The Data-Dependence graph of Adjoint Codes

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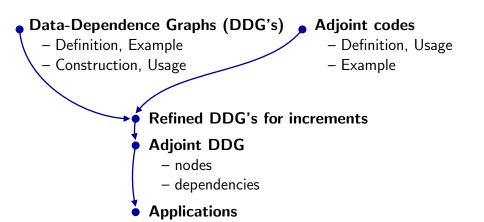
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Data-Deps of Adjoints

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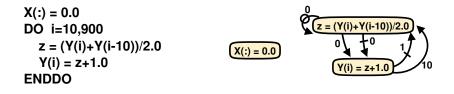
Data-Dependence graph of this talk

Relate the parallel properties of a code to those of its adjoint



Given the source of a program,

- The DDG nodes are the operations of the program. Granularity can be chosen: ops, instructions, blocks ...
- Iterated DDG nodes are collapsed
 ⇒ notion of distance in iteration spaces
- The DDG arrows are the necessary execution partial order. Collapsed nodes ⇒ possible cycles!



Data-Dependencies originate from variables ("data").

A variable v causes a Data-Dependency from node N1 to node N2 iff

- N1 writes v and N2 reads v ("true dependency"), or
- N1 reads v and N2 overwrites v ("anti dependency"), or
- N1 writes v and N2 overwrites v (*"output dependency"*). and in addition (*but not always necessary...*) v is not totally overwritten between N1 and N2.

A Data-Dependency from N1 to N2 means that any rescheduling of operations must keep the order N1 before N2. \Rightarrow DDG's are central for parallelization.

- DDG's capture notions of dead code, inlining
- In loop parallelization, DDG cycles (SCC) cannot be parallelized nor vectorized.
- Loop nests can be transformed according to Data-Dependency distances.
- In Message-Passing, DDG cycles capture deadlocks.
- Scalar expansion is a classical way to lift anti and output dependencies, thus breaking cycles.

Automatic Differentiation's Adjoint codes

- Adjoints are the most efficient way to obtain analytical gradients.
- Uses abound: optimization, least-squares, parameter estimation, sensitivities, uncertainty quantification.
- Adjoints can be built mechanically through AD.

Adjoints propagate backwards the gradient of the result. Consider P

$$P: \{I_1; I_2; \dots I_{p-1}; I_p\}$$

that computes a function $F: X \mapsto Y$

$$F(X) = Y = V_{\rho} = f_{\rho}(f_{\rho-1}(\dots f_2(f_1(V_0 = X))\dots))$$

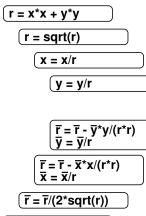
its gradient is

$$\frac{\partial Y}{\partial X} = f'_{\rho}(V_{\rho-1}) \times f'_{\rho-1}(V_{\rho-2}) \times \cdots \times f'_{2}(V_{1}) \times f'_{1}(V_{0})$$

that the adjoint code evaluates from left (row vector) to right.

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Example



$$\overline{\overline{x}} = \overline{x} + 2^* x^* \overline{r}$$

$$\overline{\overline{y}} = \overline{y} + 2^* y^* \overline{r}$$

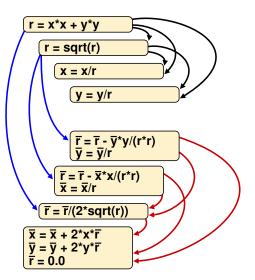
$$\overline{r} = 0.0$$

- Two successive parts (sweeps)
- 2nd sweep computes the gradient, reverse order.
- 1st sweep computes needed original values ⇒ copy of original code.
- Mechanism (not shown here) recovers needed
 r, x, y
- Gradient obtained in final x̄ and ȳ.

- **→ →** •

Image: Image:

What about the DDG ?



- Chosen granularity: I_k and $\overline{I_k}$
- Black deps are the original deps on the original copy.
- Blue deps show uses of direct values for the derivatives.
- Red deps caused only by derivative variables.
- Red deps seem symmetric of Black deps !?
 - \rightarrow true ? why ?

- **→ →** •

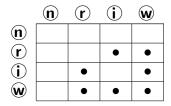
1: For DDG, increments behave just like reads

2: The adjoint of a read is an increment, and conversely.

1: Increments behave like reads

- Define the effect of DDG node on variable v to be (i)
 iff v is only used like v = v +....
- Warning: make sure increments are atomic !

Successive increments are data-independent \Rightarrow refined cases for Data-Dependency:



2: Adjoint of read is increment, and vice-versa

• Suppose
$$I_k$$
 (only) reads v (r
• then $f'_k = \begin{pmatrix} \ddots & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \ddots \end{pmatrix}$

• so that $\overline{I_k}$ actually executes:

$$\left(\begin{array}{ccc} \ldots & \overline{\mathbf{v}} & \ldots \end{array}\right) = \left(\begin{array}{ccc} \ldots & \overline{\mathbf{v}} & \ldots \end{array}\right) \times \left(\begin{array}{ccc} \ddots & \bullet & \mathbf{0} \\ \mathbf{0} & \mathbf{1} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \ddots \end{array}\right)$$

which implies *l_k* only increments *v̄* ... or just doesn't mention it

Table of adjoint DDG nodes

- Looking at all cases:
 - N (n) on v \Rightarrow \overline{N} {(n)} on \overline{v} • N (r) on v \Rightarrow \overline{N} {(i), (n)} on \overline{v} • N (i) on v \Rightarrow \overline{N} {(r), (n)} on \overline{v}
 - N () on $v \Rightarrow N \{(\mathbf{r}', \mathbf{n}')\}$ on v• N () on $v \Rightarrow \overline{N} \{(\mathbf{w}, \mathbf{r}'), (\mathbf{n})\}$ on \overline{v}
- which implies conversely:
 - $\overline{\mathbb{N}}$ (n) on $\overline{\mathbb{v}}$ \Rightarrow \mathbb{N} {(w, r), (i), n} on \mathbb{v}
 - $\overline{\mathbb{N}}$ (r) on $\overline{\mathbb{v}} \implies \mathbb{N}$ {(w),(i)} on \mathbb{v} • $\overline{\mathbb{N}}$ (i) on $\overline{\mathbb{v}} \implies \mathbb{N}$ {(w),(r)} on \mathbb{v}
 - $\overline{\mathbb{N}} \otimes \overline{\mathbb{V}}$ on $\overline{\mathbb{v}} \implies \mathbb{N} \{ \widehat{\mathbb{W}} \}$ on \mathbb{v}



- In other words, the adjoint DDG is equal to (or smaller than) the reversed original DDG
- Distances are preserved
- Nature of dependences (true, anti, output) is not preserved

- The adjoint DDG has the same structure as the original DDG
- Most parallel properties can propagate to the adjoint code:
 - The adjoint of a vector code is a vector code (in most cases).
 - The adjoint of a loop with independent iterations has independent iterations.
- There can even be more parallelism in the adjoint !
- ... but keep in mind the hypotheses (atomic increments).

Each HPC paradigm (e.g. Message-Passing SPMD) can use this DDG property in a specific way