Simulation of Very Large Scale Computing Systems (Toward Exascale and Clouds...)

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Large-Scale Distributed Systems Science?



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Requirements for a Scientific Approach

- Reproducible results
 - > You can read a paper, reproduce a subset of its results and improve
- Standard tools and methodologies
 - Grad students can learn their use and become operational quickly
 - Experimental scenario can be compared accurately

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Current practice in the field: quite different

- Very little common methodologies and tools, large load of (ad-hoc) tools
 - WhateverSim and Sim-*
 - Few are really usable: Diffusion, Software Quality Assurance, Long-term availability
 - Most rely on straightforward models with no validity assessment
- Experimental settings rarely detailed in literature

The SimGrid Project

Project Purpose

- ► Allow a scientific approach of Large-Scale Distributed Systems simulation
- Propose ready to use tools encouraging methodological best practices
- Methodological outcomes not specific to simulation

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Main Challenges (a.k.a Outline of the talk)								

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- Applicability: If it doesn't simulate what is important to you, it's void
- The SimGrid Framework as a Scientific Instrument
 - ▶ Open source, Validated, Scalable, Usable, Modular, Portable
 - ► Grounded +100 papers; 100 members on simgrid-user@; Open Source
 - Simulates real programs (using specific API), not models; C, Java, Lua, Ruby

Outline

- Validity
- Scalability
- Associated Tools
- Future Directions

SotA: Models in most simulators are either simplistic, wrong or not assessed

- ▶ PeerSim: discrete time, application as automaton; GridSim: naive packet level
- OptorSim, GroudSim: documented as wrong on heterogeneous platforms
- ► Validity evaluation: tricky, requires meticulous attention & sound methodology

Quality Levels of Validity

- Level -1: not validated (probably plainly wrong)
- ▶ Level 0 (visually ok): a few curves that look similar (generally hides a lot)
- ▶ Level 1 (ratios ok): A < B in Simulation $\Leftrightarrow A < B$ in Reality
- ▶ Level 2 (prediction abilities): bounded distance between simulation and reality

Network Communication Models

Packet-level simulation

Networking community has standards, many popular open-source projects (NS, GTneTS, OmNet++,...)

- full simulation of the whole protocol stack
- \blacktriangleright complex models \rightsquigarrow hard to instantiate
- ▶ inherently **slow**
- beware of simplistic packet-level simulation

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Delay-based models The simplest ones...

communication time = constant delay, statistical distribution, LogP

 $\rightsquigarrow(\Theta(1) \text{ footprint and } O(1) \text{ computation})$

coordinate based systems to account for geographic proximity

 $\sim (\Theta(N) \text{ footprint and } O(1) \text{ computation})$

Although very scalable, these models ignore network congestion and typically assume large bissection bandwidth

Arnaud Legrand – SG Team

Network Communication Models (cont'd)

Flow-level models A communication (flow) is simulated as a single entity

$$T_{i,j}(S) = L_{i,j} + S/B_{i,j}$$
, where $\begin{cases} S & \text{message size} \\ L_{i,j} & \text{latency between } i \text{ and } j \\ B_{i,j} & \text{bandwidth between } i \text{ and } j \end{cases}$

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Assume steady-state and **share bandwidth** every time a new flow appears or disappears

Setting a set of flows \mathcal{F} and a set of links \mathcal{L} Constraints For all link *j*: $\sum_{i \in I_j} \rho_i \leq C_j$ if flow i uses link j



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Objective function

- Max-Min max(min(ρ_i))
- or other fancy objectives
 - e.g., Reno $\sim \max(\sum \log(\rho_i))$



SimGrid validity: Research focus since 2002

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Settings: Synthetic App. + Synthetic WAN. Compare against GTNetS

- Errors were hunted down + unexpected phenomenon were understood
- Sharing mechanism from theoretical literature experimentally proved wrong
- \sim The model and its instanciation were considerably improved
- SimGrid and packet-level simulators now mostly diverge in extreme cases

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In this scenario, GTNetS and SG agree on termination date of most flows. The most diverging gets no bandwidth for a while although all others are done. Such **fluid models can account** for TCP key characteristics

- slow-start
- flow-control limitation

- RTT-unfairness
- cross traffic interference

They are a very reasonable approximation for most LSDC systems

What about HPC?

Going Further: Real App. +LAN \sim SMPI

- ► Good prediction for short messages is crucial → mixture of piecewise linear, "LogP", and flow-based modeling
- ► Accurately modeling MPI semantic (asynchronous & collectives ops) is tricky ~ looked at the code of openMPI and reproduce
- ► Need to account for MPI overhead; what is Real with several MPI implems? ~ account for such overheads through benchmarking

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Taking resource sharing into account

- Rather good (visual) accuracy
- Our "error" pprox difference between runtimes
- This is only one collective

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"", "difficult" workload: Sweep3D

- Lots of ridiculously small messages and computations
- We do not only compare total time but also state distribution
- More complex apps are on their way

Outline

• Validity

- Scalability
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Scalability Challenge

