implementations
  - Together with potential interdependencies
    - Leads to a dynamic acyclic graph of tasks
    - Data-flow approach
- Provide a high-level data management layer
  - Application should only describe
    - Which data may be accessed by tasks
    - How data may be divided



# Code styles and optimization

```
for(int i = 0 ; i < N ; i++)
  for(int j = 0 ; j < N ; j++)
    for(int k = 0 ; k < N ; k++)
      c[i][j] += a[i][k] * b[k][j];
```

```
for(int kk = 0 ; kk < N ; kk+=B)
  for(int ii = 0 ; ii < N ; ii+=B)
    for(int jj = 0 ; jj < N ; jj+=B)
      for(int i = ii ; i < ii+B ; i++)
        for(int k = kk ; k < kk+B ; k++) {
          c_i = c[i];
          a_ik = a[i][k];
          b_k = b[k];
          for(int j = jj ; j < jj+B ; j+=2) {
            c_i[j] += a_ik * b_k[j];
            c_u[j+1] += a_ik * b_k[j+1];
          }
        }
      }
```

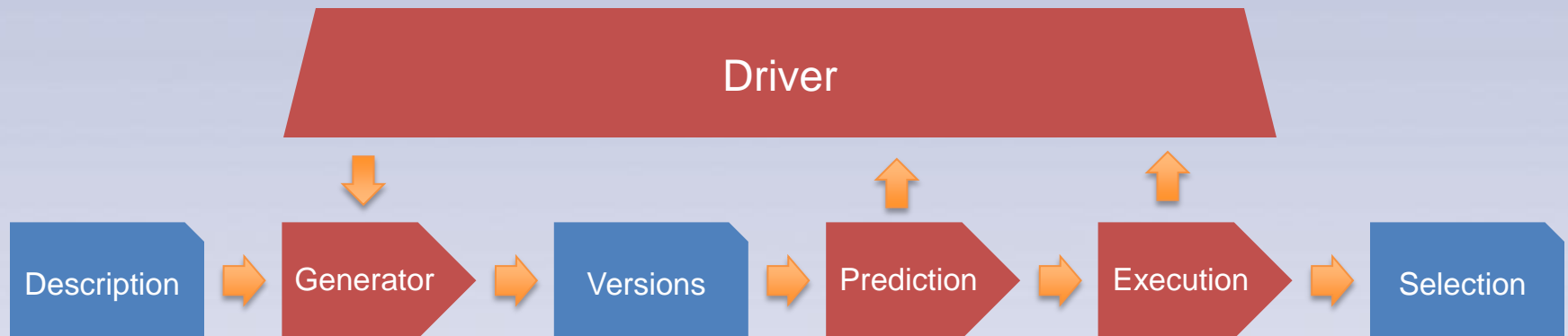


# Empirical search

- Generation of multiple solutions
  - Algorithmic exploration
- Theoretical evaluation
  - Usually unreliable
  - Filtering heuristic
- Empirical evaluation (execution)
  - slow (very slow when looking at bad versions)



# Generalized system overview



- Predictor
  - Filters what versions are actually executed
- Driver
  - Guide the search