Situation in 2009

► Timings from CERN guys



- Maximal amount of user processes
 - GridSim: 10,922 (hard limit)
 - SimGrid: 200k (memory limit, 4Gb)
- But needs of the users:
 - ► CERN: 300 × bigger than that (10 days/run)
 - BOINC: 600k volatile hosts over a year
- PeerSim simulates millions of processes
 - but with simplistic models only

Scalability Improvements

- Compact Routing Representation and Lazy Evaluation
- Parallel and distributed simulation
- Simpler models: Coordinate-based and Last-mile models









SimGrid Scalability Results

Millions of small processes (P2P)



Chord simulation

HPC "Workload"



MPI Broadcast: SG vs. LogGopSim SG uses a hierarchical platform

Dozen of huge processes



Binomial scatter with 16 processes

Hundreds of large processes



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Associated Tools Challenge

Workflow to any Simulation Experiment

- 1. Prepare the scenarios
- 2. Launch thousands of runs
- 3. Post-process and analyze results
- $\rightsquigarrow\,$ Each simulation is only a brick



- ▶ SotA: Most frameworks come with *ad hoc* tools (many are *demowares*)
 - Build a *demoware* is easy, ease understanding is harder

The SimGrid Ecosystem

- 1. Workload generation:
 - ▶ Platforms: Simulacrum (generation), PDA (archive) and MintCAR (mapping)
 - Applicative Workload: Tau-based trace collection + replay
 - Background Workload: Pilgrim (trace aggregation tool)
- 2. Campaign management: Workflow engine
- 3. Single simulation analysis: Visualization
 - Builds upon separate established projects: Triva and Paje

SimGrid Visualization Results

- Generic Visualization: map between trace variable to graphic objects;
- Right Representation: gantt charts, tree-maps, graphs
- Scalable tools: avoid visualization artifacts with sound aggregation
- Easy navigation in space and time: selection, aggregation, animation
- Trace comparison: Early work on trace diffing

Lucas Schnorr: Paje, Triva, Viva



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And now?

1998-2001 Baby steps: Factorize some code between PhD students in scheduling 2001-2003 Infancy: CSP and improved models

2003-2008 Teenage: Performance, validity, multi-APIs

2008-2011 Maturation: Scope increase to P2P, visualization

2012- Spreading:

- Scope extension to HPC and Cloud
- Improve asociated tools: visualization, campaign management
- ANR INFRA SONGS project

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SONGS (Simulation Of Next Generation Systems)

Lessons learned from past projects

- Much emphasis on methodology, but users' concerns are important too
- ► Science pulled by needs, not pushed by abilities: Use-Case Driven Research

Main Goal: Making SimGrid usable in 2 more domains

- ► Task 1: [Data]Grid (with CERN)
- Task 2: Peer-to-Peer and Volunteer Computing (with BOINC)
- ► Task 3: IaaS Clouds
- Task 4: High Performance Computing
- Factorize developments on simulation pillars
 - ► Task 5: Simulation Kernel (efficient and standard simulations)
 - ► Task 6: Concepts and Models (power, storage, CPU/Mem, networks, volatility)
 - ► Task 7: Analysis and Visualization
 - ► Task 8: Experimental Methodology (DoE, Open science, Campaign magmt)

SONGS: Simulating IaaS Clouds

Envisioned Provider-Side Studies

- Anticipated provisioning of VMs to face peak demands
- Allocation algorithms to map VMs to physical hosts
- Placement of VM images to reduce VM startup and migration
- ▶ Metrics: Performance, Energy, Resource usage, Economics
- API: VM operations (start/stop/migrate), images storage, SLA

Envisioned Client-Side Studies

- Leverage cloud billing model to get the best performance at the best prices
- Evaluate trade-off between price and performance according to the workload
- ▶ Force provider to SLA violations to get free resources ;)
- API: EC2 (de facto standard)

Missing models:

APIs elements, non-CPU-bound tasks, resource sharing between VMs

SONGS: Simulating HPC systems

Challenge: Simulate complex apps running on modern HPC platforms

Huge modeling task, daunting validation challenge

Missing Models and Concepts

- \blacktriangleright CPU model: Flops count \leadsto multicores w/ complex mem. hierarchies, GPU
- Network: Ethernet only \sim infiniband at least
- Memory resource to be added (cache effects, NUMA archs)
- Energy need DVFS API and flexible composition, I/Os...

Envisioned Studies

- Classical MPI applications
- Challenging MPI apps (highly optimized wrt memory and CPU), StarPU
- ► ExaScale: Capacity planning for 100,000+ ARM processors (easier than Intel)

Risks and backups

- Previous experience with SMPI (simulated MPI)
- Huge task split in several steps; doing some steps would be something

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Potential collaborations in the joint lab

LogGOPSim Loading GOAL in SimGrid is trivial; Would allow to simulate seamlessly network hierarchy and contention

- ▶ Is the GOAL formalism still relevant? LogGS linear regressions?
- What about injecting system noise? Failures?
- Using SG to evaluate topology-aware collective communications?

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Visualization tools (UFRGS, Brazil) need new tools with aggregation capabilities